

# Daytime Raman Lidar measurements

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# Lidar signal and skylight background

Atmospheric response:

$$P(r) = E_0 f_L Q(r) K \frac{A}{r^2} \frac{c\tau}{2} \beta_\pi(r) \exp\left(-2 \int_0^r \alpha(x) dx\right)$$

Sky background:

$$P_{BGR} = E_\nu K A \Delta\Omega \Delta\nu f_L \tau$$

Signal to background:

$$\frac{P}{P_{BGR}} \sim \frac{E_0 \beta_\pi}{\Delta\Omega \Delta\nu}$$

$E_0$  laser pulse energy

$f_L$  pulse repetition rate

$K$  total throughput

$A$  receiving telescope area

$\tau$  time bin length

$Q(r)$  overlap function

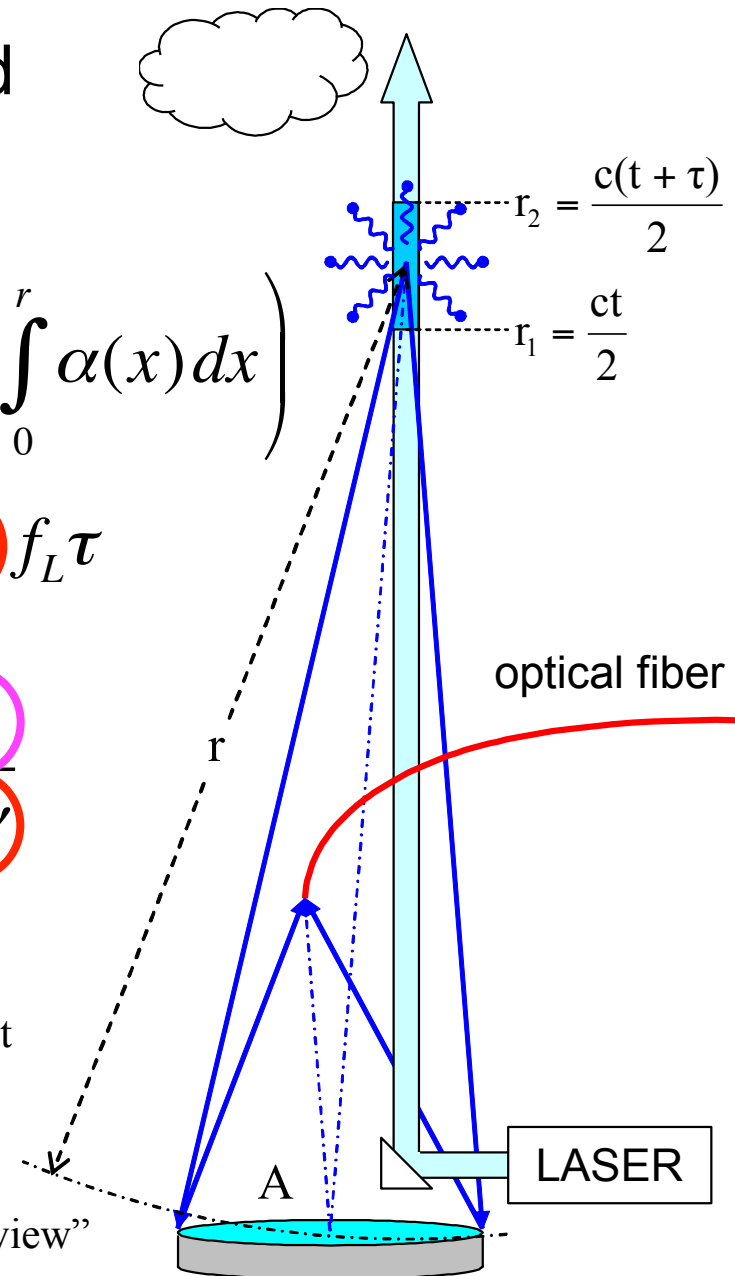
$E_\nu$  sky brightness density

$\beta_\pi(r)$  backscatter coefficient

$\alpha(r)$  extinction coefficient

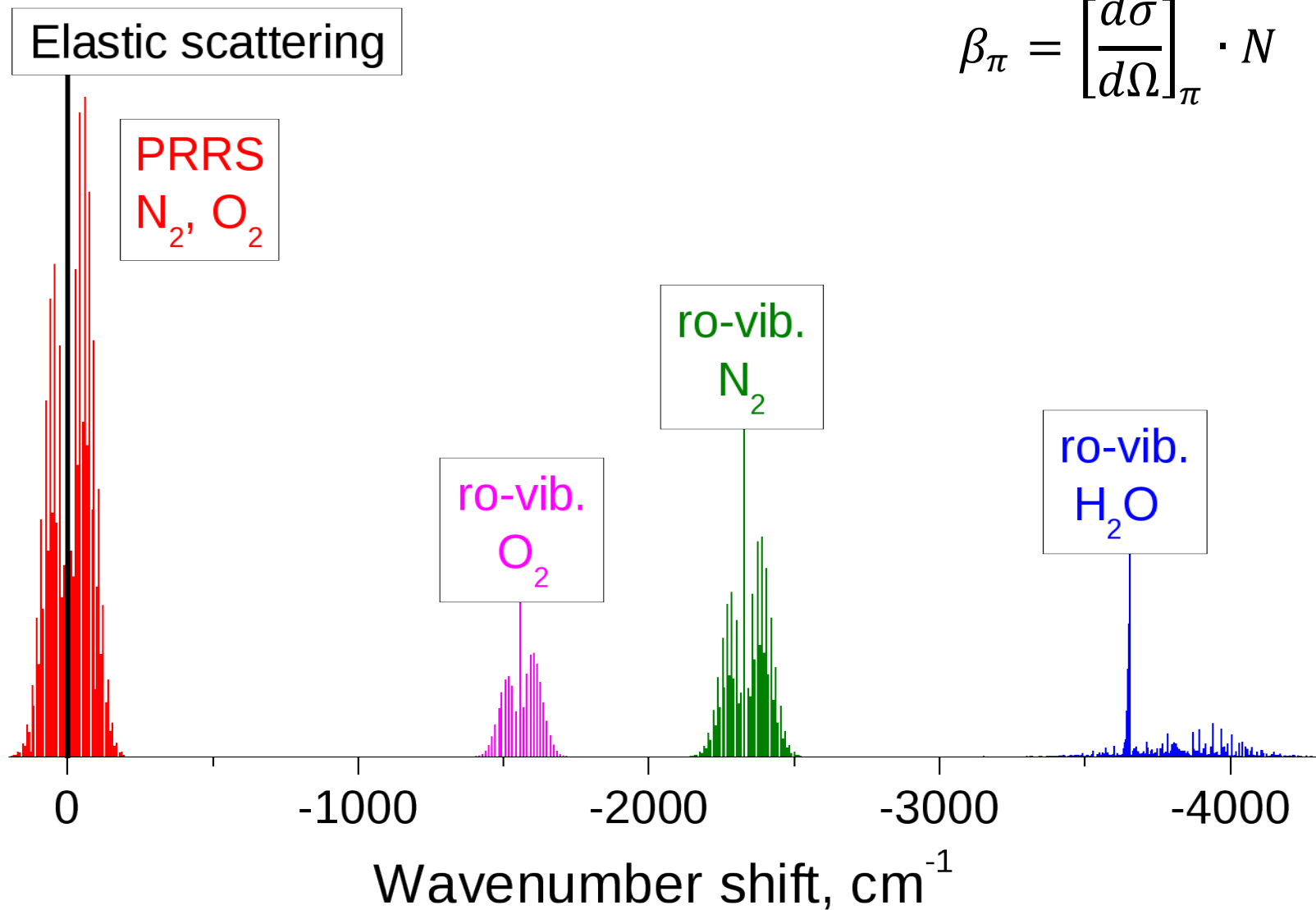
$\Delta\nu$  spectral passband

$\Delta\Omega$  solid angle of “field-of-view”

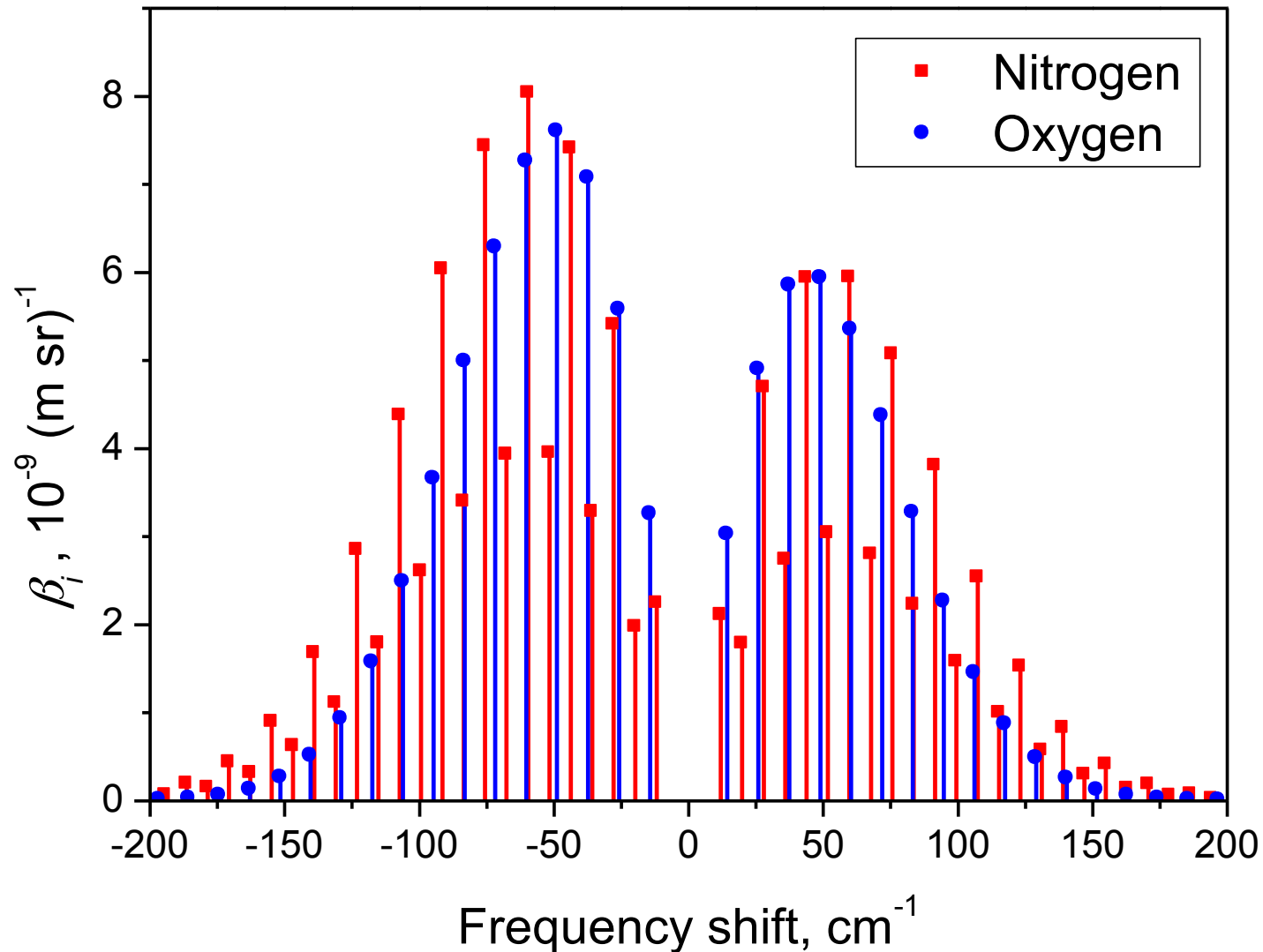


# Atmospheric response

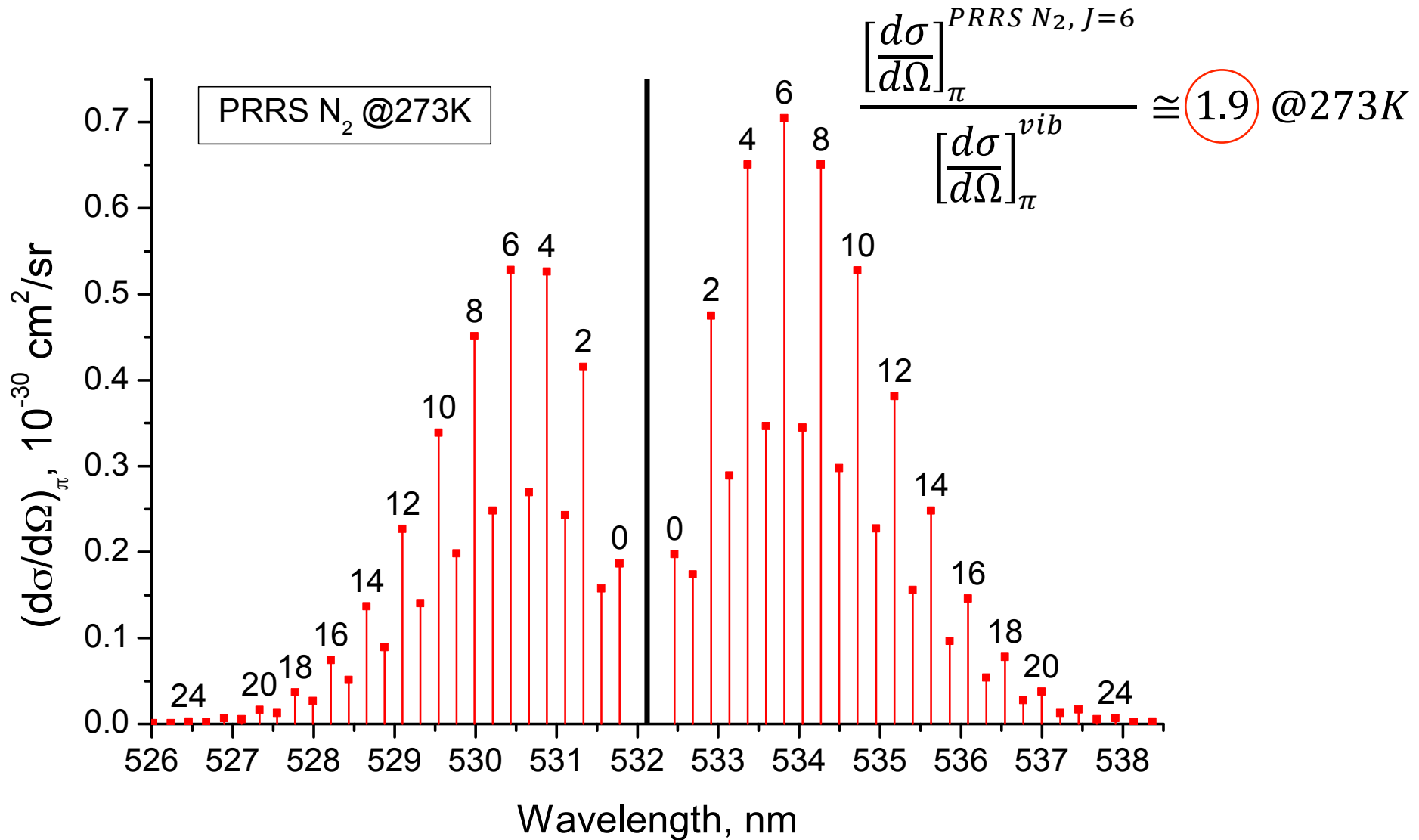
$$\beta_{\pi} = \left[ \frac{d\sigma}{d\Omega} \right]_{\pi} \cdot N$$



# Pure rotational Raman spectra of N<sub>2</sub> and O<sub>2</sub>



# Scattering efficiency @532nm



# Scattering efficiency

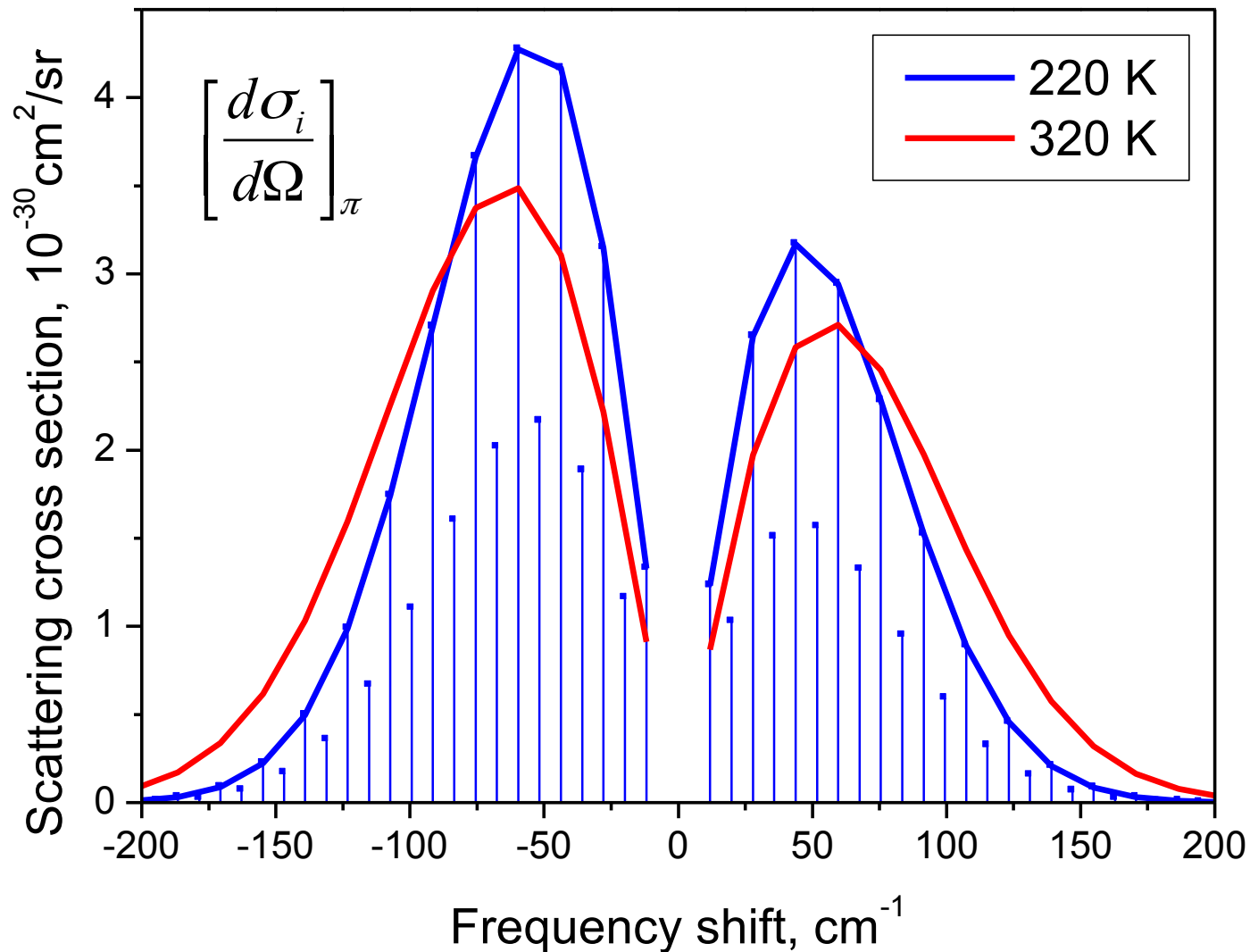
$$\frac{\left[\frac{d\sigma}{d\Omega}\right]_{\pi}^{PRRS N_2, J=6}}{\left[\frac{d\sigma}{d\Omega}\right]_{\pi}^{vib}} \cong 1.9 @273K$$

$$N_{lines}^{eff} = \frac{1}{n_{N_2} \left[\frac{d\sigma}{d\Omega}\right]_{\pi}^{vib}} \left( n_{N_2} \sum_{\forall J}^{N_2} \left[\frac{d\sigma}{d\Omega}\right]_{\pi}^J + n_{O_2} \sum_{\forall J}^{O_2} \left[\frac{d\sigma}{d\Omega}\right]_{\pi}^J \right) \cong 48 @273K$$

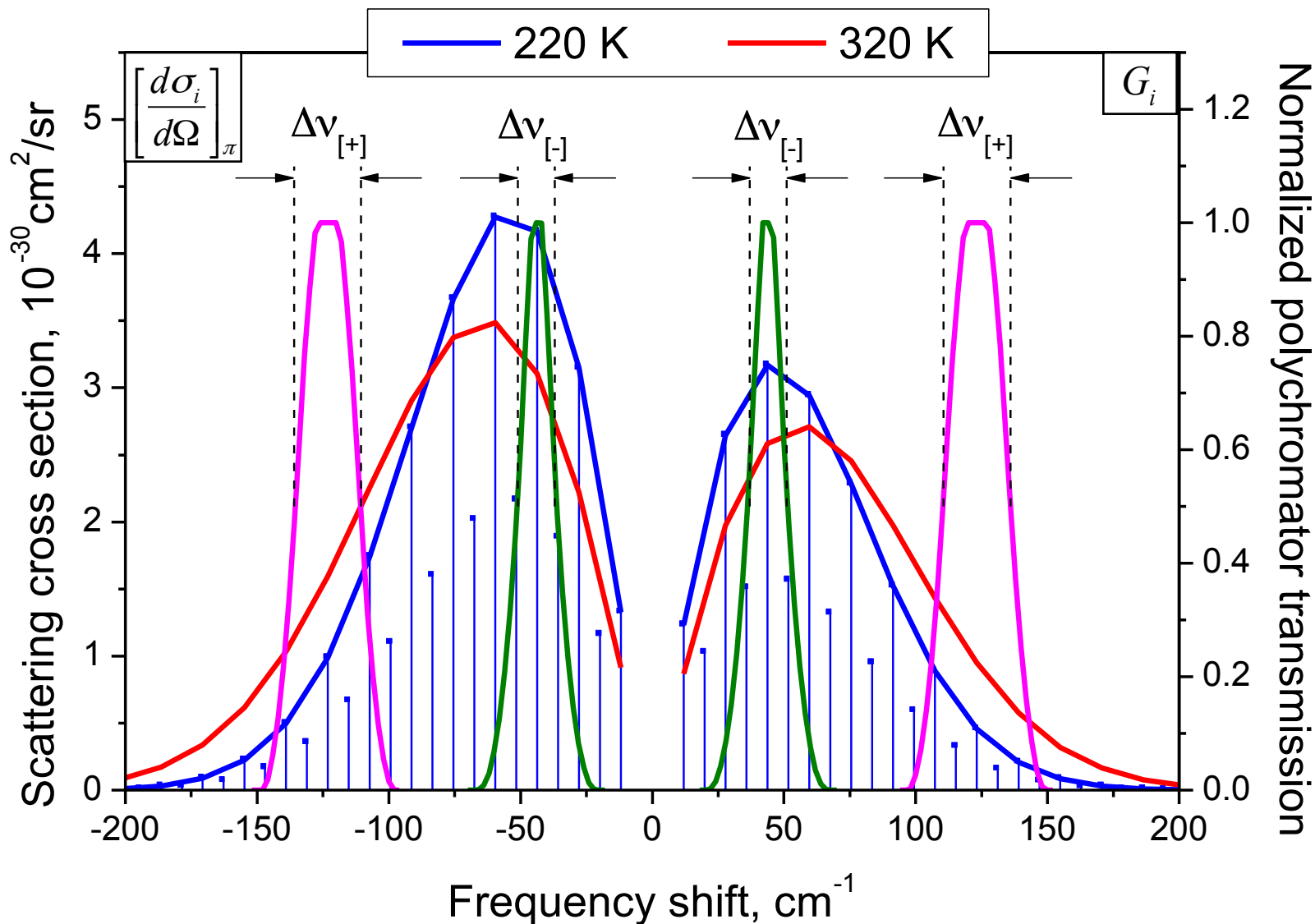
$$\frac{1}{\left[\frac{d\sigma}{d\Omega}\right]_{\pi}^{vib}} \sum_{\forall J}^{N_2} \left[\frac{d\sigma}{d\Omega}\right]_{\pi}^J \cong 28 @273K$$

$$\frac{n_{O_2}}{n_{N_2} \left[\frac{d\sigma}{d\Omega}\right]_{\pi}^{vib}} \sum_{\forall J}^{O_2} \left[\frac{d\sigma}{d\Omega}\right]_{\pi}^J \cong 20 @273K$$

# PRRS, temperature sensitivity

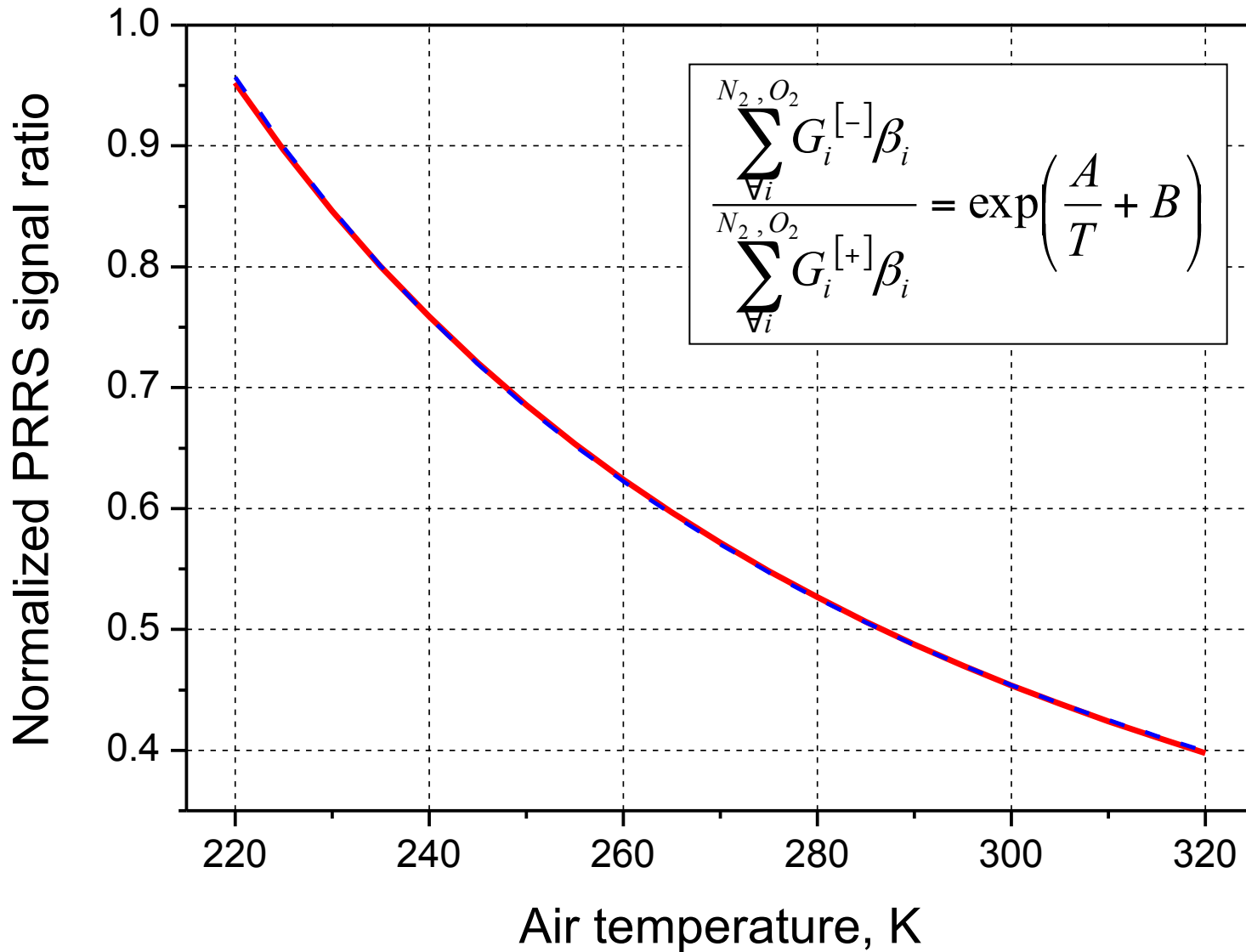


# PRRS, temperature sensitivity



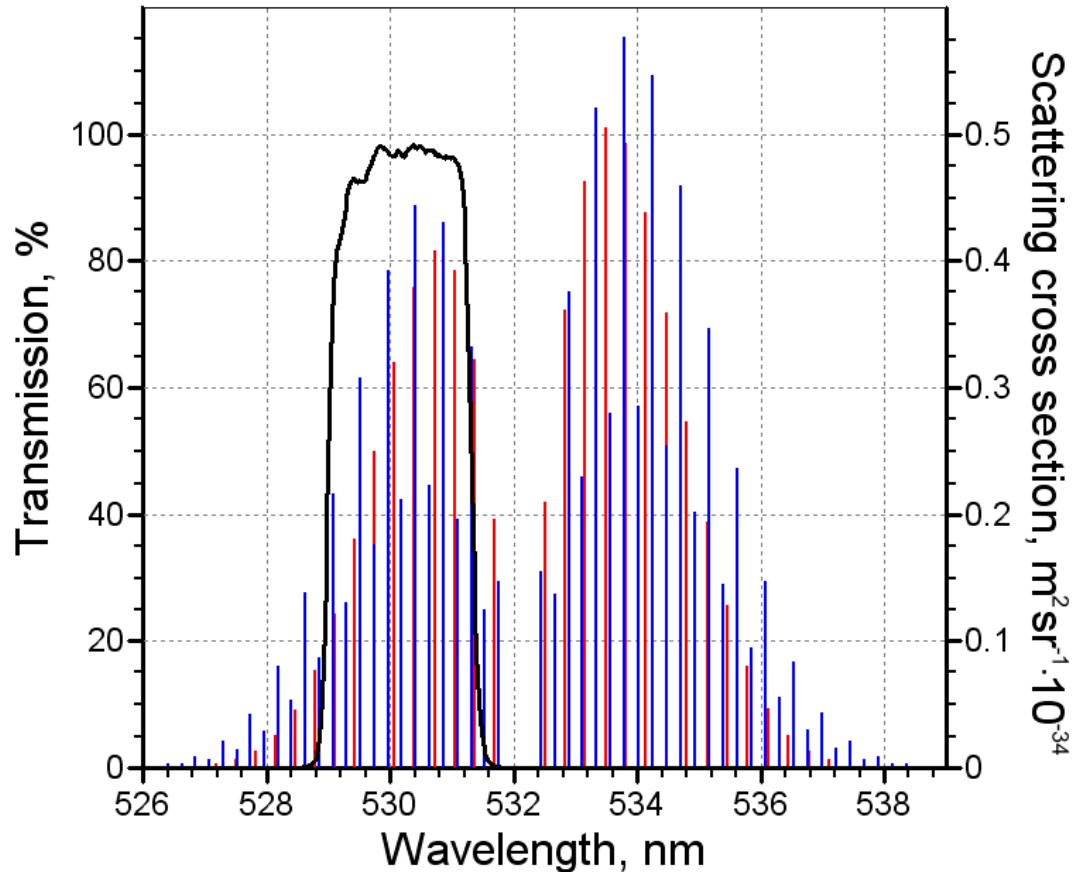


# PRRS signal ratio



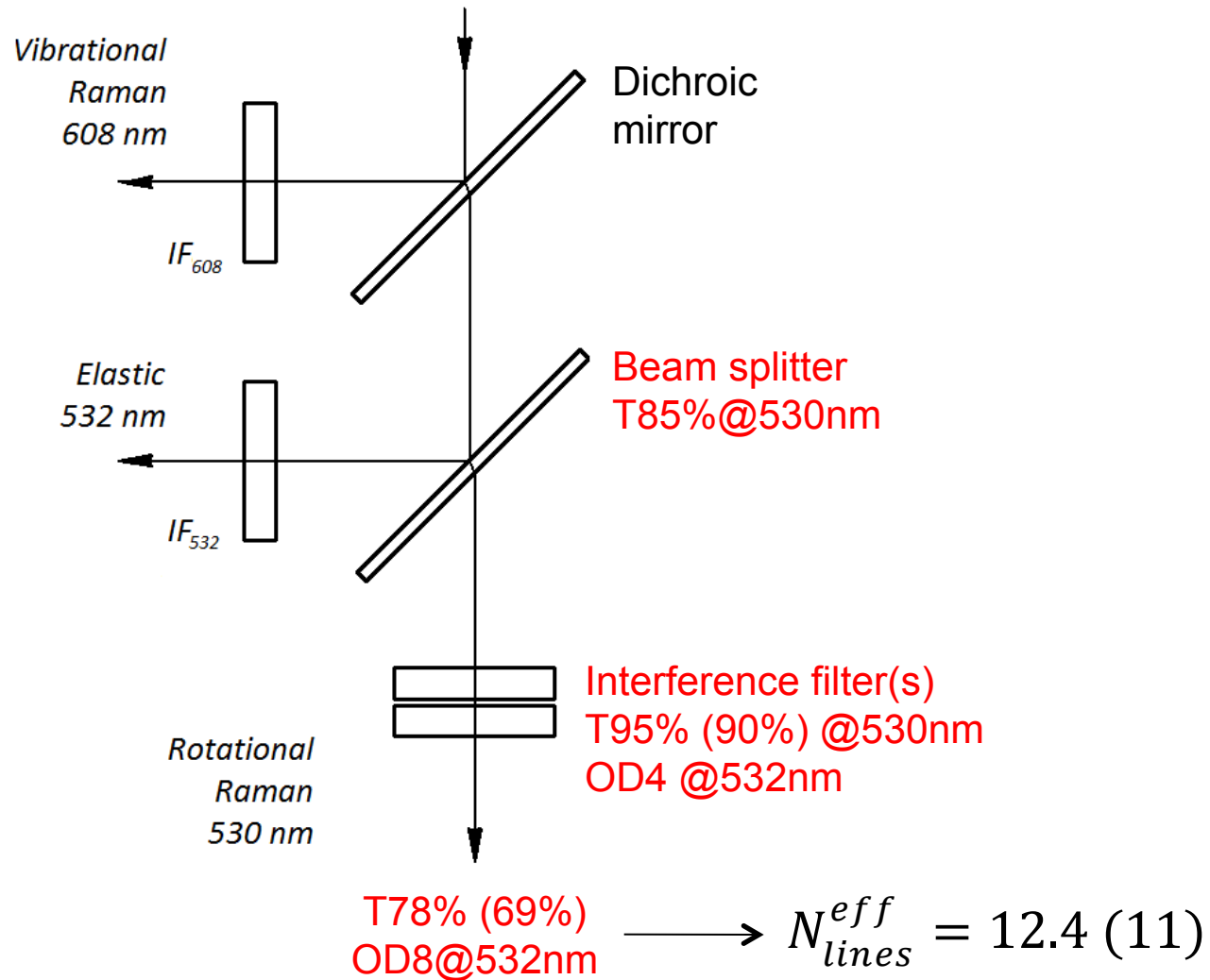
# Isolating “temperature-insensitive” lines with interference filters

$$N_{lines}^{eff} = \frac{1}{n_{N_2} \left[ \frac{d\sigma}{d\Omega} \right]_{\pi}^{vib}} \left( n_{N_2} \sum_{\forall J}^{N_2} G_J \left[ \frac{d\sigma}{d\Omega} \right]_{\pi}^J + n_{O_2} \sum_{\forall J}^{O_2} G_J \left[ \frac{d\sigma}{d\Omega} \right]_{\pi}^J \right) \cong 16 @273K$$



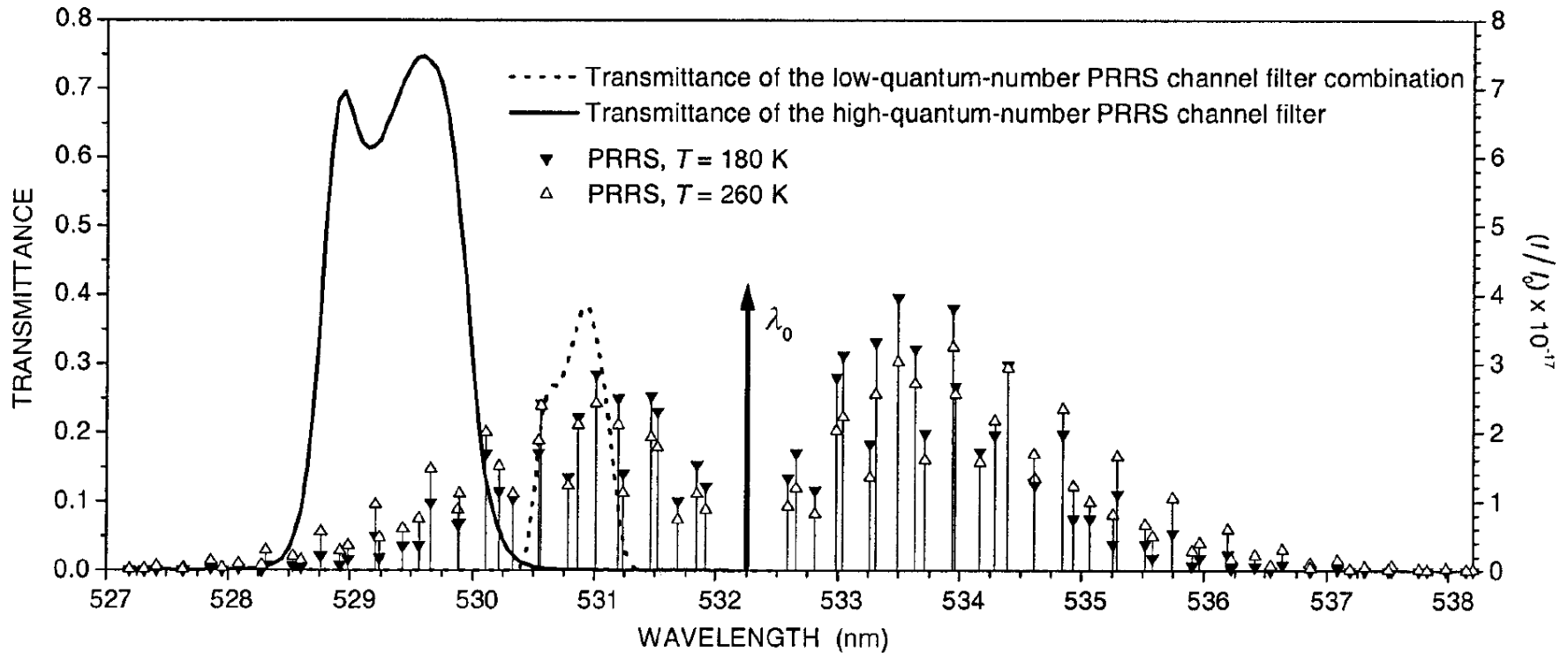
“PRRS of  $N_2$  (blue) and  $O_2$  (red) @ $T=300$  K and the interference filter transmission” after Veselovskii et al. “Use of rotational Raman measurements in multiwavelength aerosol lidar for Evaluation of particle backscattering and extinction”, Atmos. Meas. Tech., 8, 4111–4122, 2015

# Isolating “temperature-insensitive” lines with interference filters



after Veselovskii et al. “Use of rotational Raman measurements in multiwavelength aerosol lidar for Evaluation of particle backscattering and extinction”, Atmos. Meas. Tech., 8, 4111–4122, 2015

# Isolating “temperature-sensitive” lines with interference filters

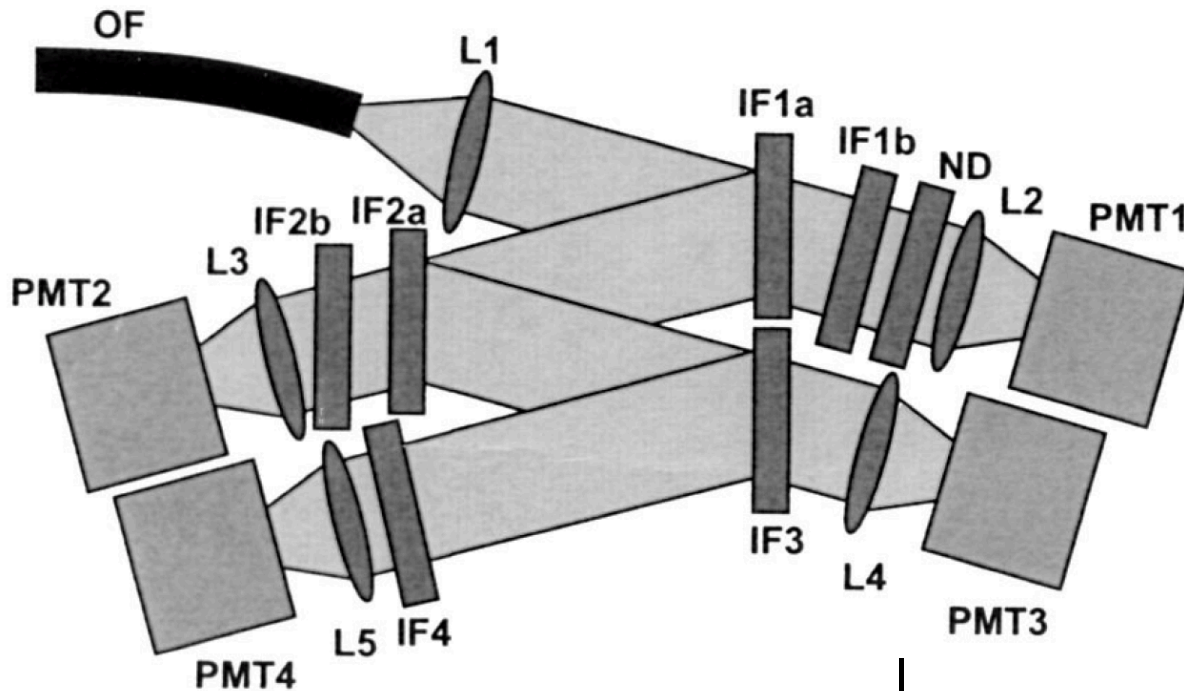


“Scaled intensity of the PRR signal and transmittances of employed interference filters”

after Behrendt and Reichardt, “Atmospheric temperature profiling in the presence of clouds with a pure rotational Raman lidar by use of an interference-filter-based polychromator”

App. Opt., Vol. 39, No. 9, 1372-1378, 2000

# Isolating “temperature-sensitive” lines with interference filters

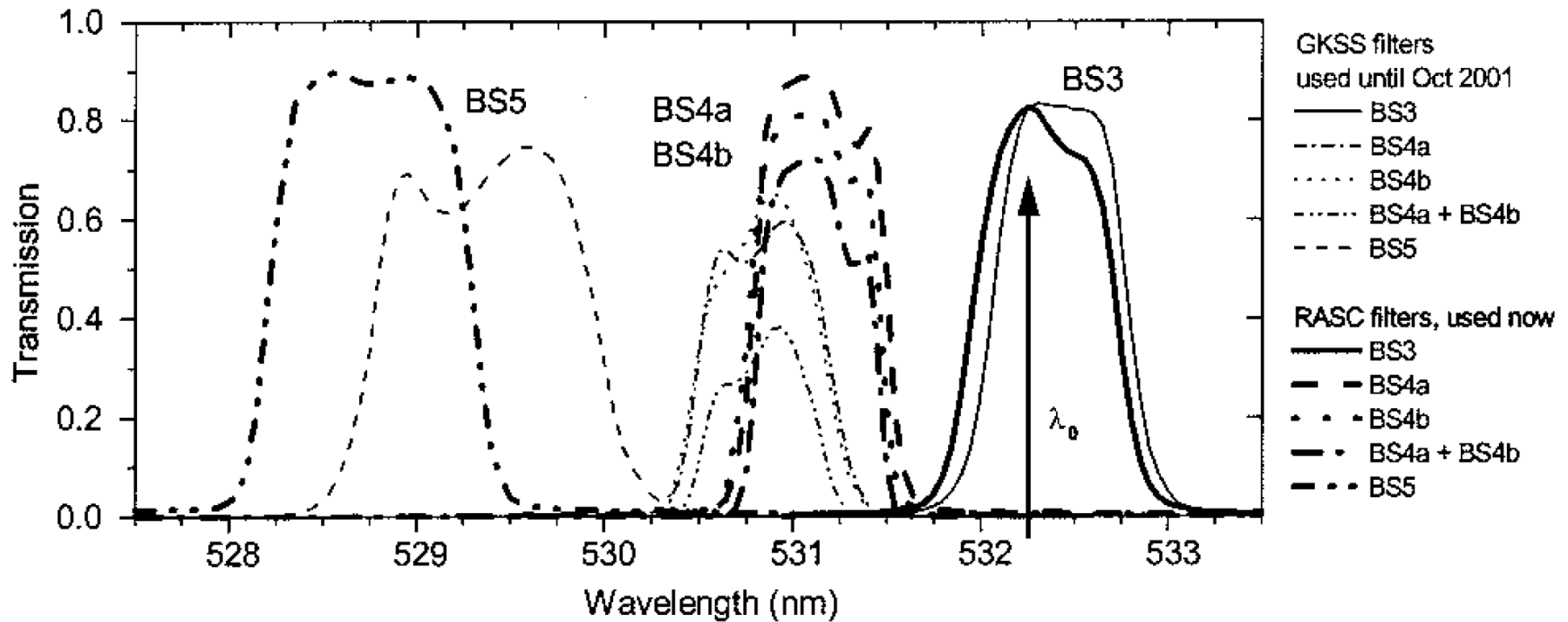


Elastic (PMT1)	$n_{[-]}$ (PMT2)	$n_{[+]}$ (PMT3)
$T_{IF1a} \cdot T_{IF1b}$	$R_{IF1a} \cdot T_{IF2a} \cdot T_{IF2b}$	$R_{IF1a} \cdot R_{IF2a} \cdot T_{IF3}$
62%	36%	68%
	$\geq OD7@532nm$	$\geq OD7@532nm$

after Behrendt and Reichardt, “Atmospheric temperature profiling in the presence of clouds with a pure rotational Raman lidar by use of an interference-filter-based polychromator”

App. Opt., Vol. 39, No. 9, 1372-1378, 2000

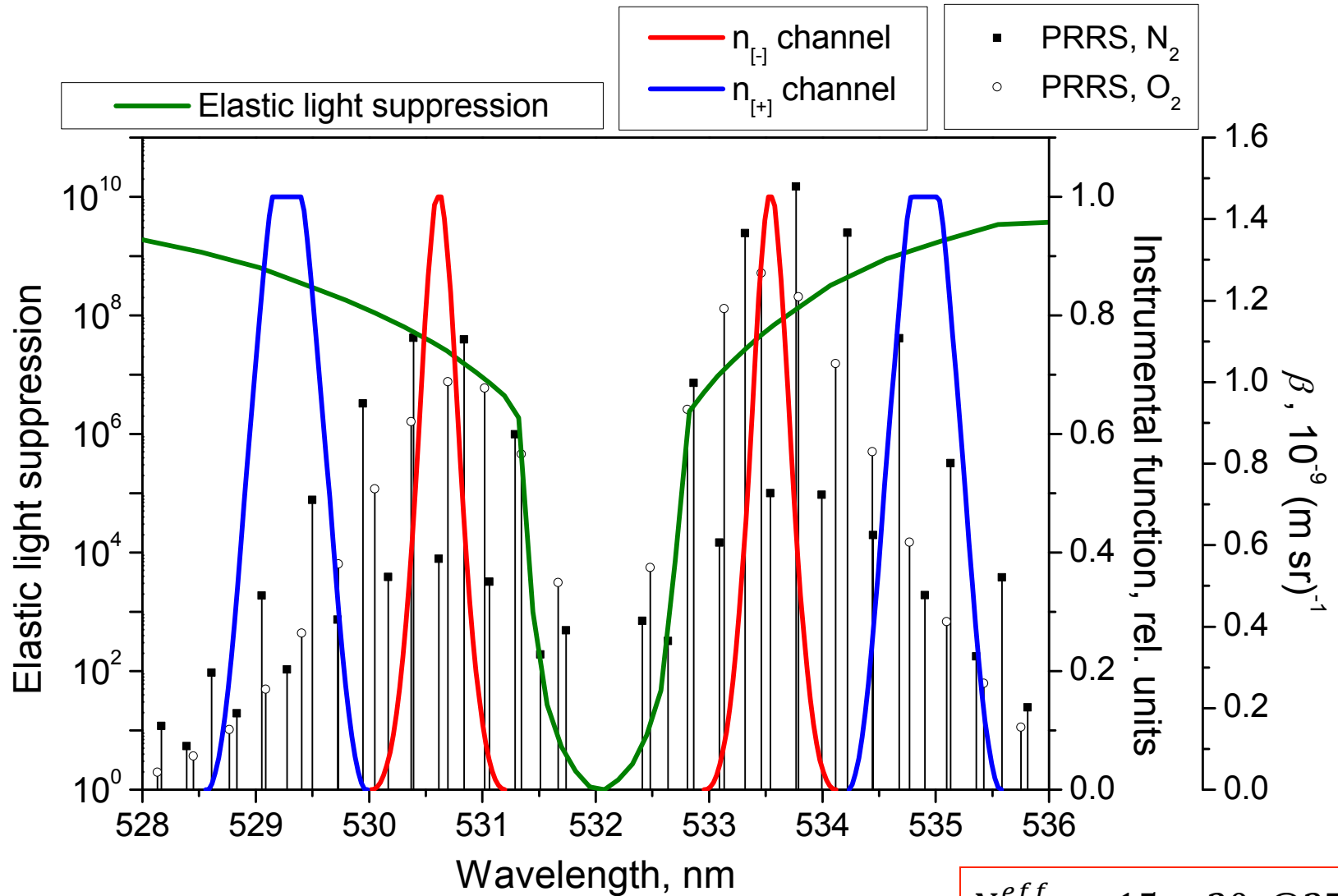
# Improved transmission of interference filters (as of 2004)



Elastic	$n[-]$	$n[+]$
$T_{BS3}$	$R_{BS3} \cdot T_{BS4a} \cdot T_{BS4b}$	$R_{BS3} \cdot R_{BS4a} \cdot T_{BS5}$
82%	68%	80%
	$\geq 0D7@532nm$	$\geq 0D7@532nm$

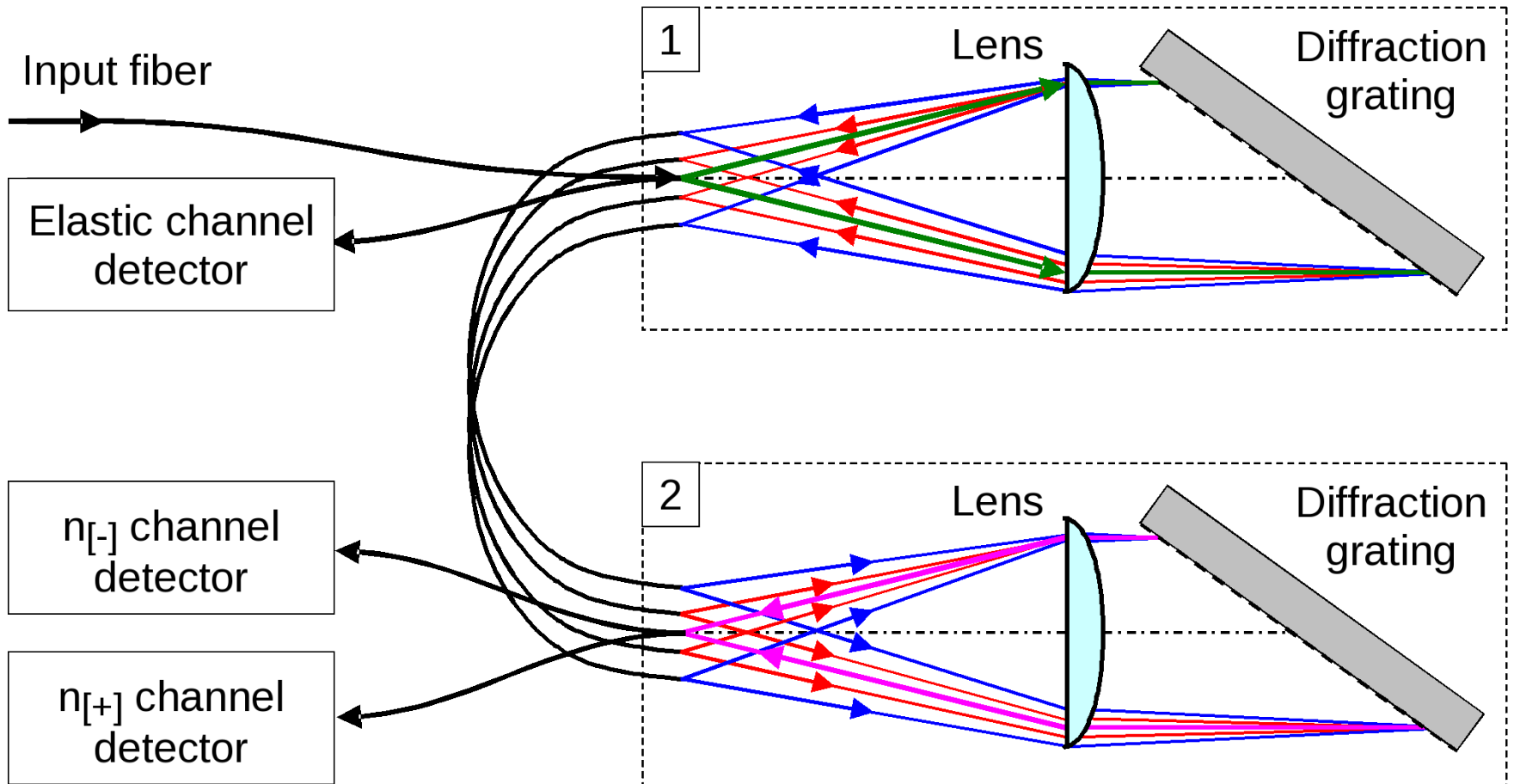
after Behrendt et al., "Combined temperature lidar for measurements in the troposphere, stratosphere, and mesosphere", App. Opt., Vol. 43, No. 14, 2930-2939, 2004

# Isolating “temperature-sensitive” lines with diffraction gratings



$$N_{lines}^{eff} = 15 \div 20 @273K$$

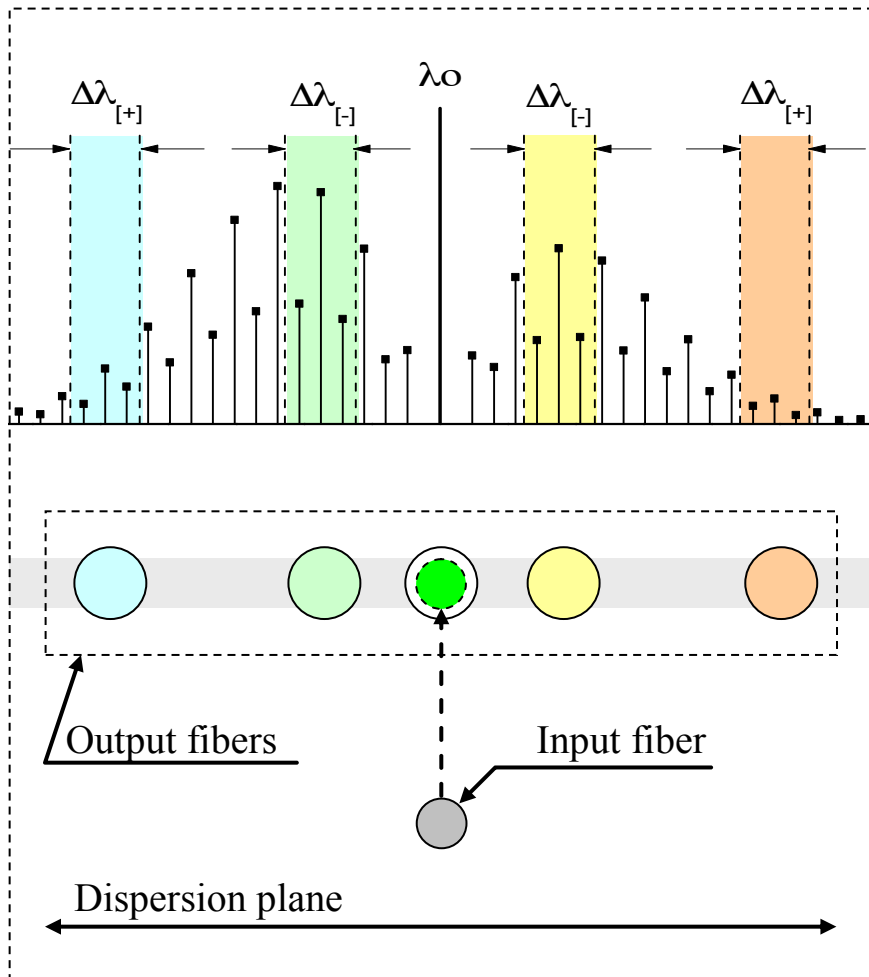
# Diffraction grating polychromator



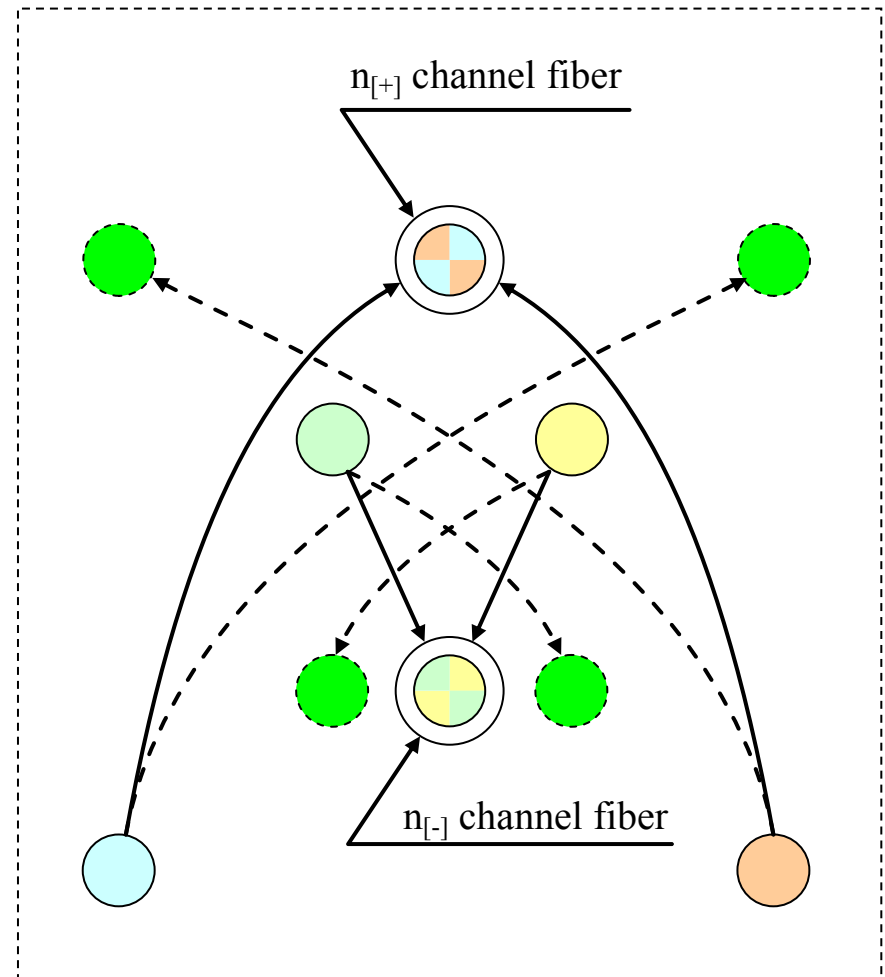
\*  $n_{[+]}$  and  $n_{[-]}$  refer to the PRRS lines with positive and negative temperature dependence



# Input / output “slits” (fibers) arrangement



first unit

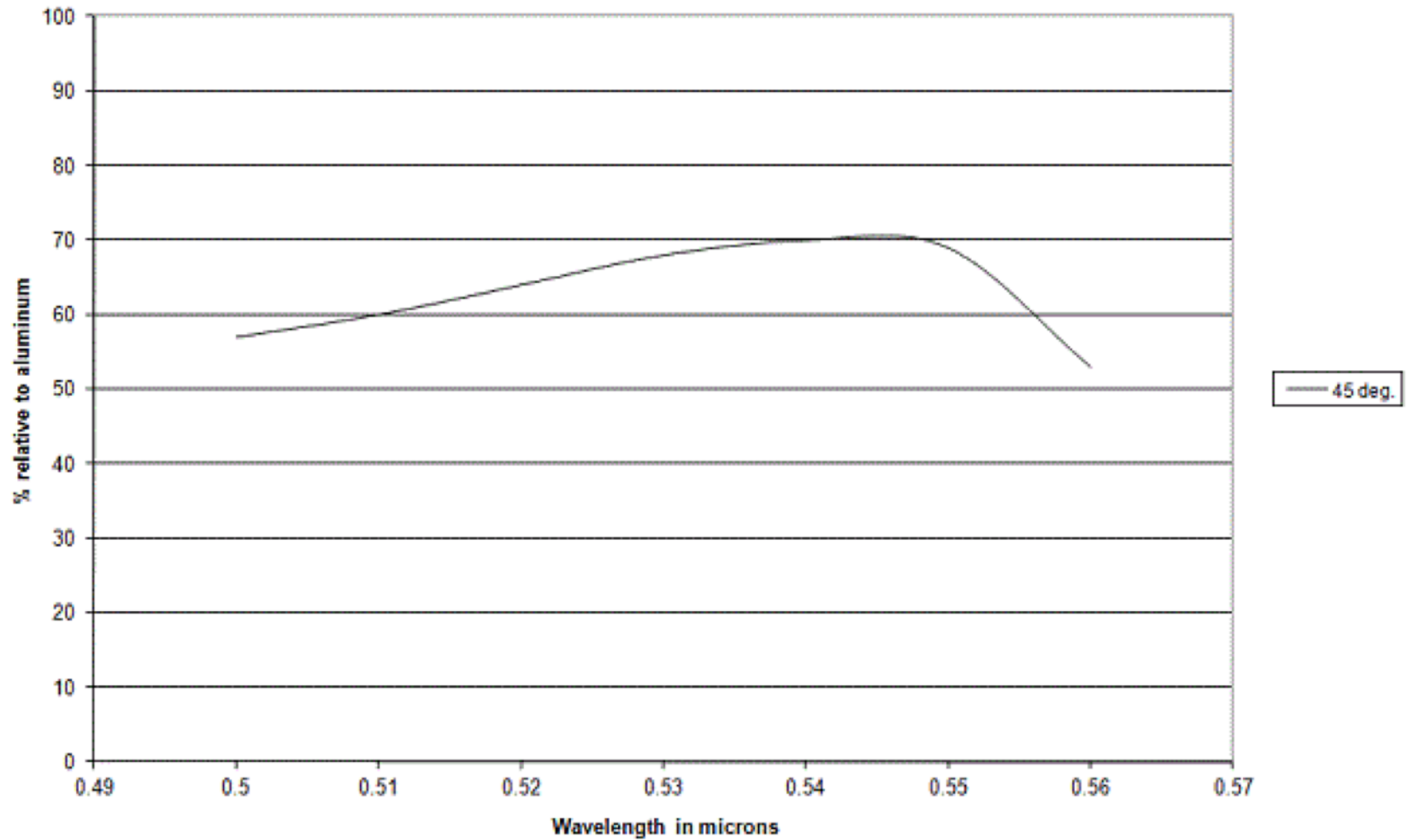


second unit

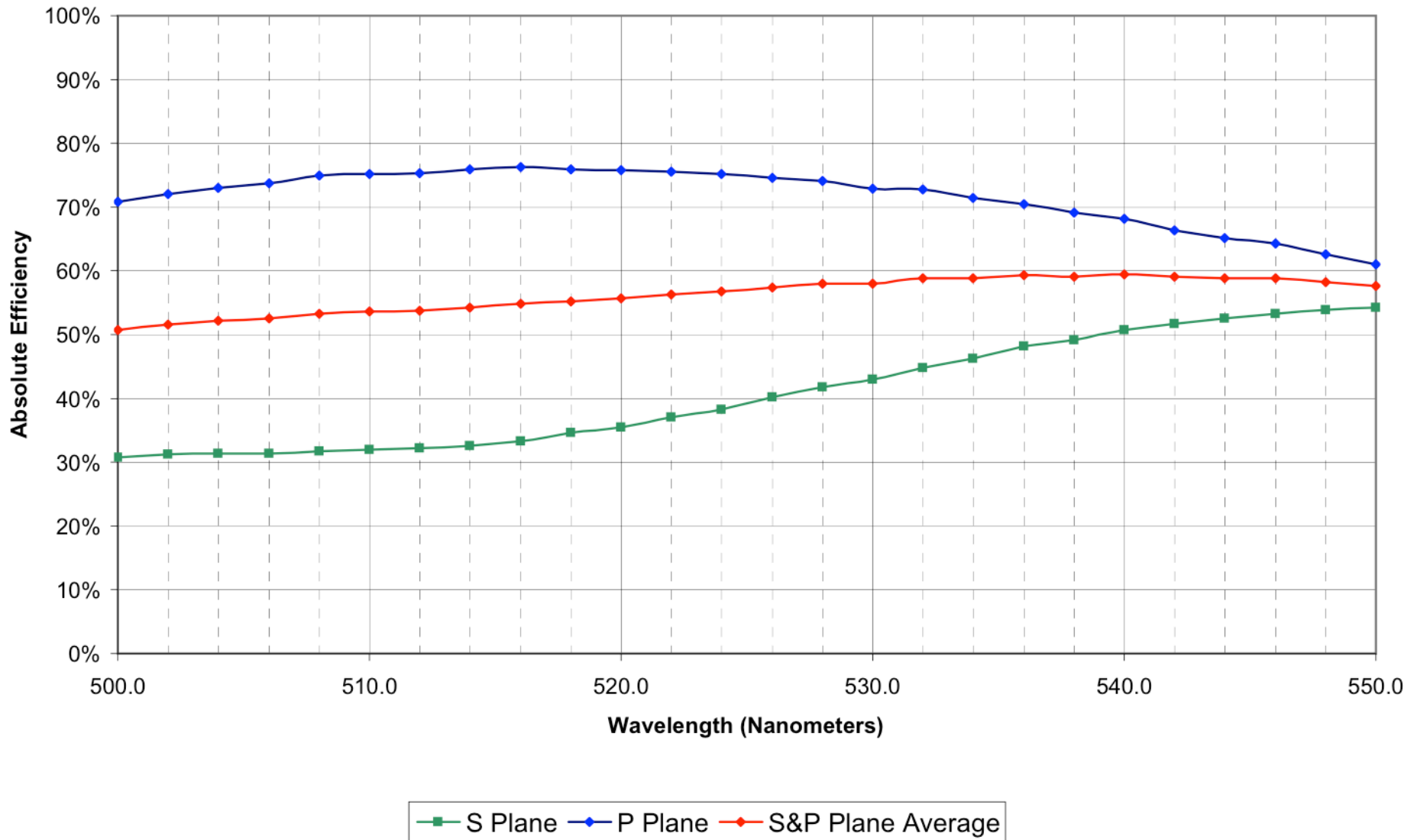
Single telescope configuration.

# Diffraction grating efficiency (Richardson Gratings Lab)

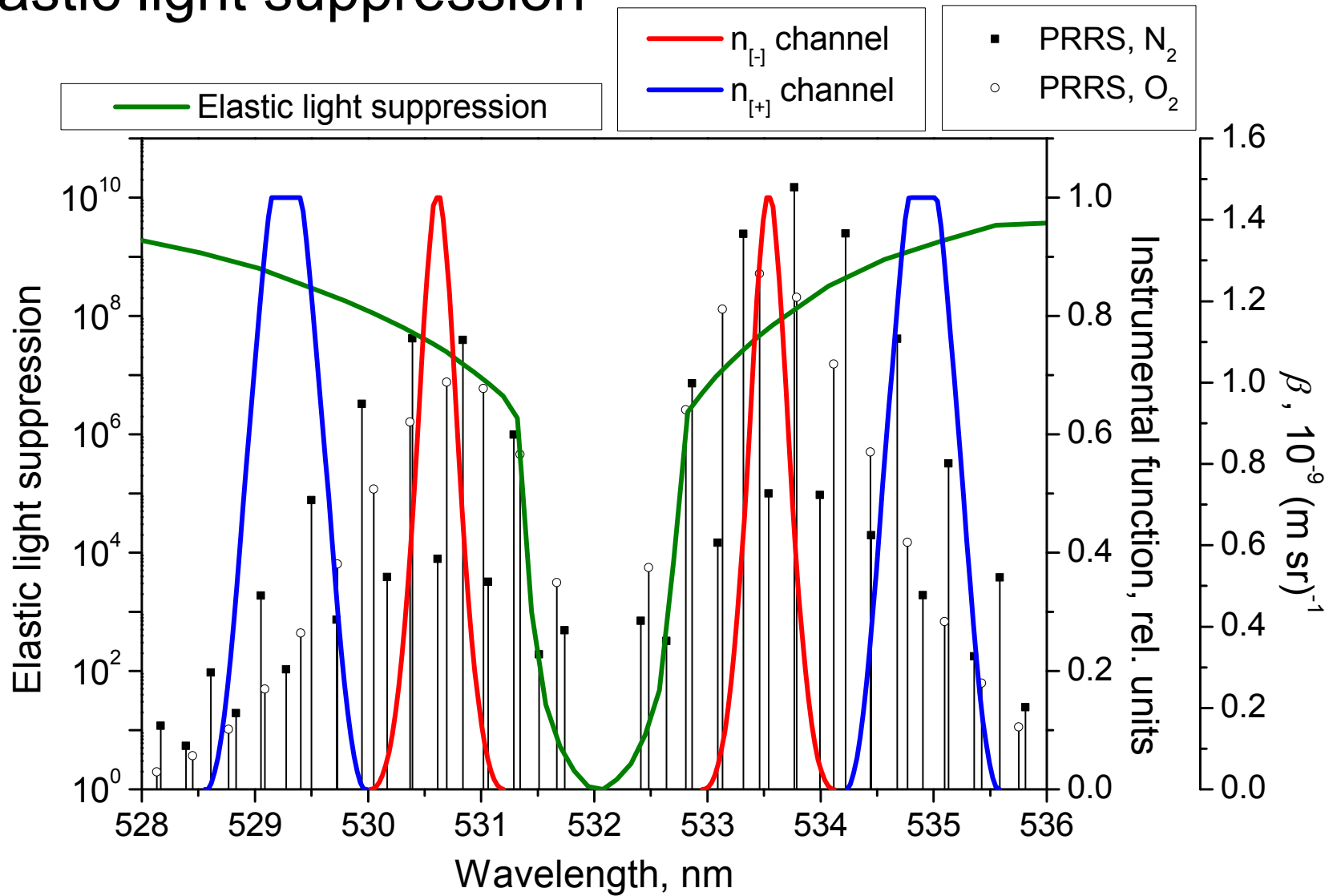
2972-1, 600 g/mm, 2.7  $\mu\text{m}$ , 54 deg., M=5, Cat# 53-\*466, Plane ruled, Max RA 102 x 102 mm



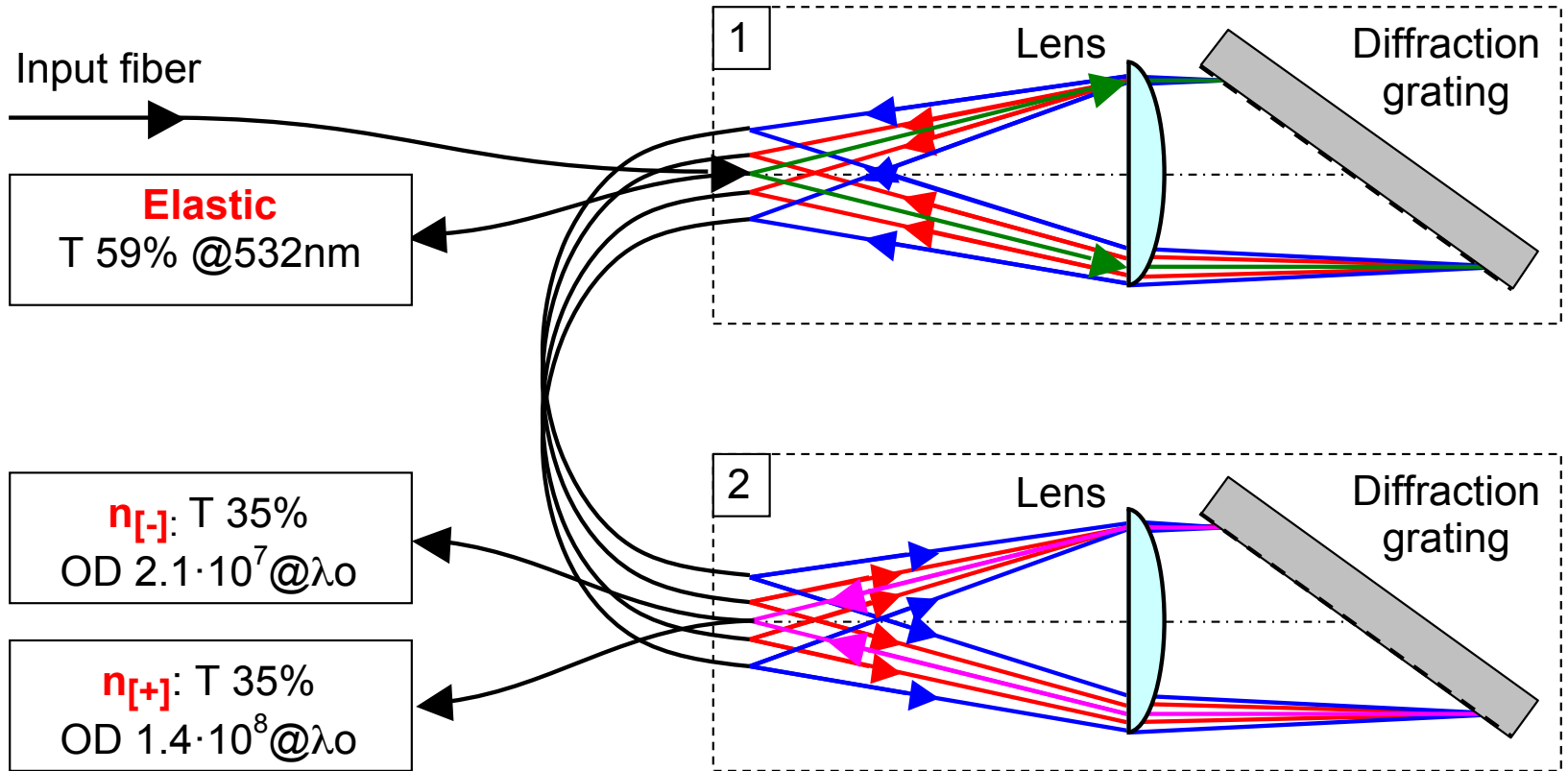
# Diffraction grating efficiency (Richardson Gratings Lab)



# Elastic light suppression



# Grating polychromator: efficiency and stray light suppression



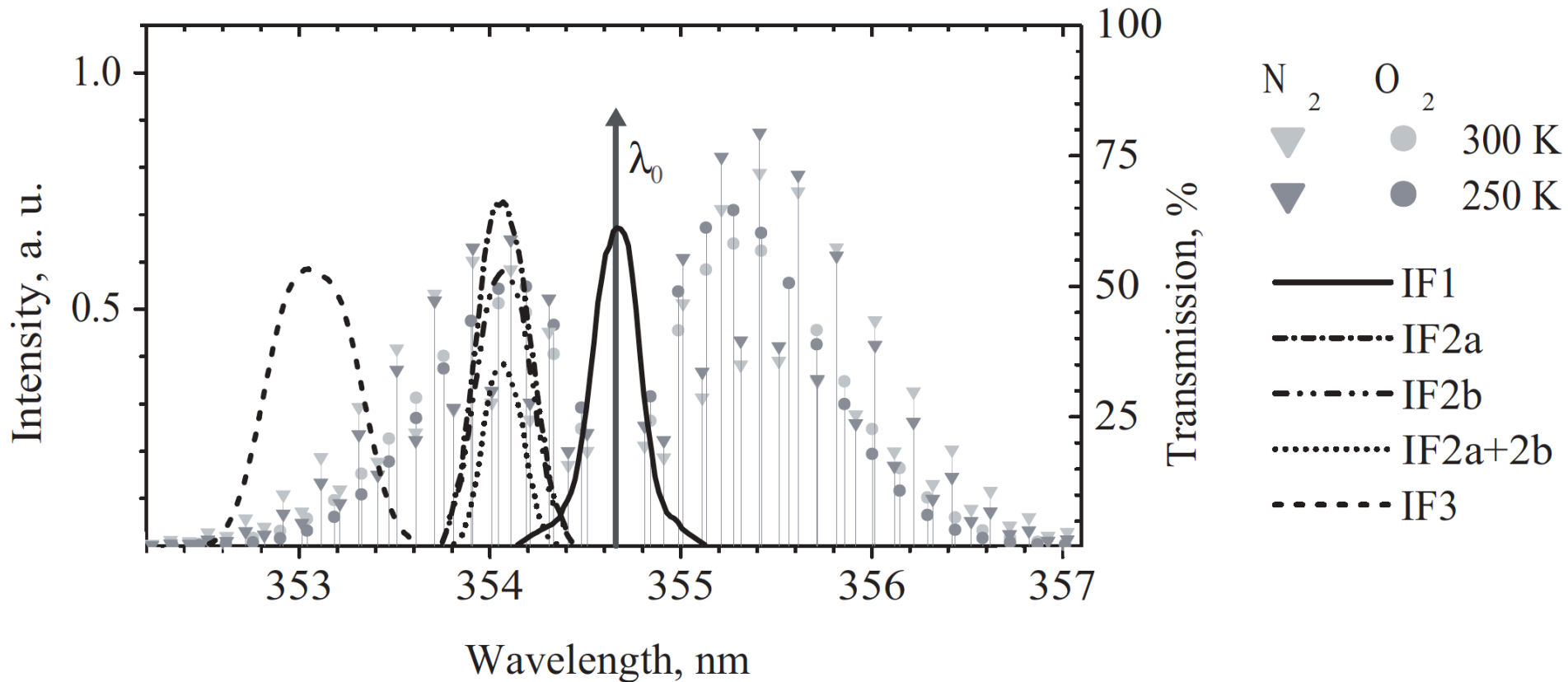
“Effective” polychromator transmission:  $n_{[-]}$  T = 78%,  $n_{[+]}$  T = 100%

$$\left. \frac{n_{[-]}^{total}}{n_{[-]}^{anti-stokes}} \right|_{220K} = 2.24$$

$$\left. \frac{n_{[+]}^{total}}{n_{[+]}^{anti-stokes}} \right|_{220K} = 2.86$$

$$N_{lines}^{eff} = 5.3 \div 7 @273K$$

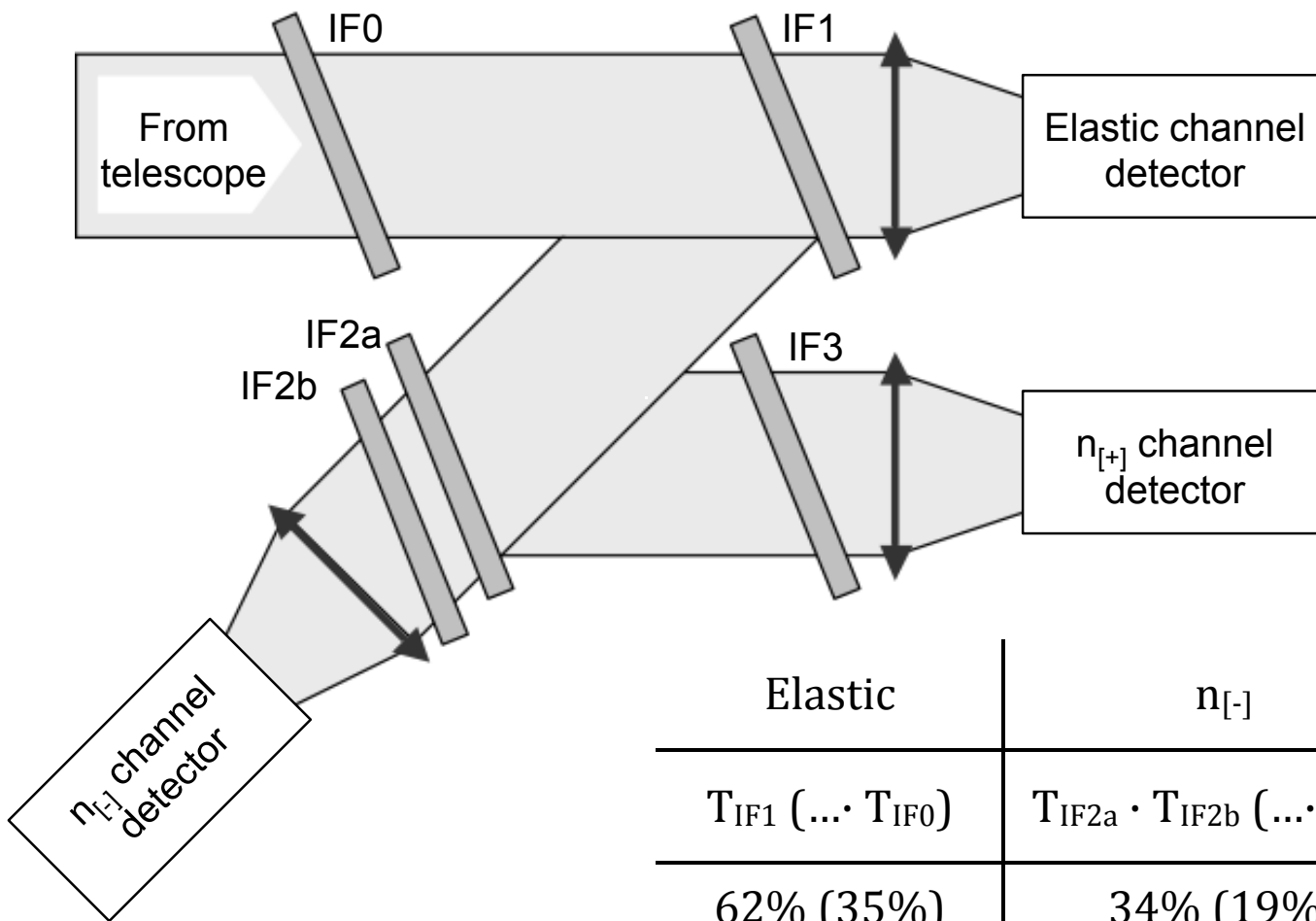
# Isolating “temperature-sensitive” lines with interference filters



“Transmission of interference filters and PRRS of  $N_2$  and  $O_2$  at 300K and 250K”

after Radlach et al. “Scanning rotational Raman lidar at 355nm for the measurement of tropospheric temperature fields”, Atmos. Chem. Phys., 8, 159–169, 2008

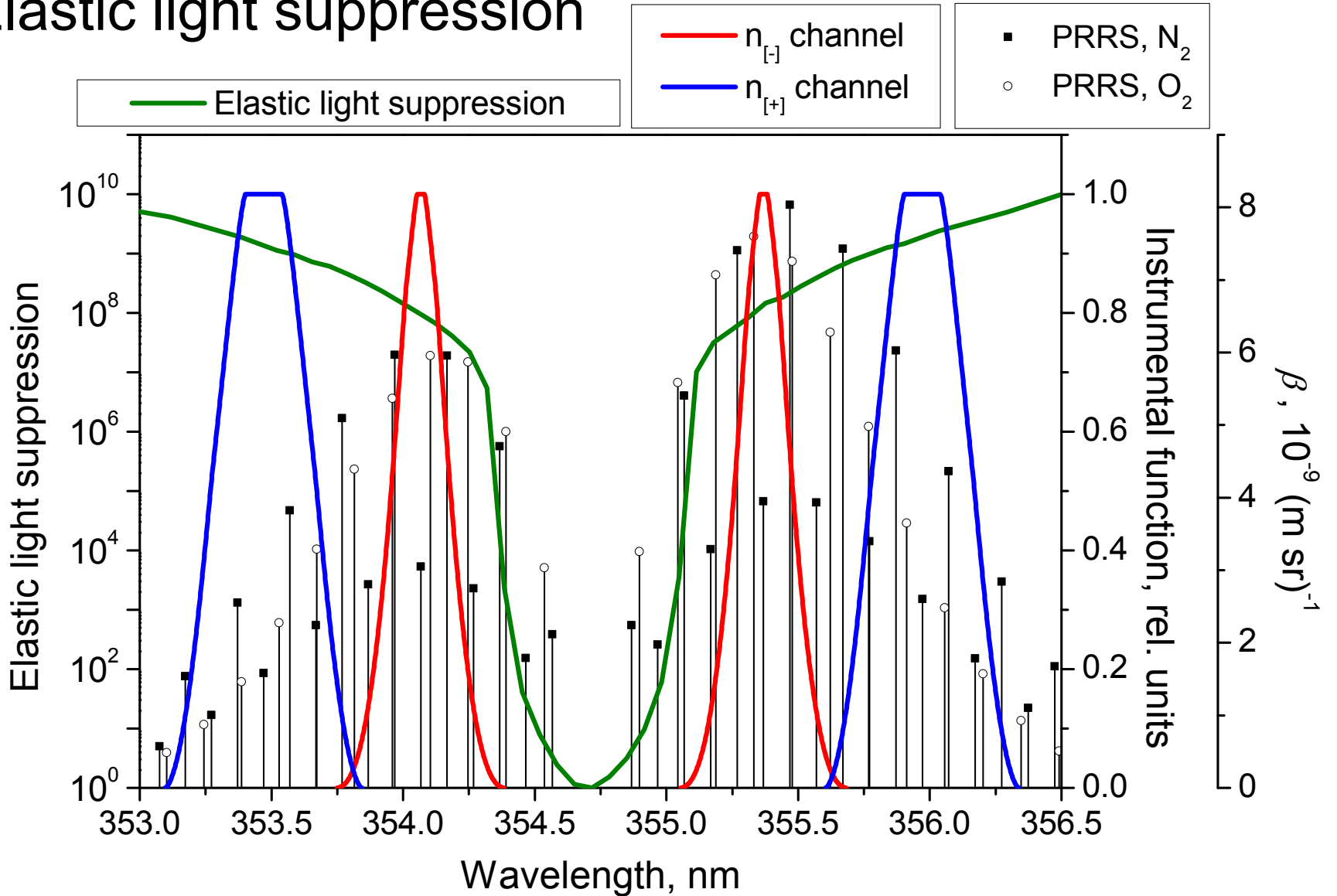
# Isolating “temperature-sensitive” lines with interference filters



Elastic	$n_{[-]}$	$n_{[+]}$
$T_{IF1} (\dots T_{IF0})$	$T_{IF2a} \cdot T_{IF2b} (\dots T_{IF0})$	$T_{IF3} (\dots T_{IF0})$
62% (35%)	34% (19%) OD7@355nm	52% (29%) OD7@355nm

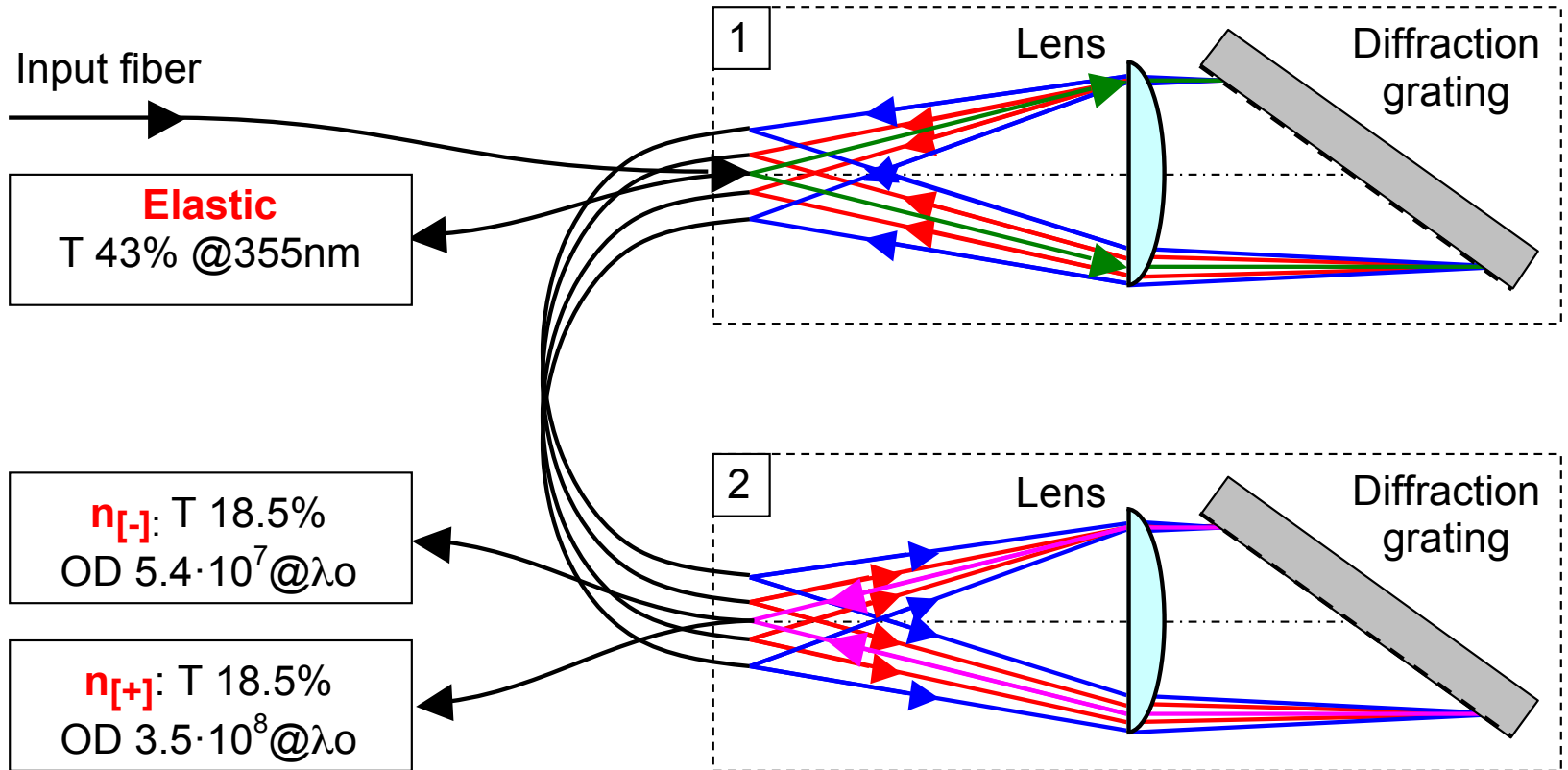
after Radlach et al. “Scanning rotational Raman lidar at 355nm for the measurement of tropospheric temperature fields”, Atmos. Chem. Phys., 8, 159–169, 2008

# Elastic light suppression





# Grating polychromator: efficiency and stray light suppression

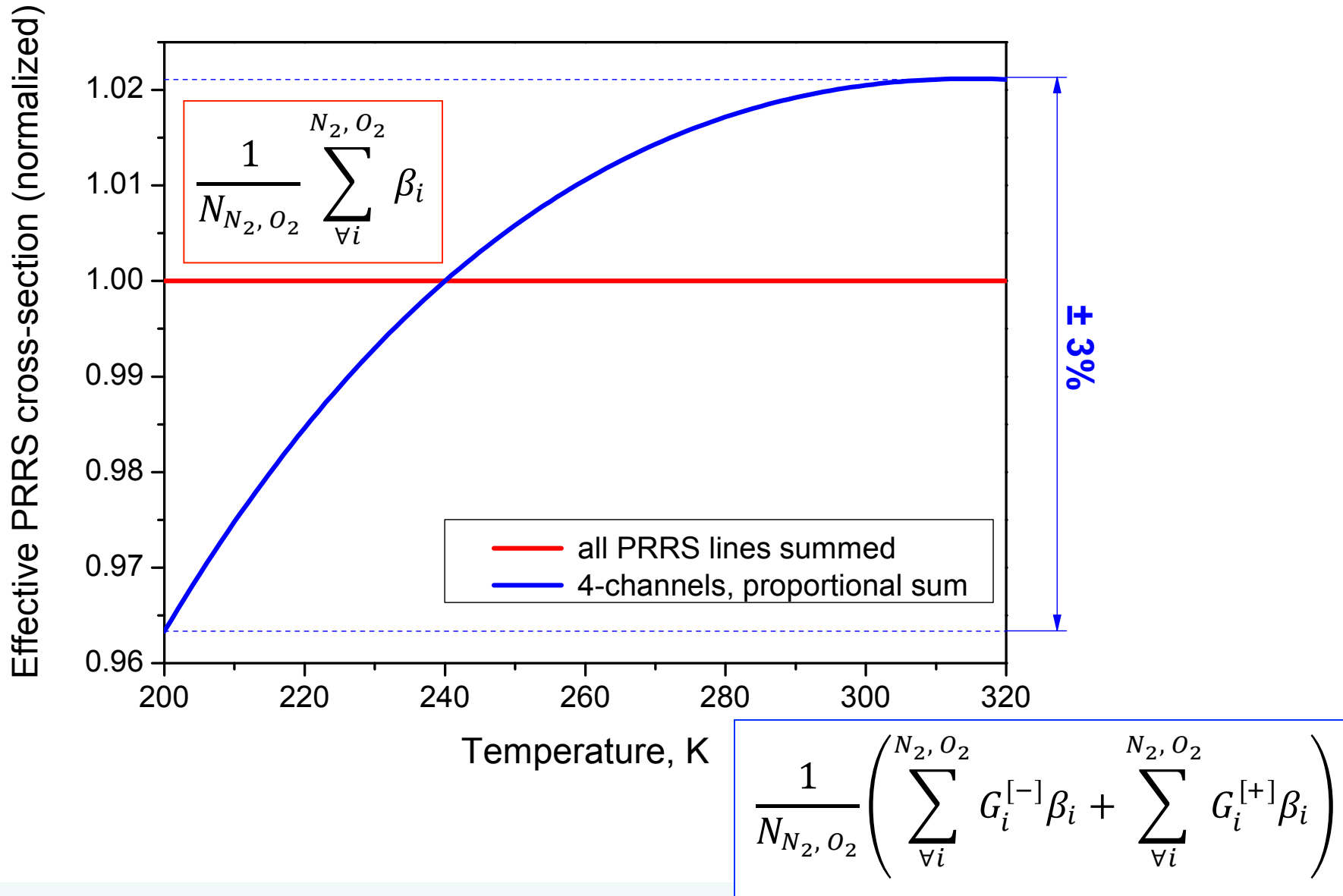


“Effective” polychromator transmission:  $n_{[-]}$  T = 41%,  $n_{[+]}$  T = 53%

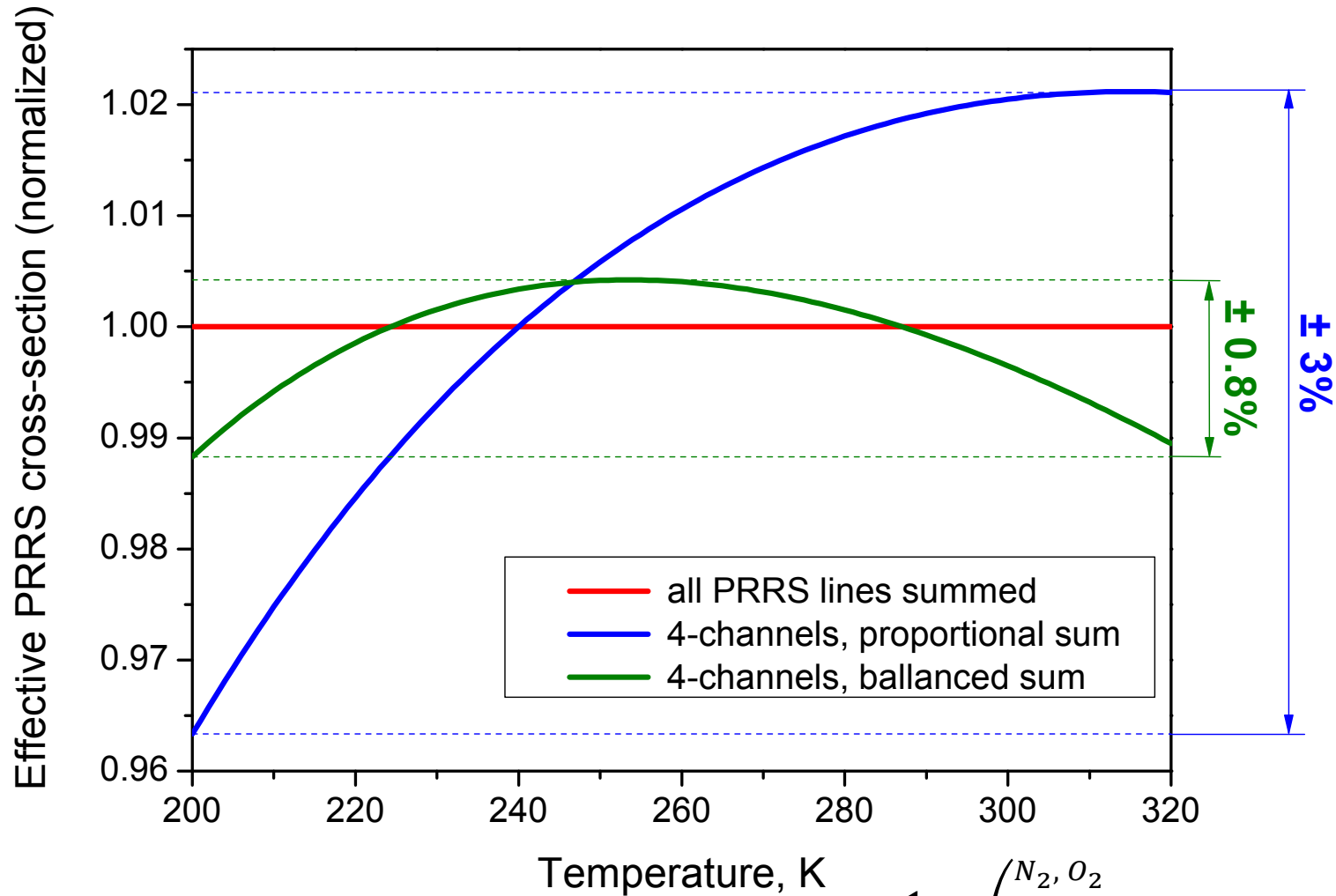
$$\left. \frac{n_{[-]}^{total}}{n_{[-]}^{anti-stokes}} \right|_{220K} = 2.24$$

$$\left. \frac{n_{[+]}^{total}}{n_{[+]}^{anti-stokes}} \right|_{220K} = 2.86$$

# Temperature dependence of combined PRRS signal

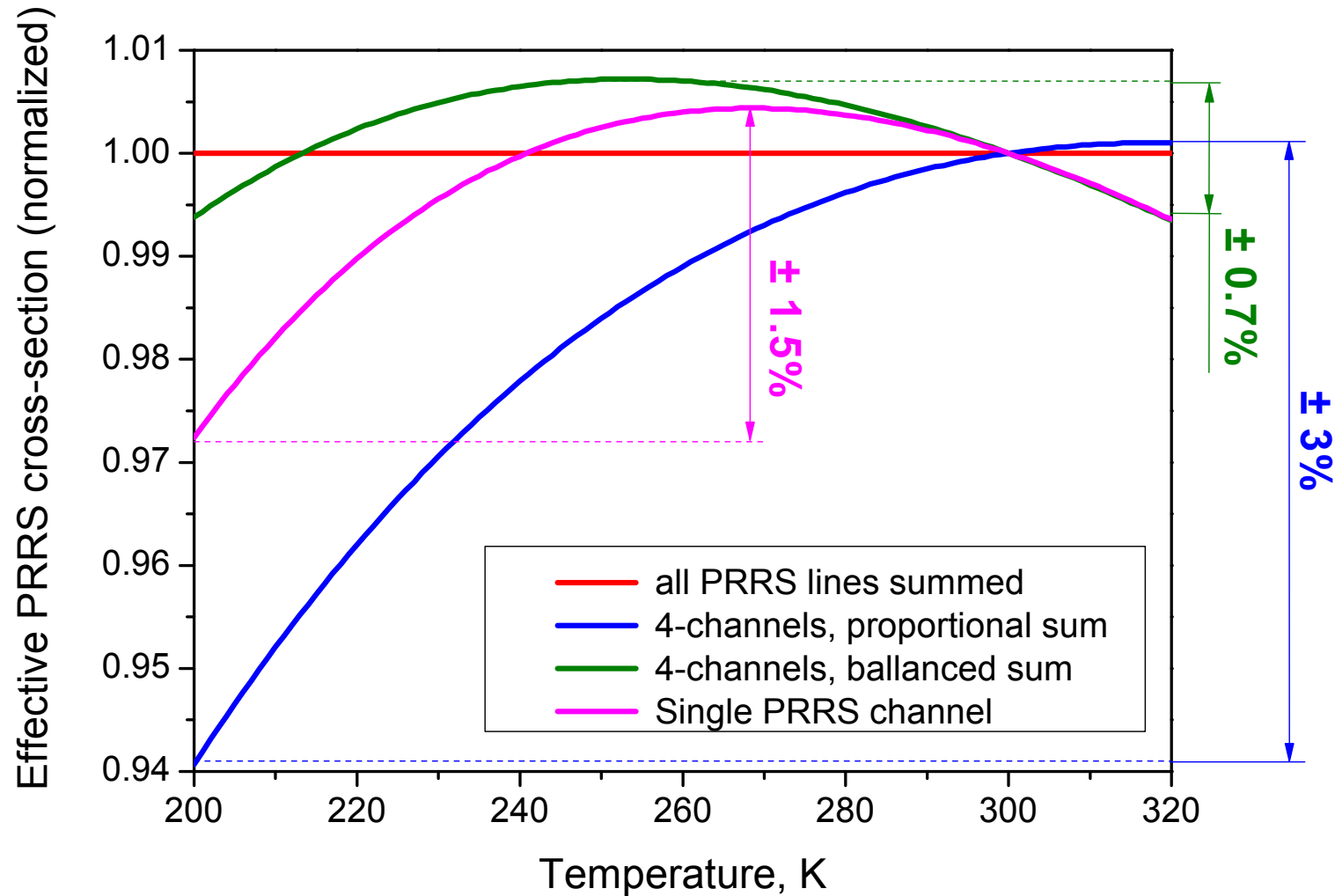


# Temperature dependence of combined PRRS signal

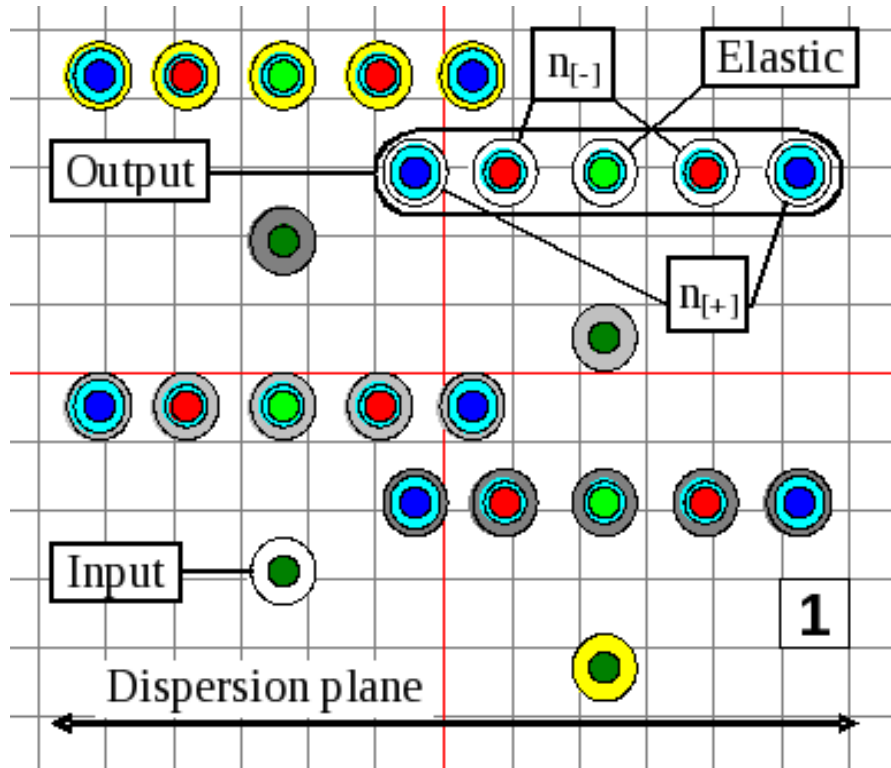


$$\frac{1}{N_{N_2, O_2}} \left( \sum_{\forall i}^{N_2, O_2} G_i^{[-]} \beta_i + \boxed{\text{coef}} \cdot \sum_{\forall i}^{N_2, O_2} G_i^{[+]} \beta_i \right)$$

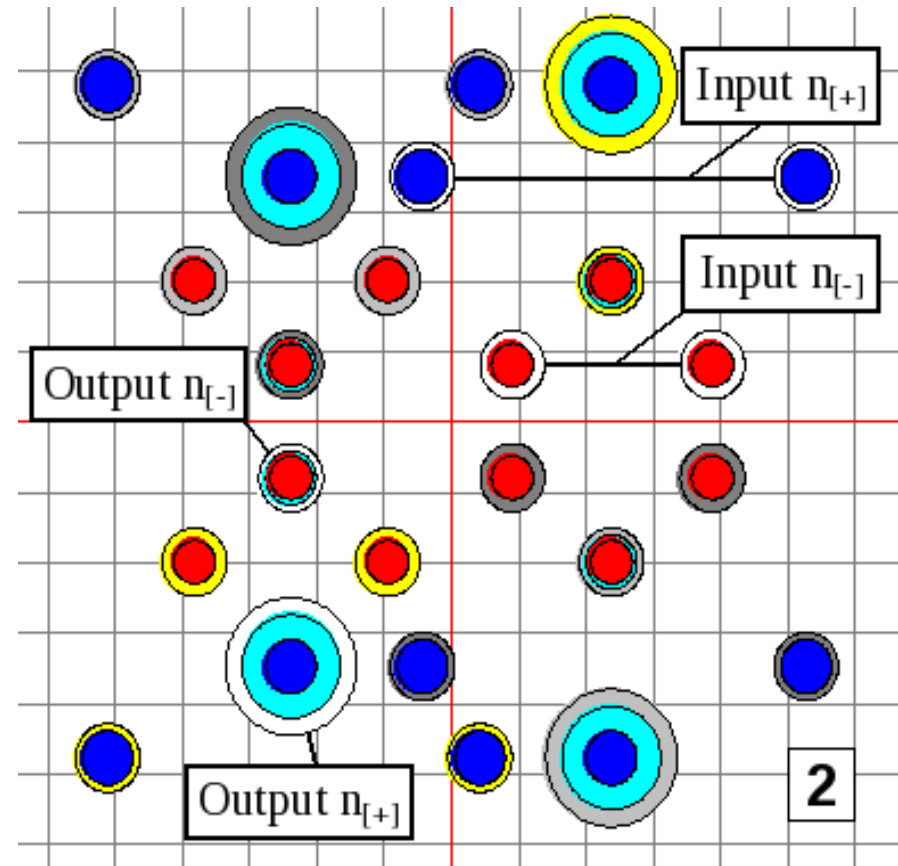
# Temperature dependence of combined PRRS signal



# “Four telescopes” configuration



first unit



second unit

# Lidar signal and skylight background

Atmospheric response:

$$P(r) = E_0 f_L Q(r) K \frac{A}{r^2} \frac{c\tau}{2} \beta_\pi(r) \exp\left(-2 \int_0^r \alpha(x) dx\right)$$

Sky background:

$$P_{BGR} = E_\nu K A \Delta\Omega \Delta\nu f_L \tau$$

Signal to background:

$$\frac{P}{P_{BGR}} \sim \frac{E_0 \beta_\pi}{\Delta\Omega \Delta\nu}$$

$E_0$  laser pulse energy

$f_L$  pulse repetition rate

$K$  total throughput

$A$  receiving telescope area

$\tau$  time bin length

$Q(r)$  overlap function

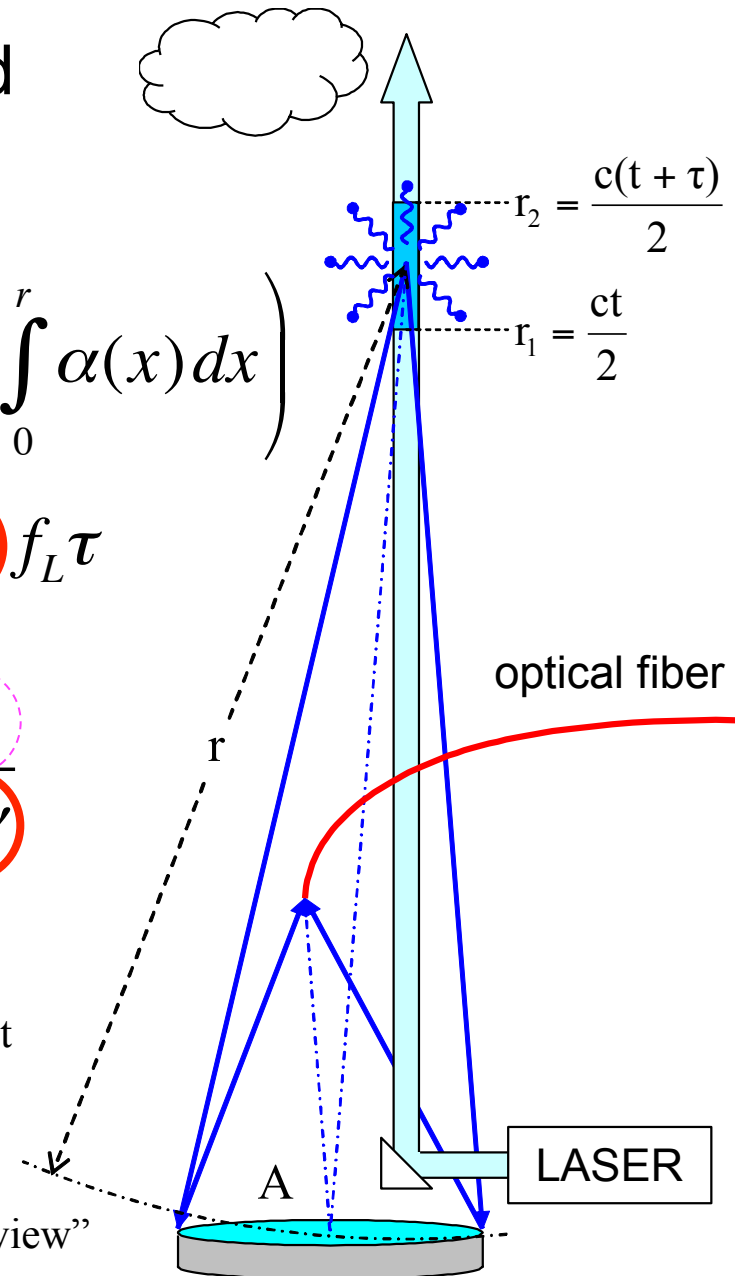
$E_\nu$  sky brightness density

$\beta_\pi(r)$  backscatter coefficient

$\alpha(r)$  extinction coefficient

$\Delta\nu$  spectral passband

$\Delta\Omega$  solid angle of “field-of-view”



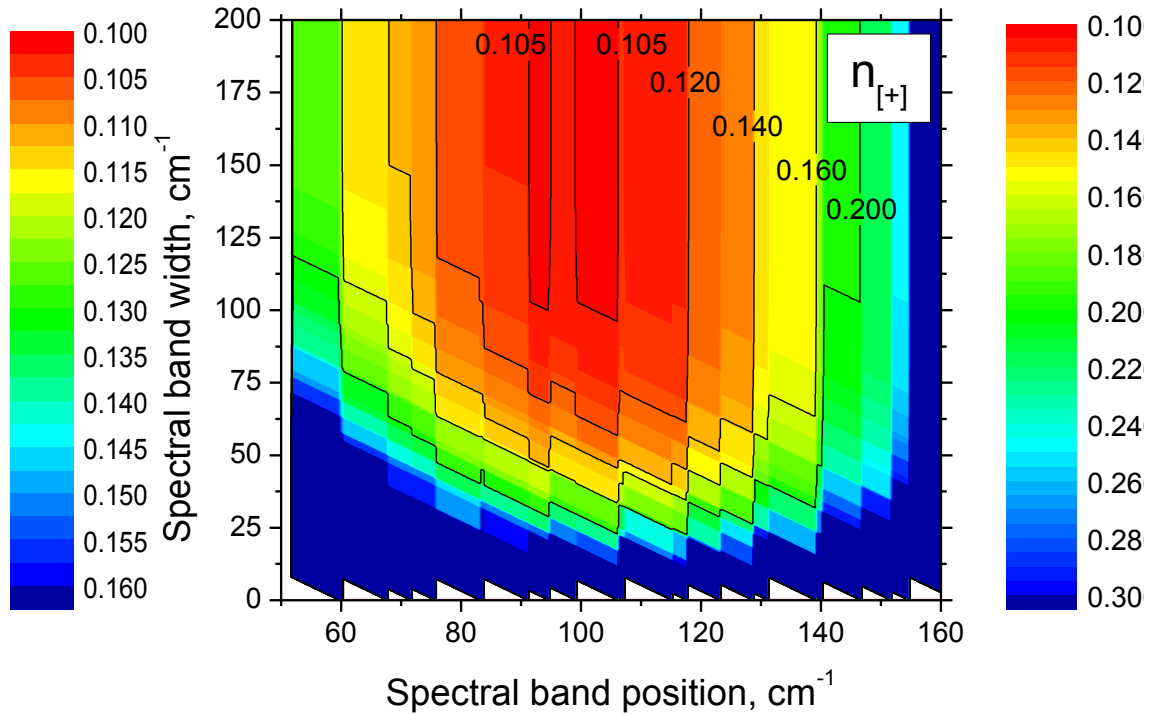
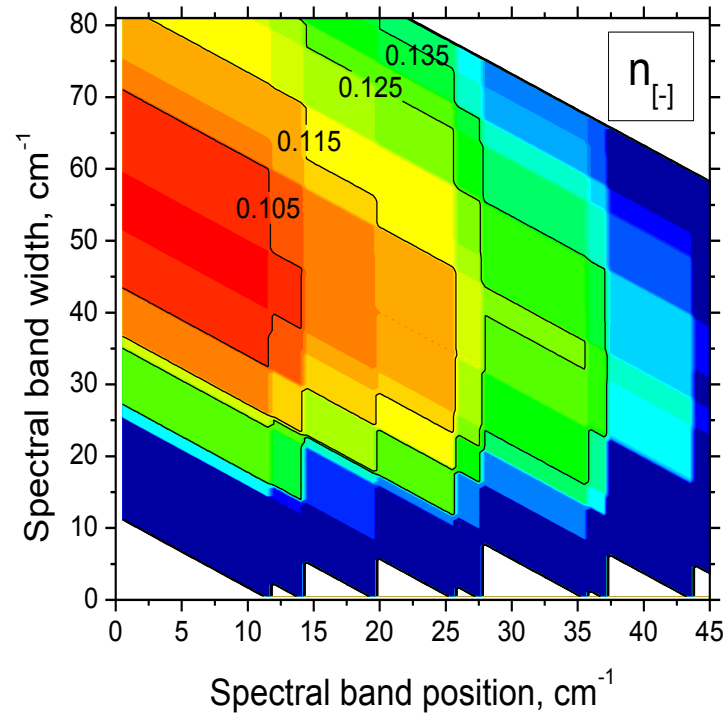
# Temperature channel for night-time operation

$$R = \frac{N_{[-]}}{N_{[+]}} \quad \frac{\Delta R}{\bar{R}} = \sqrt{\frac{\mu_2(N_{[-]})}{\bar{N}_{[-]}^2} + \frac{\mu_2(N_{[+]})}{\bar{N}_{[+]}^2}} \quad \frac{\Delta R}{\bar{R}} = \sqrt{\frac{1}{\bar{N}_{[-]}} + \frac{1}{\bar{N}_{[+]}}}$$

$$\Delta R = \pm 2.24 \bar{R} \sqrt{\frac{1}{\bar{N}_{[-]}} + \frac{1}{\bar{N}_{[+]}}} \quad \Delta R = \frac{dR}{dT} \Delta T \quad \Delta T = \frac{4.48}{\sqrt{\Delta t}} \sqrt{\frac{1}{n_{[-]}} + \frac{1}{n_{[+]}}} \frac{1}{\bar{R}} \frac{dR}{dT}$$

$$\Delta t = \left( \frac{1}{n_{[-]}} + \frac{1}{n_{[+]}} \right) \left( \frac{4.48}{\Delta T} \frac{1}{\bar{R}} \frac{dR}{dT} \right)^2 \quad \delta t = \frac{\Delta t}{[\Delta t]_{norm}}$$

# Optimum spectral intervals (night-time)





# Temperature channel for daytime operation

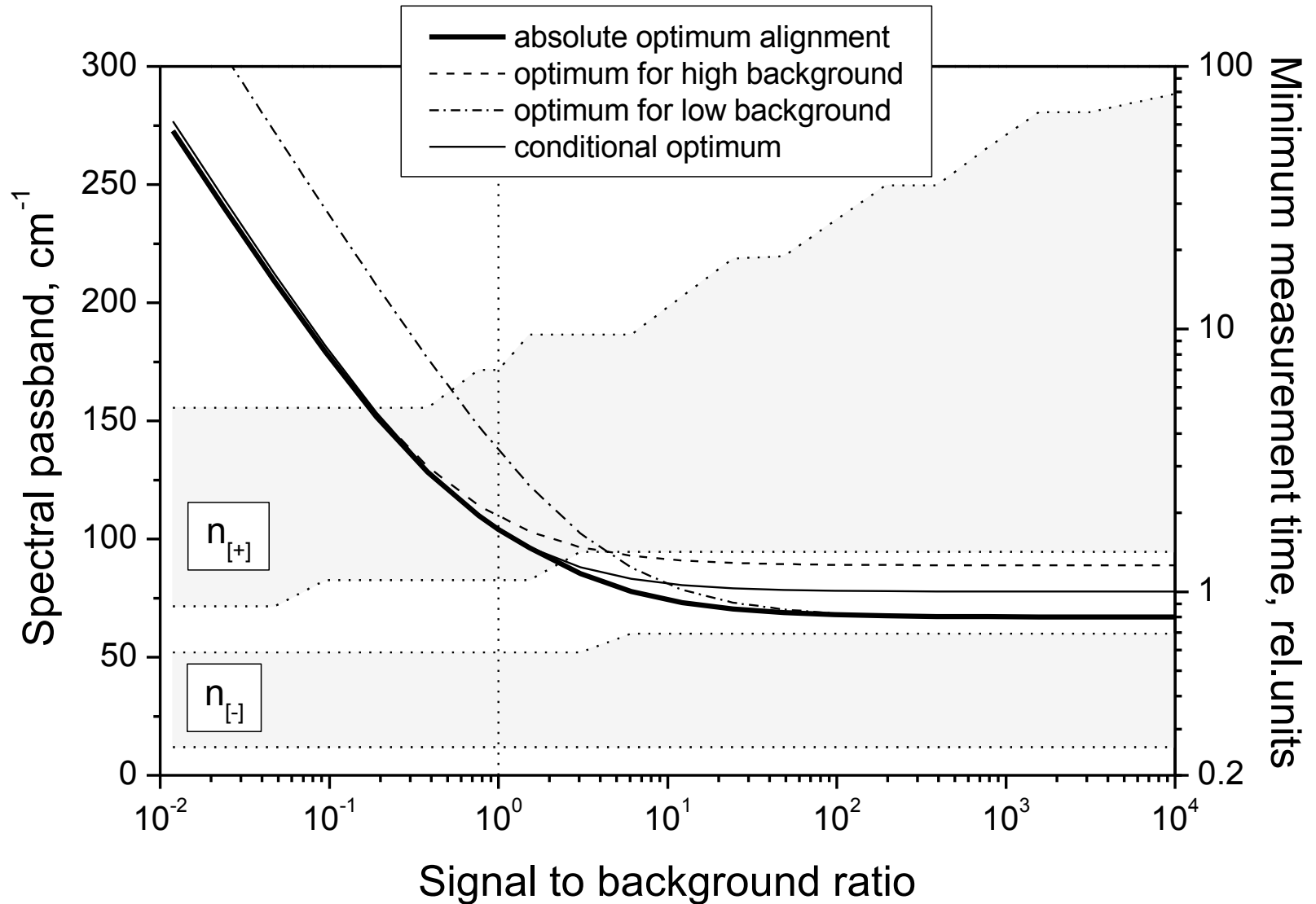
$$\tilde{N}_{[-]} = (n_{[-]} + n_v^{sky} \cdot \Delta v_{[-]}) \Delta t$$

$$\tilde{N}_{[+]} = (n_{[+]} + n_v^{sky} \cdot \Delta v_{[+]}) \Delta t$$

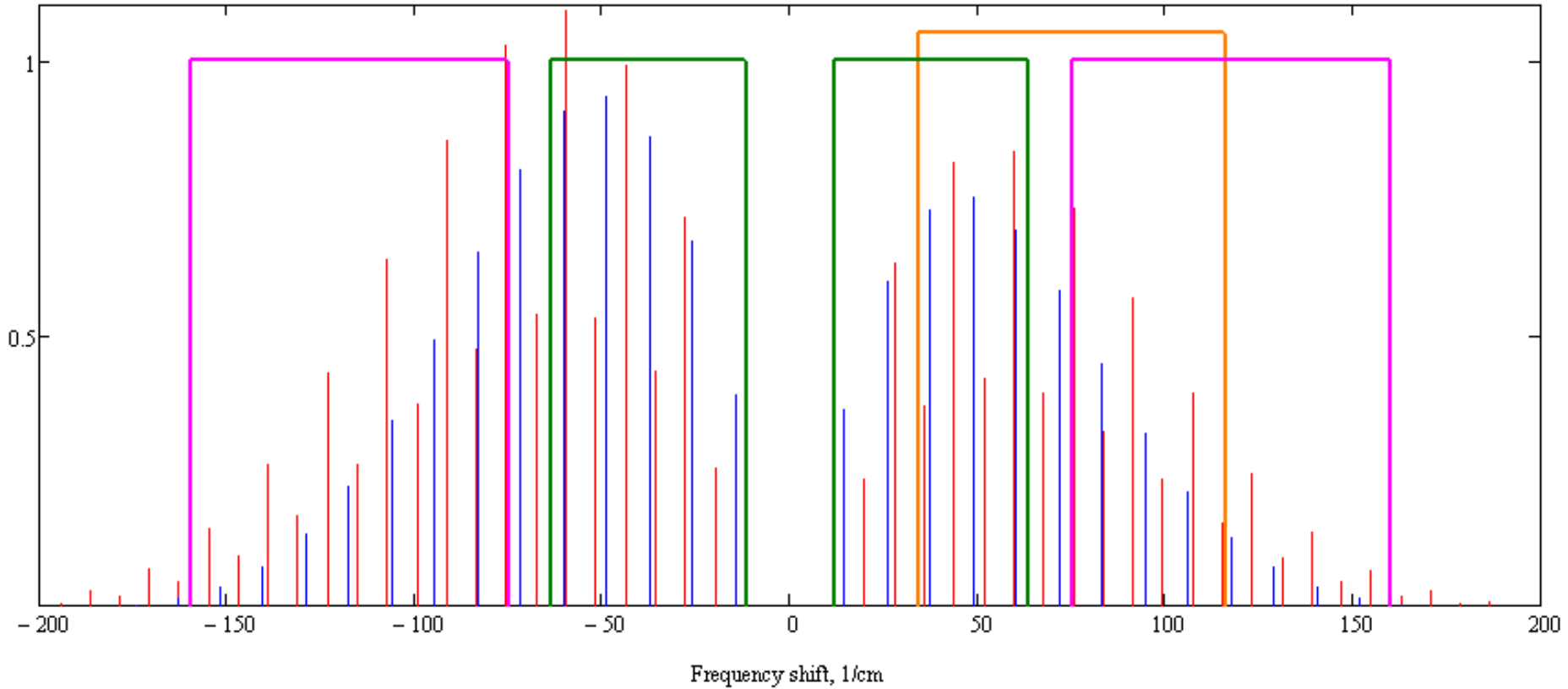
$$R = \frac{\tilde{N}_{[-]} - \overline{n_v^{sky}} \Delta v_{[-]} \Delta t}{\tilde{N}_{[+]} - \overline{n_v^{sky}} \Delta v_{[+]} \Delta t}$$

$$\Delta t = \left( \frac{\overline{n_{[-]} + n_v^{sky} \Delta v_{[-]}}}{\overline{n_{[-]}}^2} + \frac{\overline{n_{[+]} + n_v^{sky} \Delta v_{[+]}}}{\overline{n_{[+]}}^2} \right) \left( \frac{4.48}{\Delta T} \frac{1}{\overline{R}} \frac{dR}{dT} \right)^2$$

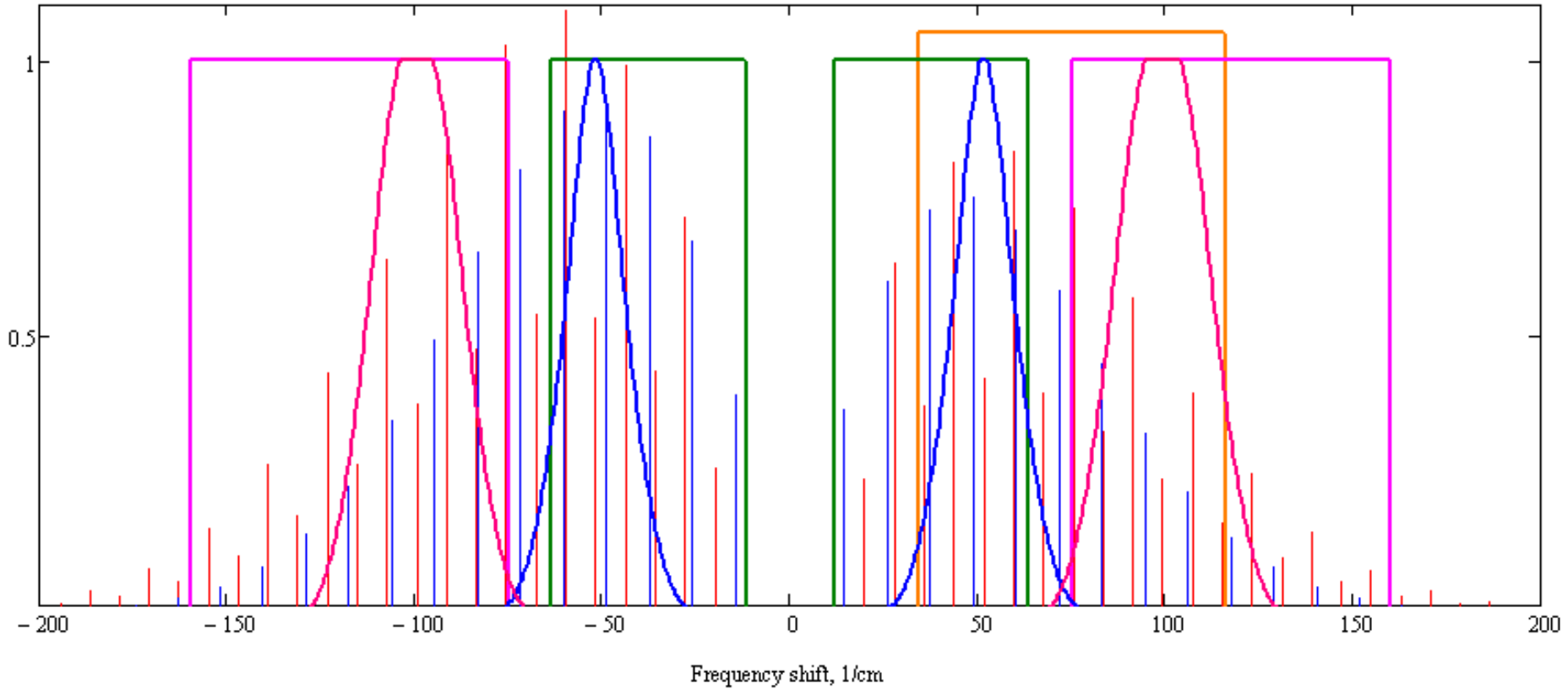
# Optimum spectral intervals (daytime)



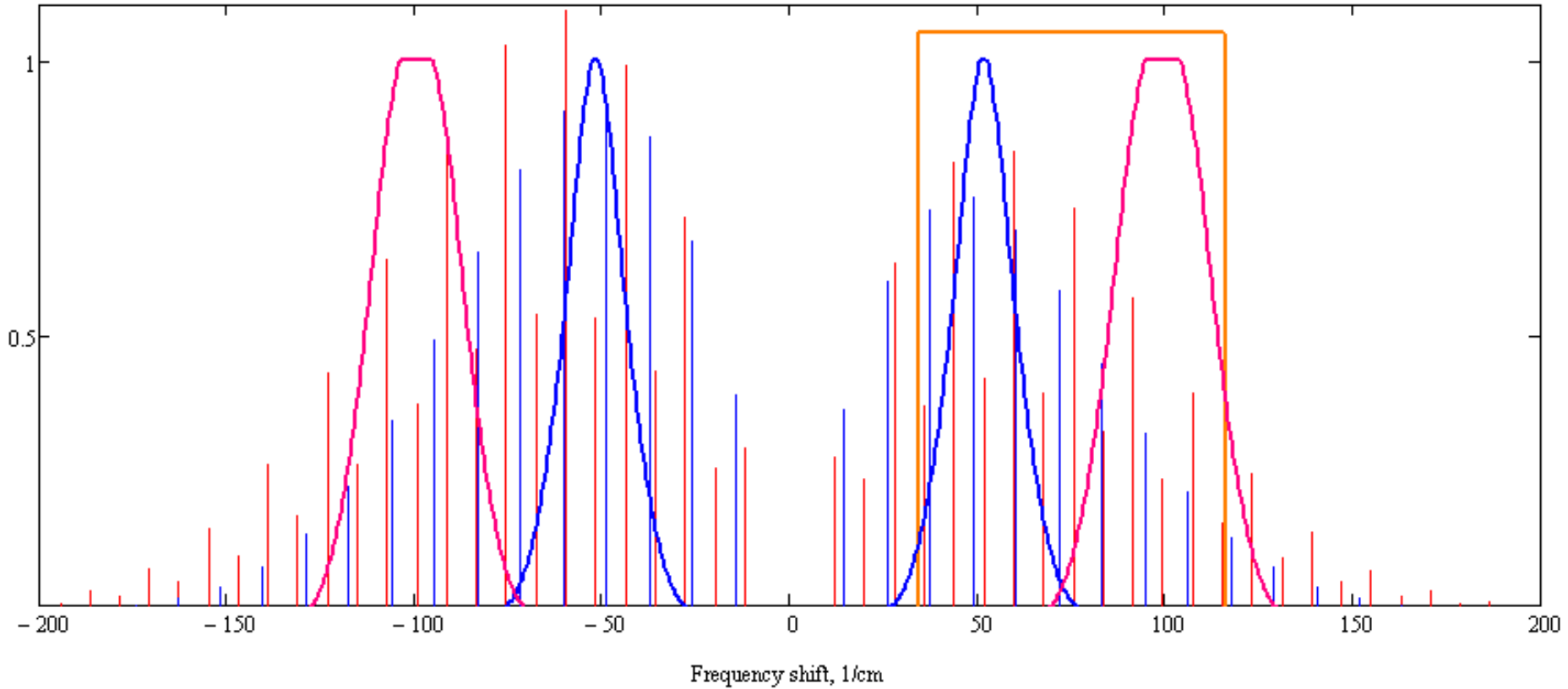
# Optimum spectral intervals (daytime)



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# Optimum spectral intervals (daytime)



# Lidar signal and skylight background

Atmospheric response:

$$P(r) = E_0 f_L Q(r) K \frac{A}{r^2} \frac{c\tau}{2} \beta_\pi(r) \exp\left(-2 \int_0^r \alpha(x) dx\right)$$

Sky background:

$$P_{BGR} = E_\nu K A \Delta\Omega \Delta\nu f_L \tau$$

Signal to background:

$$\frac{P}{P_{BGR}} \sim \frac{E_0 \beta_\pi}{\Delta\Omega \Delta\nu}$$

$E_0$  laser pulse energy

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$K$  total throughput

$A$  receiving telescope area

$\tau$  time bin length

$Q(r)$  overlap function

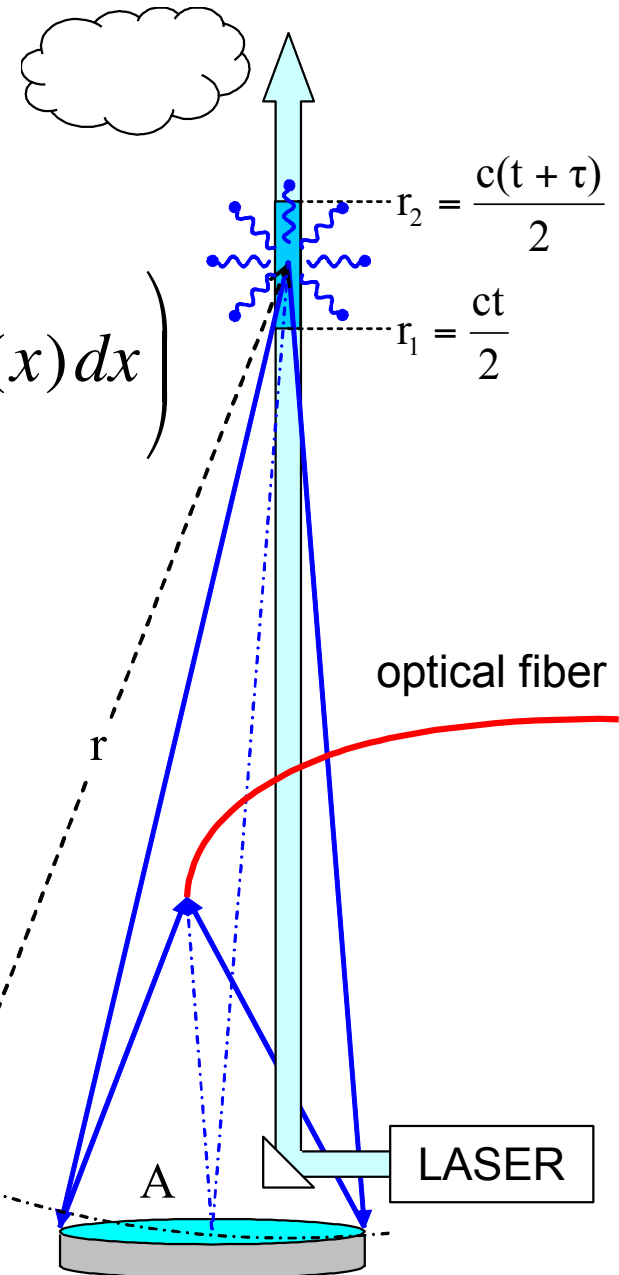
$E_\nu$  sky brightness density

$\beta_\pi(r)$  backscatter coefficient

$\alpha(r)$  extinction coefficient

$\Delta\nu$  spectral passband

$\Delta\Omega$  solid angle of “field-of-view”



# Lidar signal and skylight background

Atmospheric response:

$$P(r) = E_0 f_L Q(r) K \frac{A}{r^2} \frac{c\tau}{2} \beta_\pi(r) \exp\left(-2 \int_0^r \alpha(x) dx\right)$$

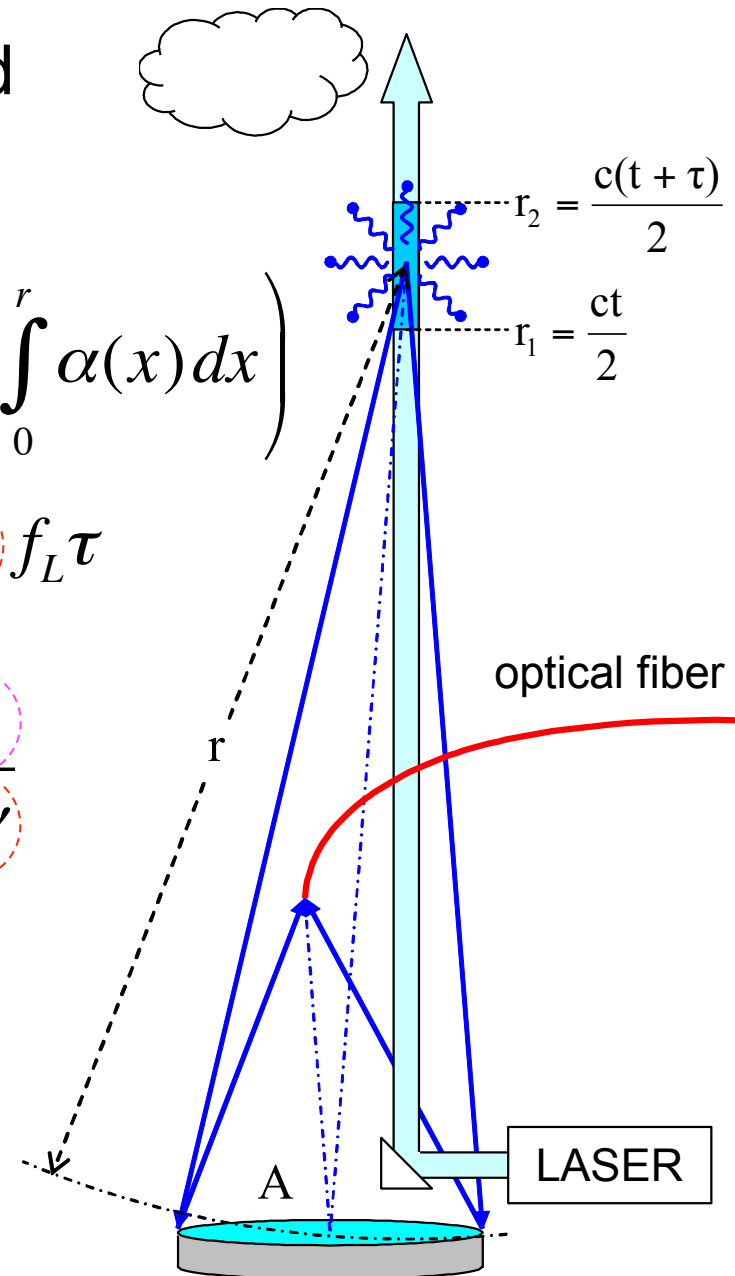
Sky background:

$$P_{BGR} = E_v K A \Delta\Omega \Delta\nu f_L \tau$$

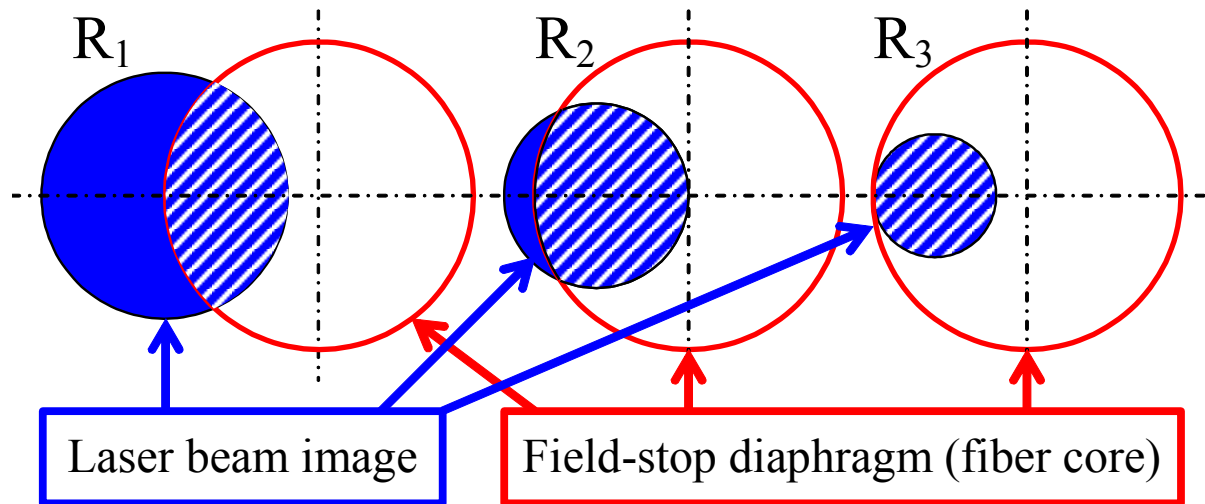
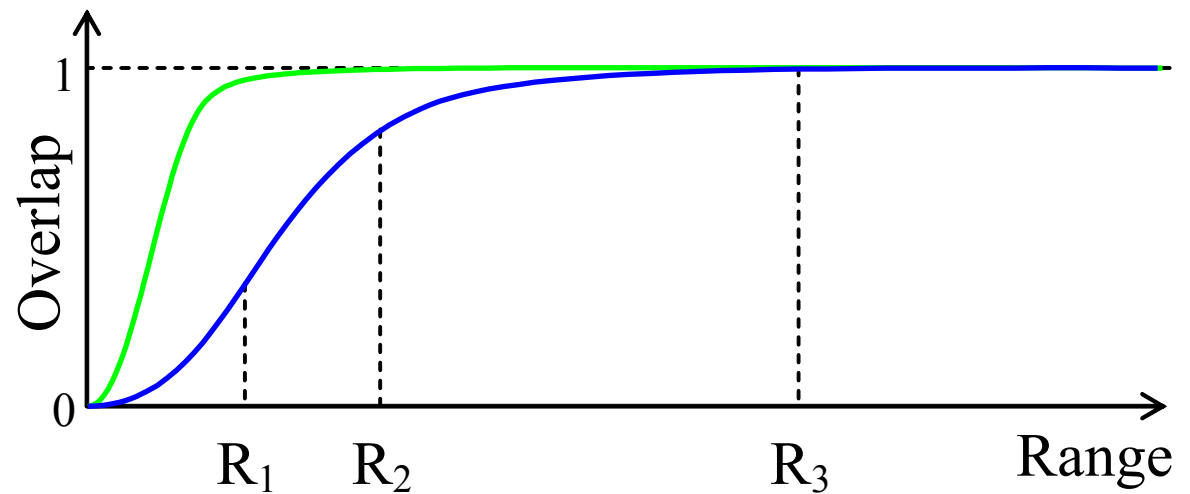
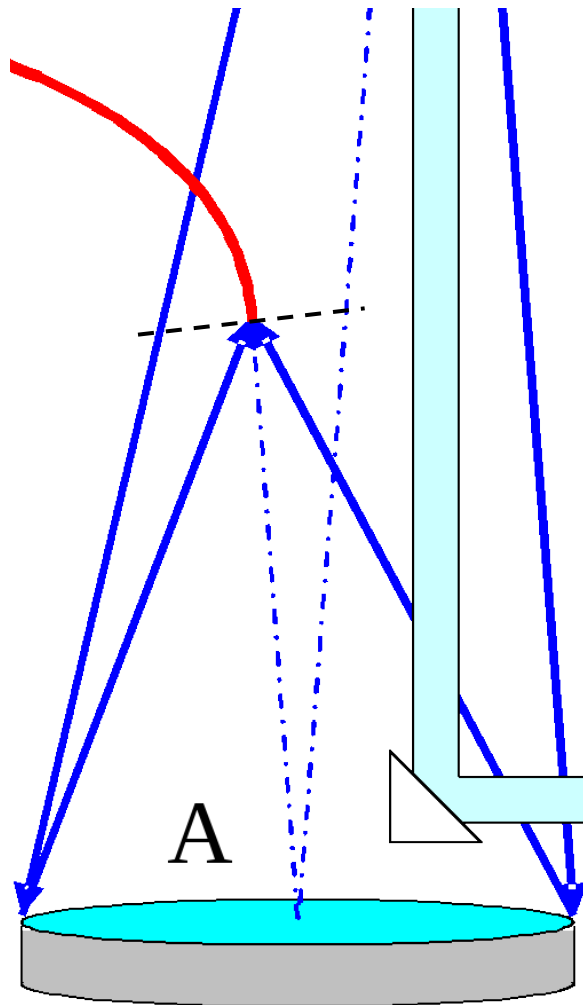
Signal to background:

$$\frac{P}{P_{BGR}} \sim \frac{E_0 \beta_\pi}{\Delta\Omega \Delta\nu}$$

$$\frac{\Delta\Omega(1 \text{ mrad})}{\Delta\Omega(0.2 \text{ mrad})} = 25$$

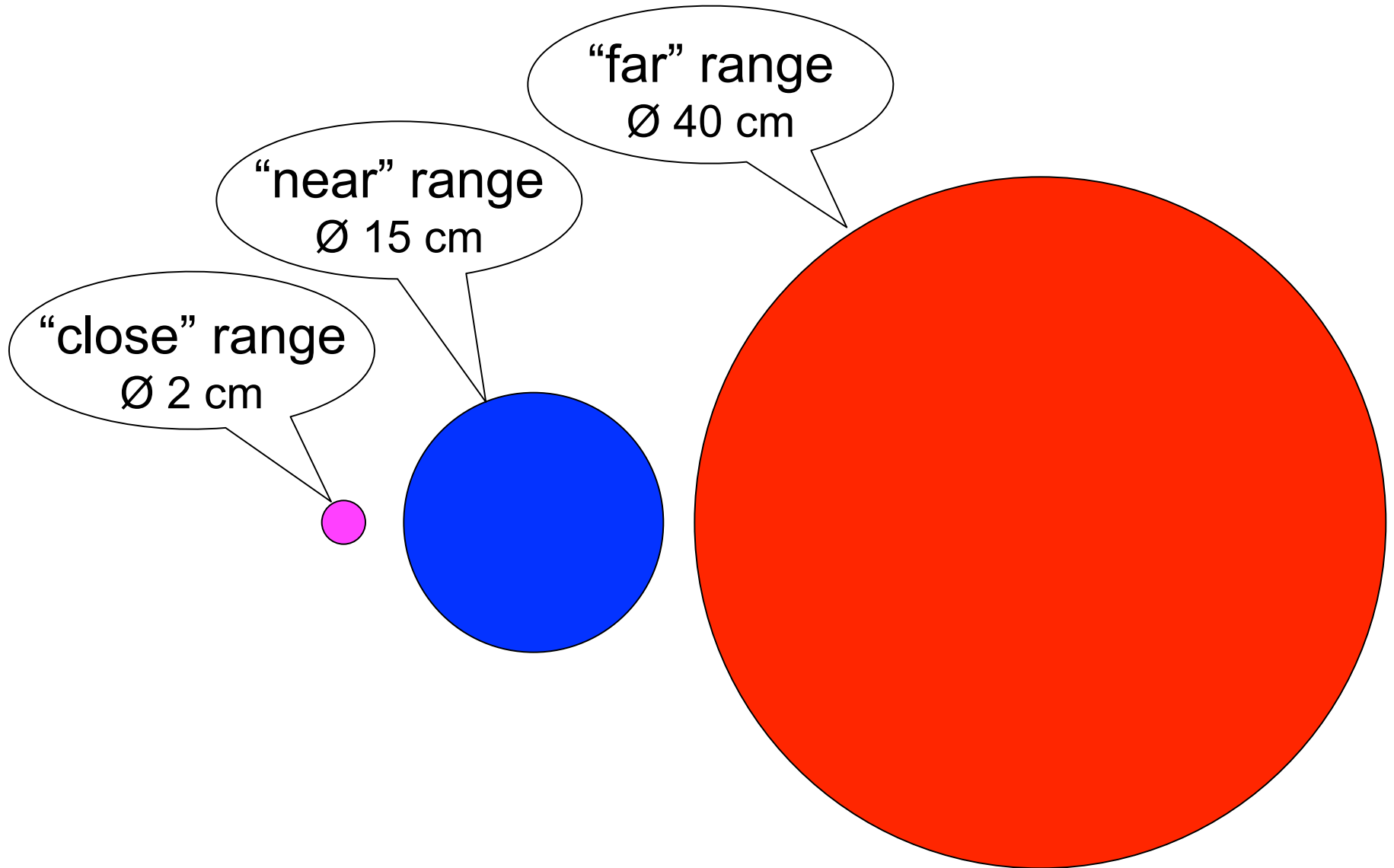


# Overlap function: efficiency of light collection

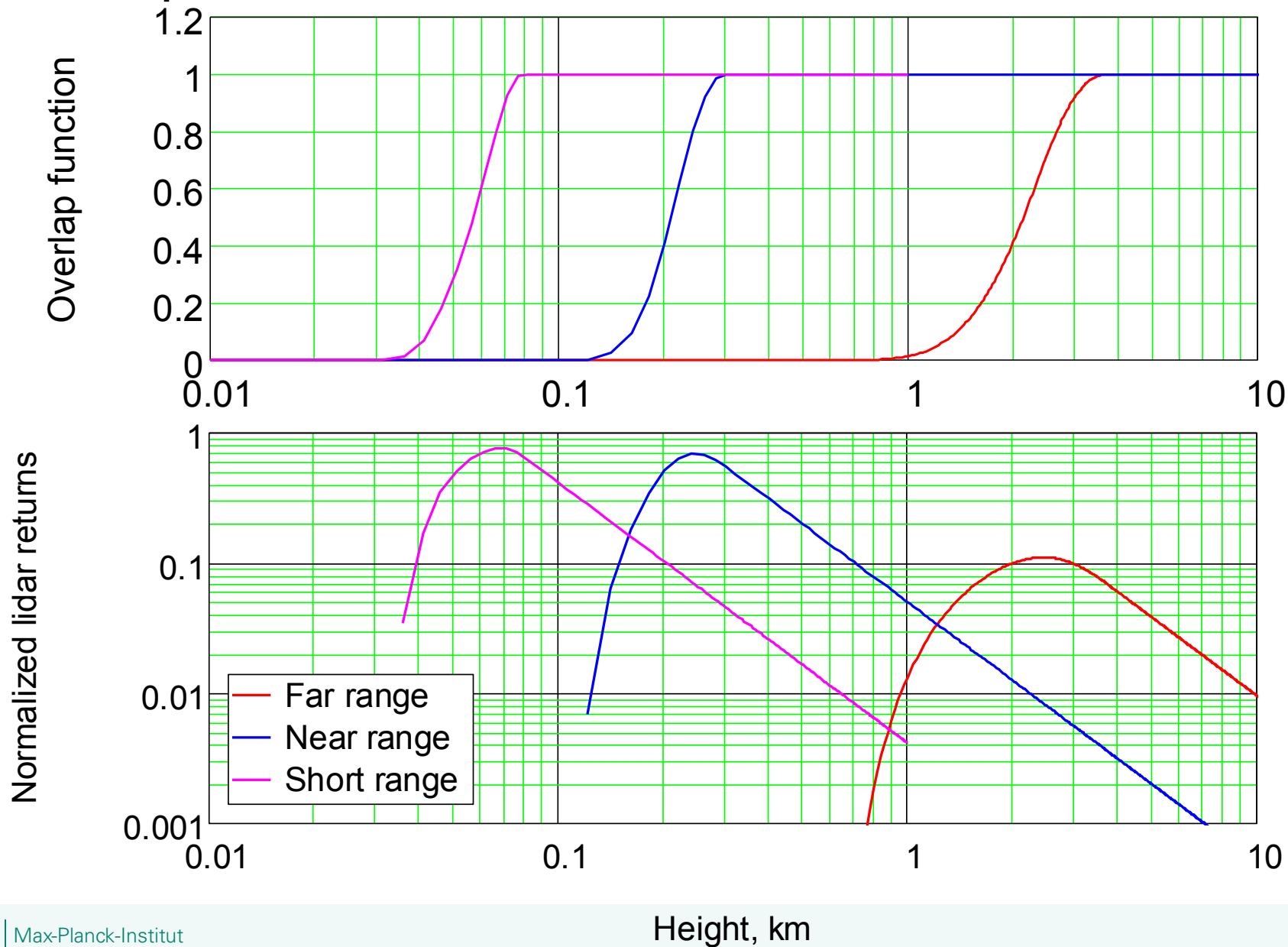




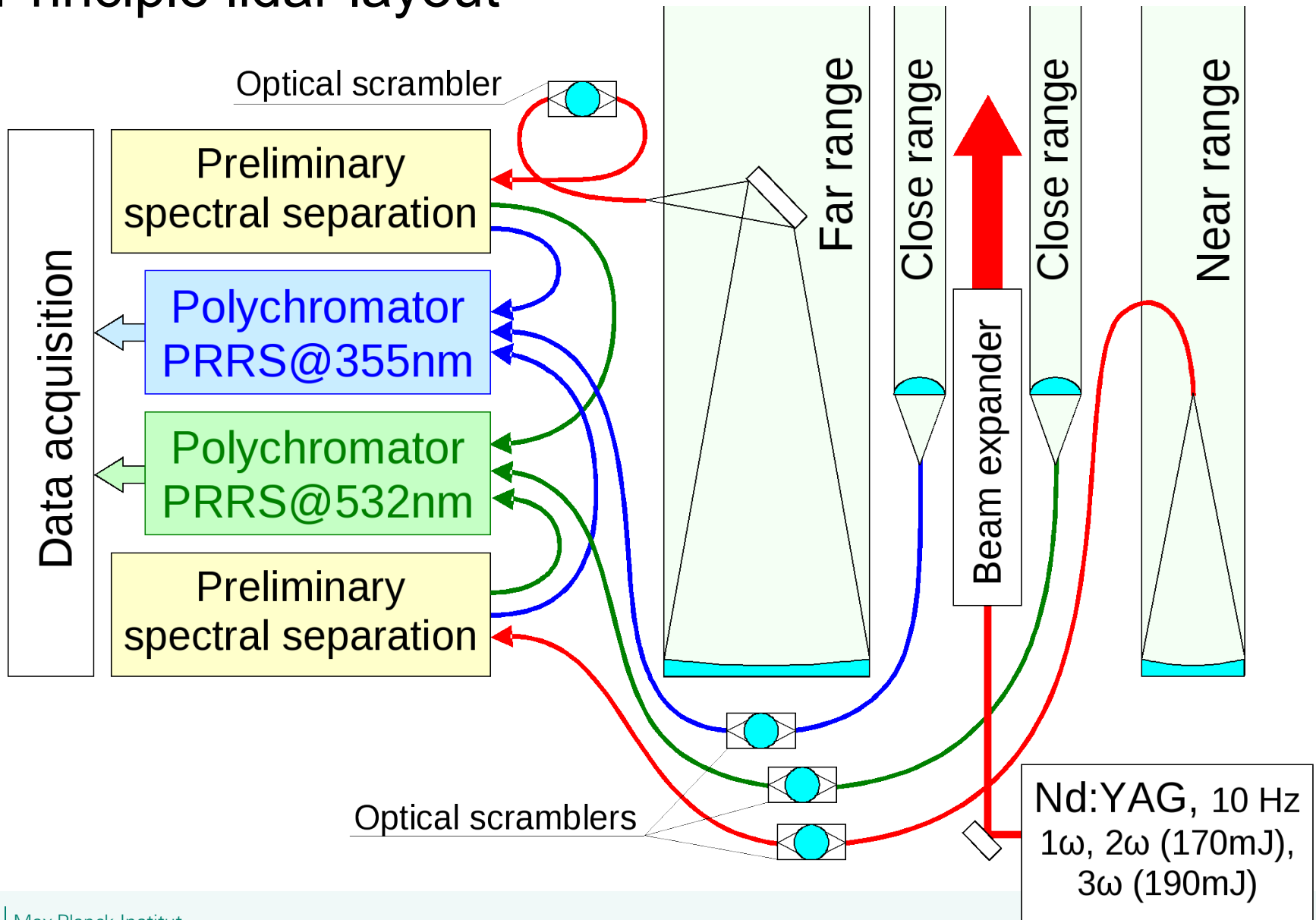
# Telescope assignment



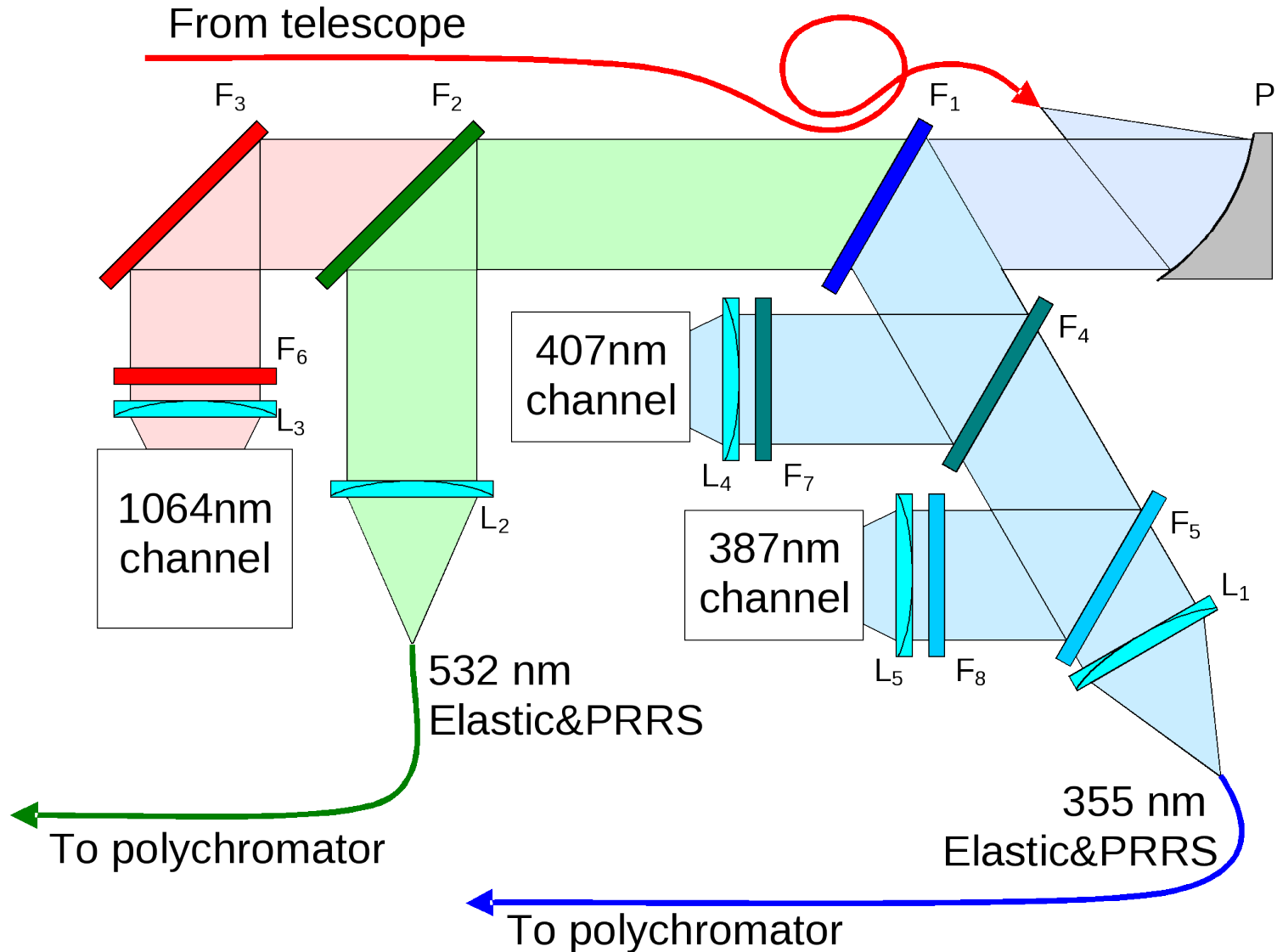
# Overlap function & lidar returns



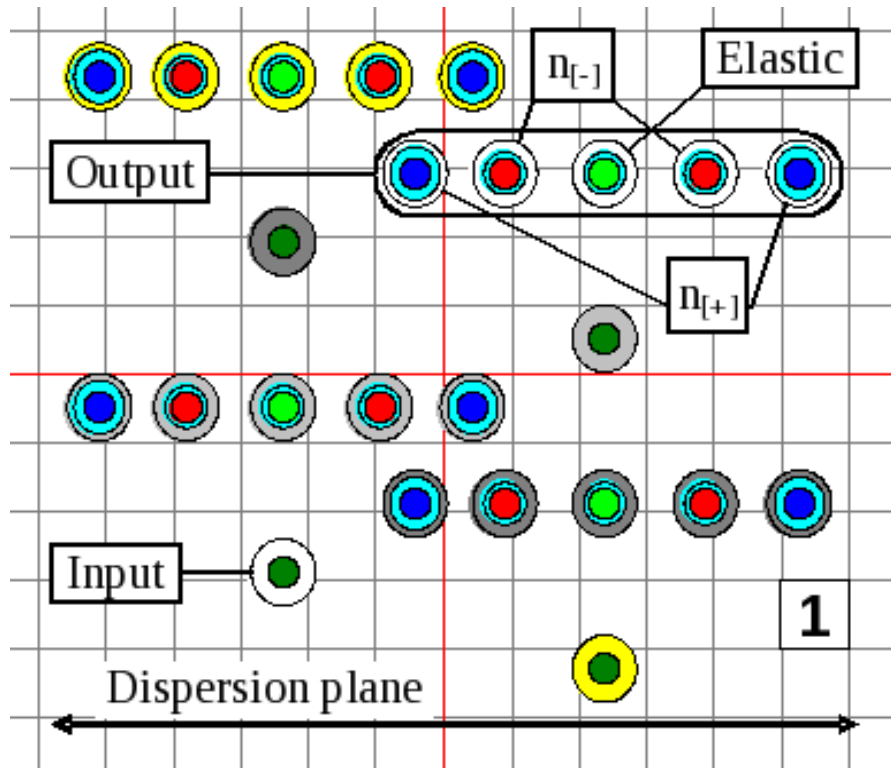
# Principle lidar layout



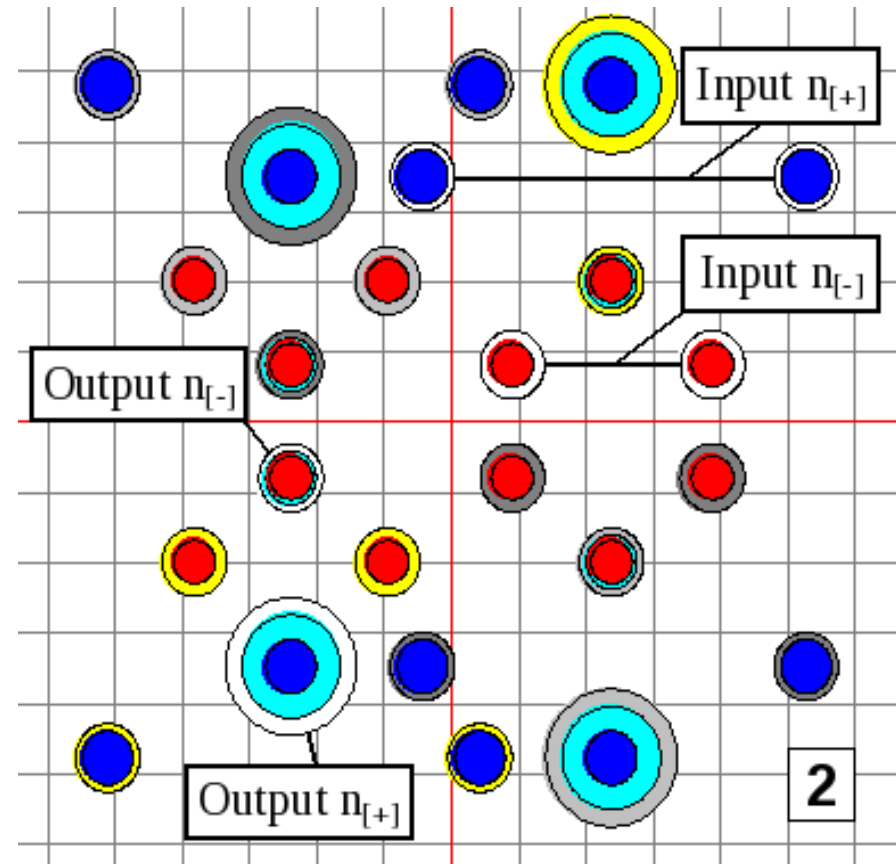
# Preliminary spectral separation



# “Four telescopes” configuration

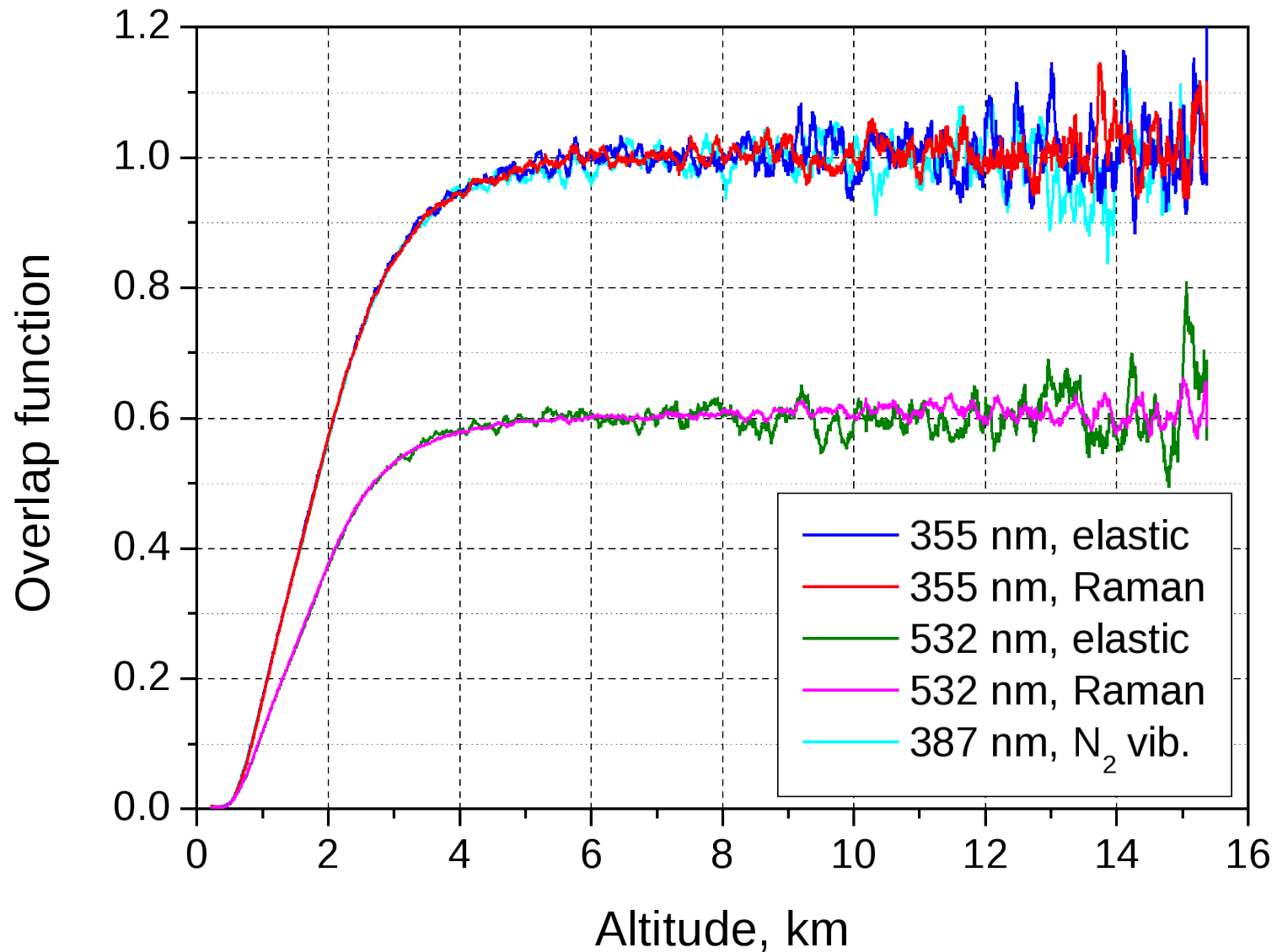


first unit

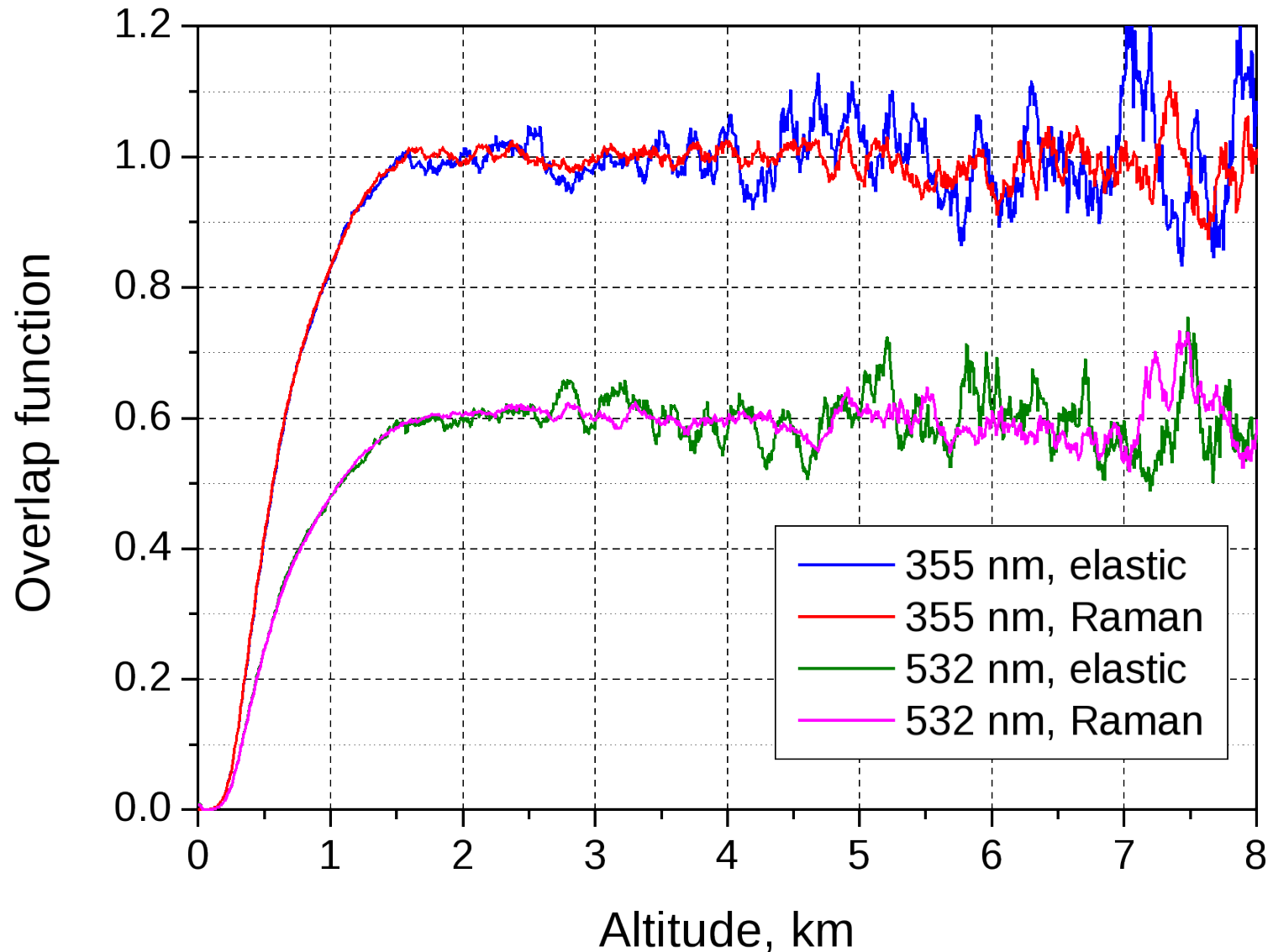


second unit

# Overlap function, far range telescope

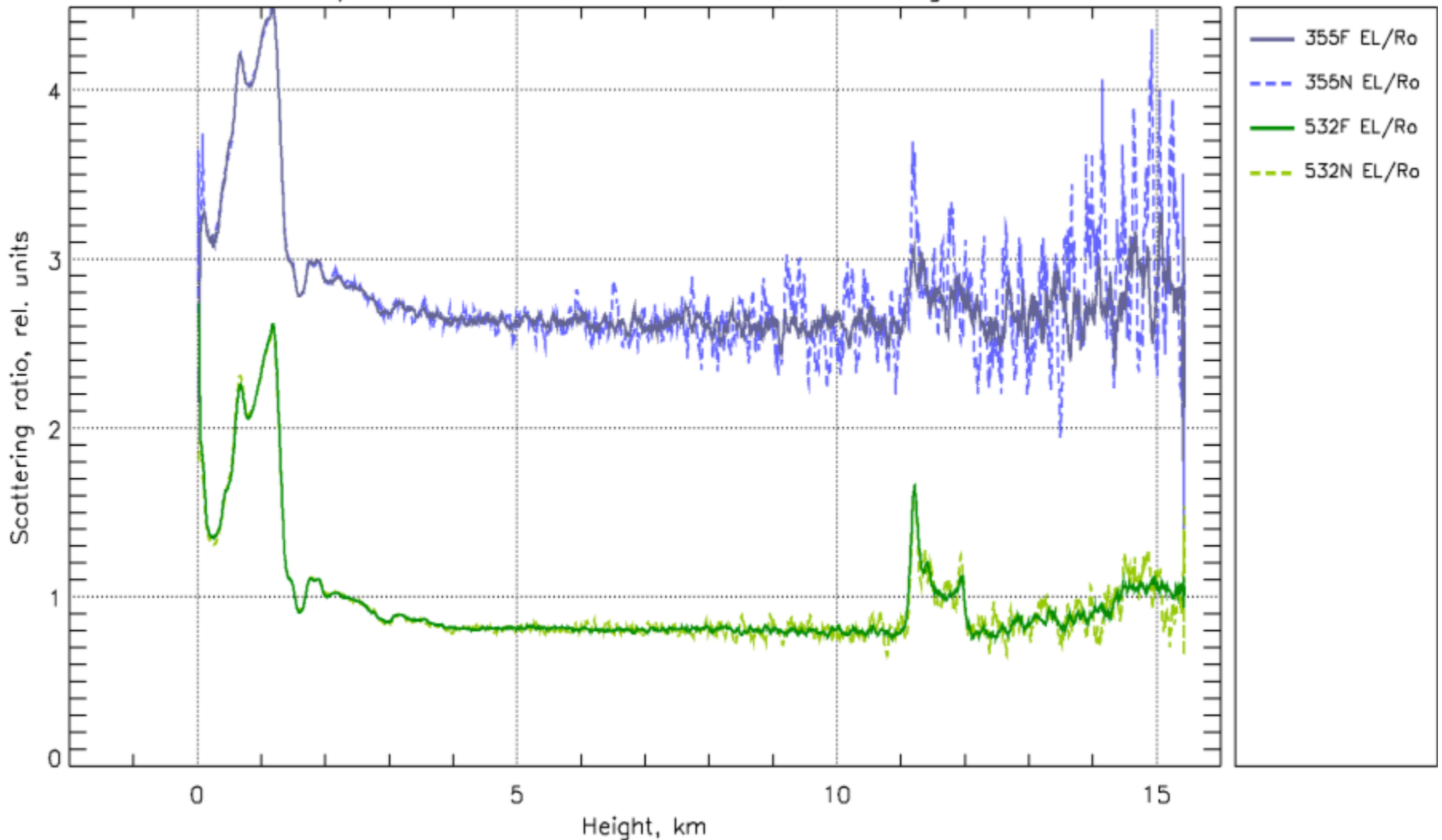


# Overlap function, near range telescope



# Particle backscatter 355 & 532, far- and near-range

hh01/r090919.2100, 21:00–23:00, scattering ratio

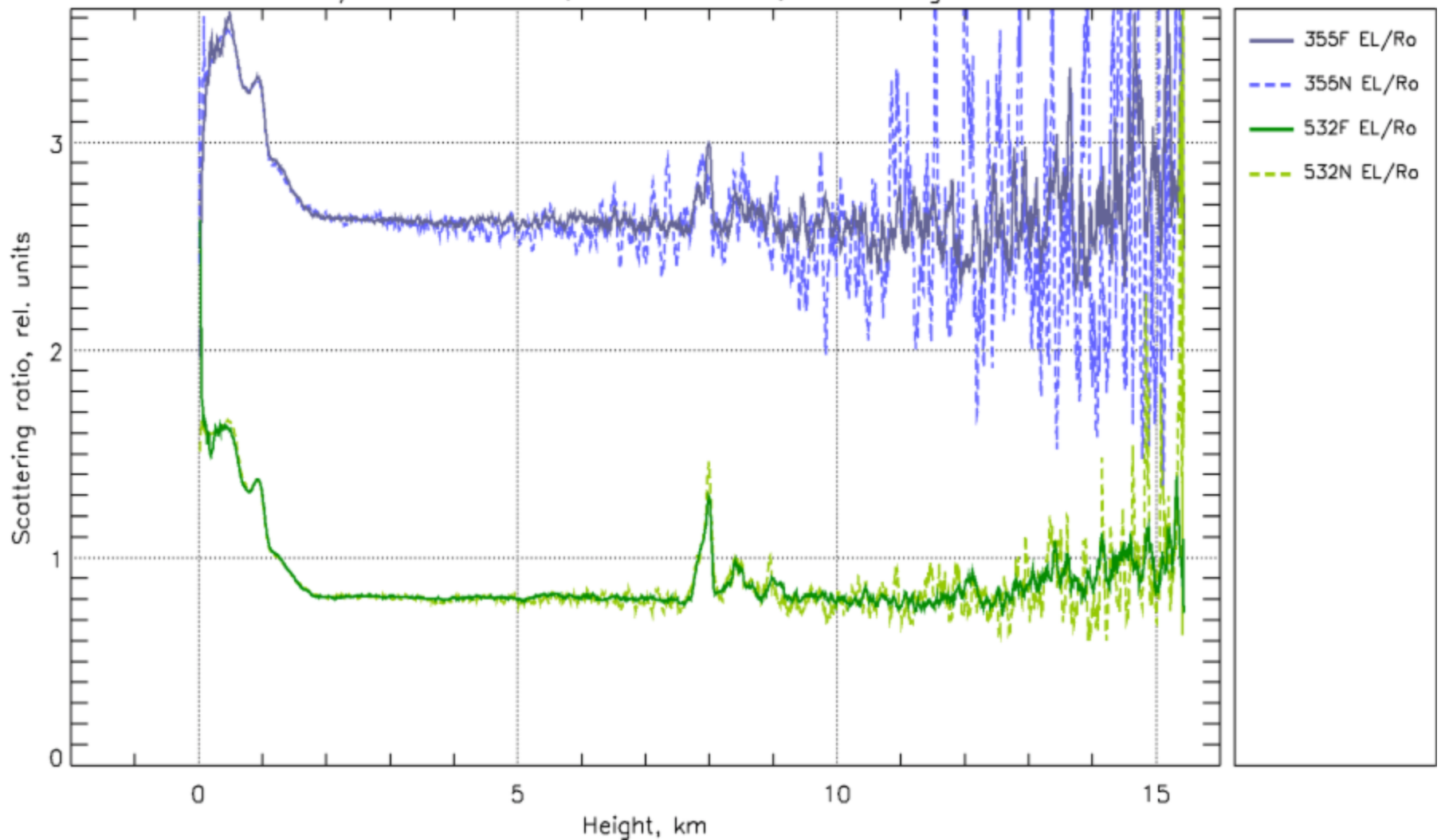


resolution: 30 minutes, 60÷180 meters; **midnight**



# Particle backscatter 355 & 532, far- and near-range

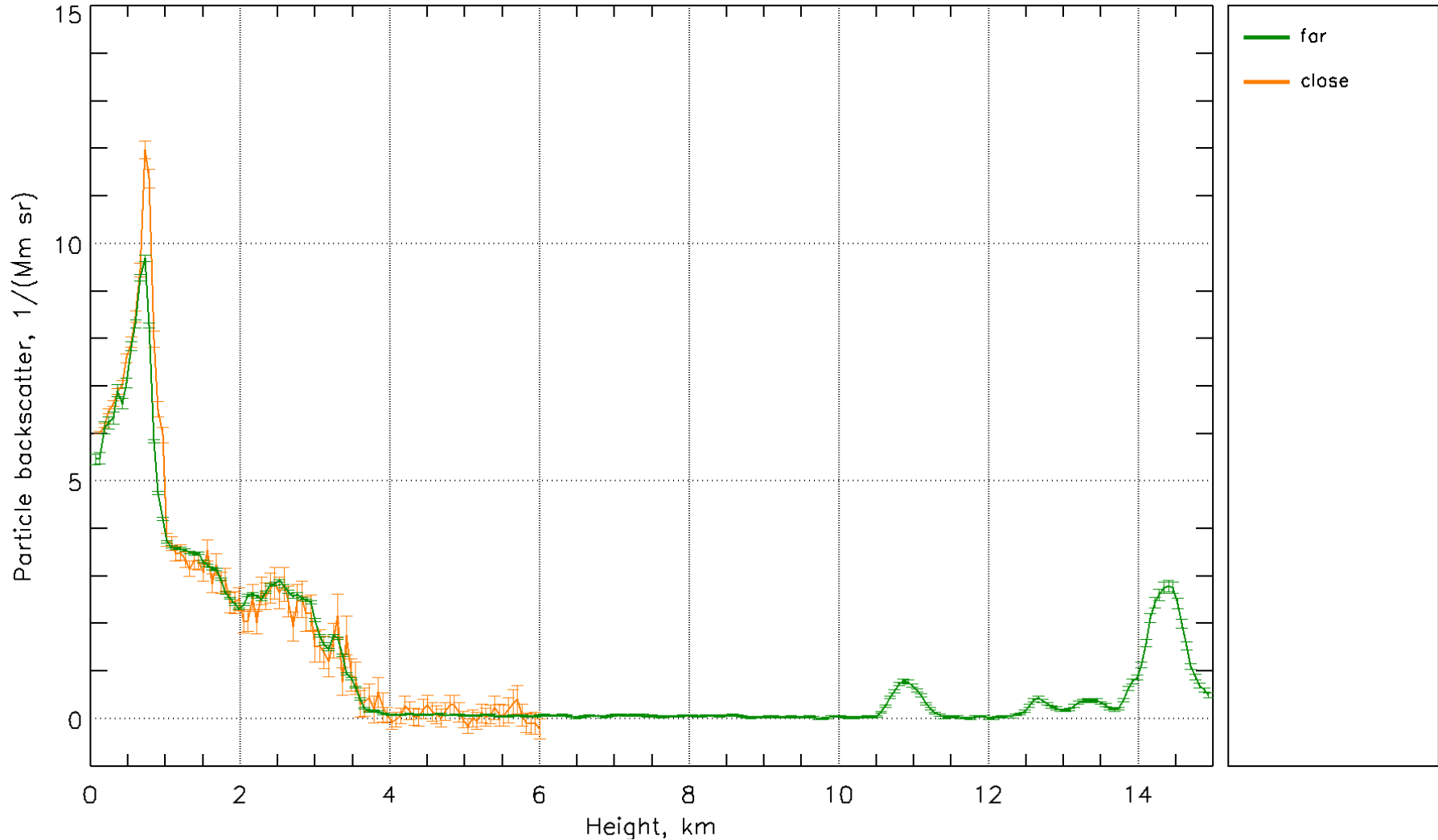
hh01/r090919.1200, 12:00–14:59, scattering ratio



resolution: 30 minutes, 60÷180 meters; **midday**

# Particle backscatter 532nm, far & close range

Particle backscatter, 532nm, 2010.07.15, 02:00–02:30 UTC (time zone: -4)

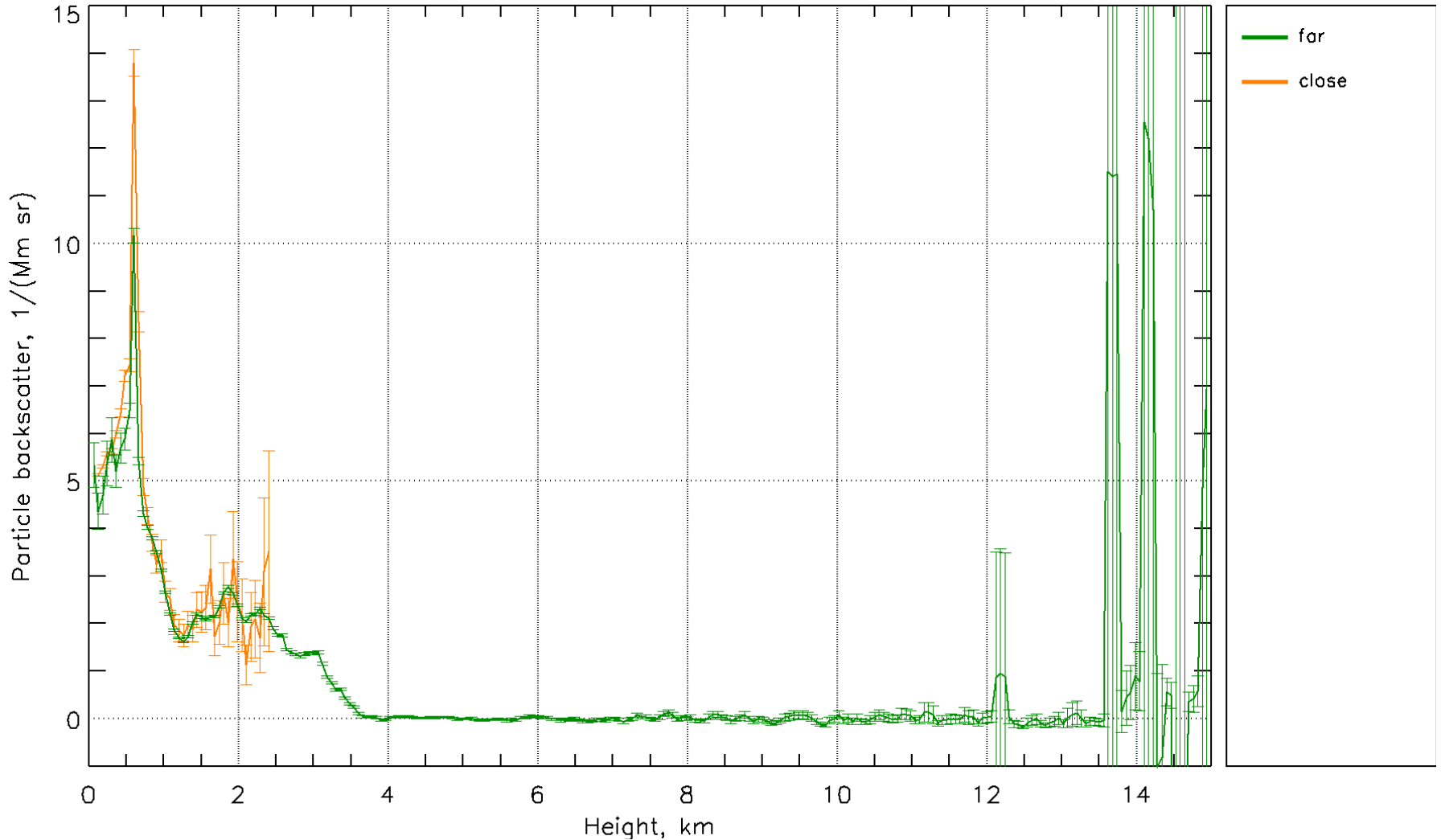


resolution: 30 minutes, 60÷180 meters; 22:00 Barbados time



# Particle backscatter 532nm, far & close range

Particle backscatter, 532nm, 2010.07.15, 14:00–14:30 UTC (time zone: -4)

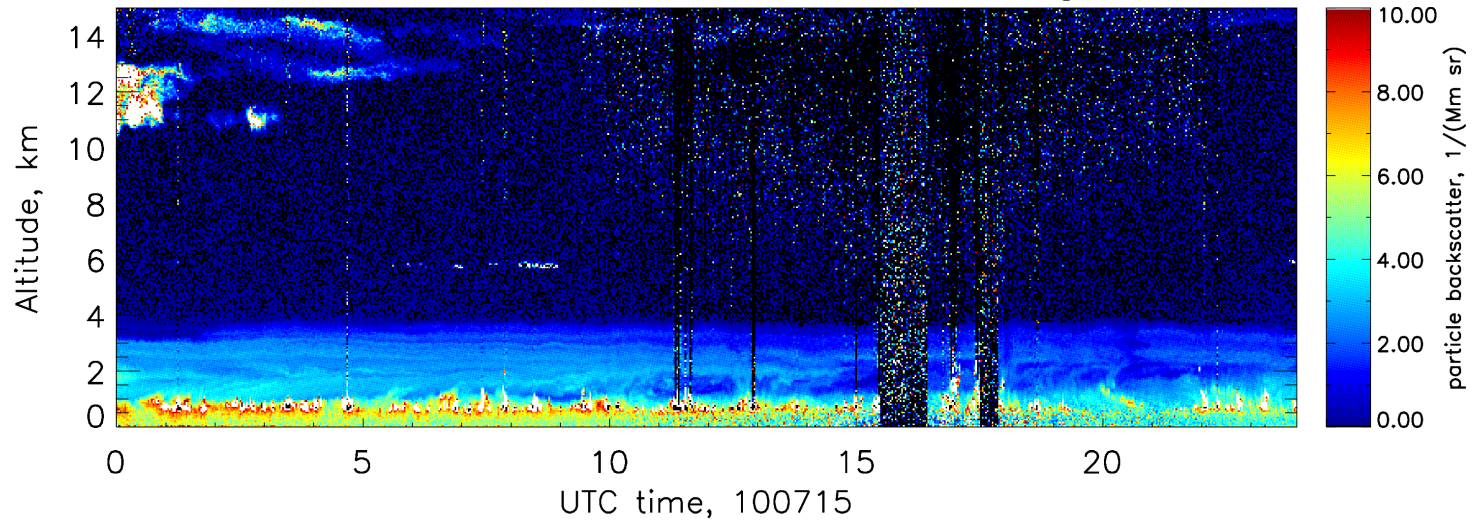


resolution: 30 minutes, 60÷180 meters; 10:00 Barbados time

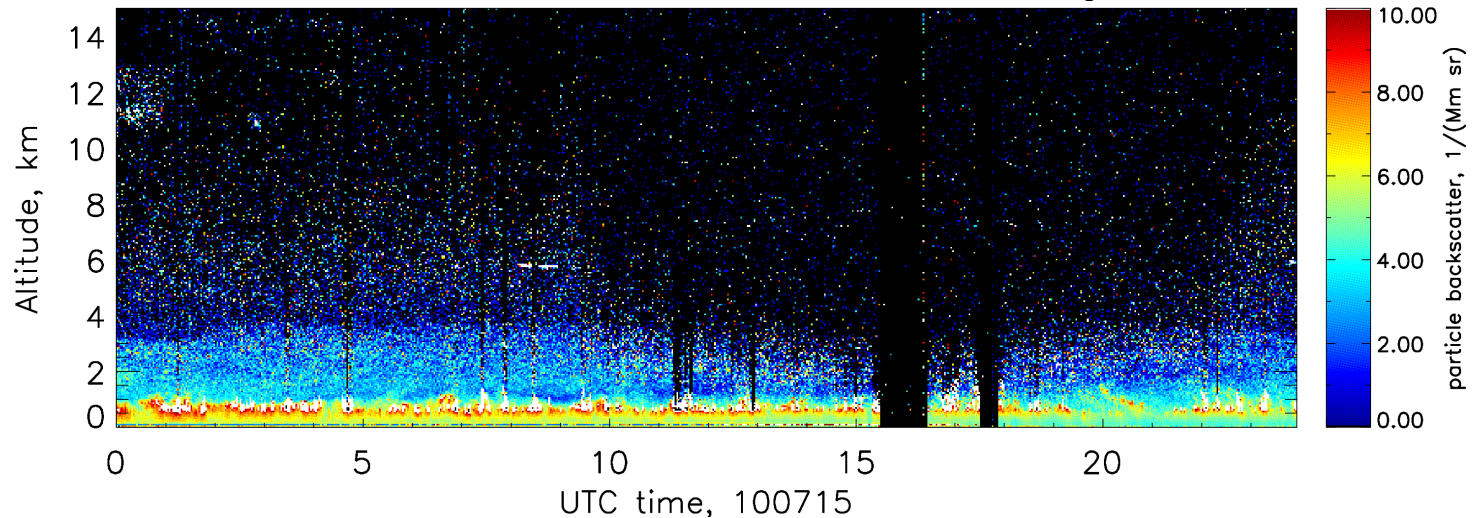


# Particle backscatter 532nm, far & close range

particle backscatter, 532nm, far range



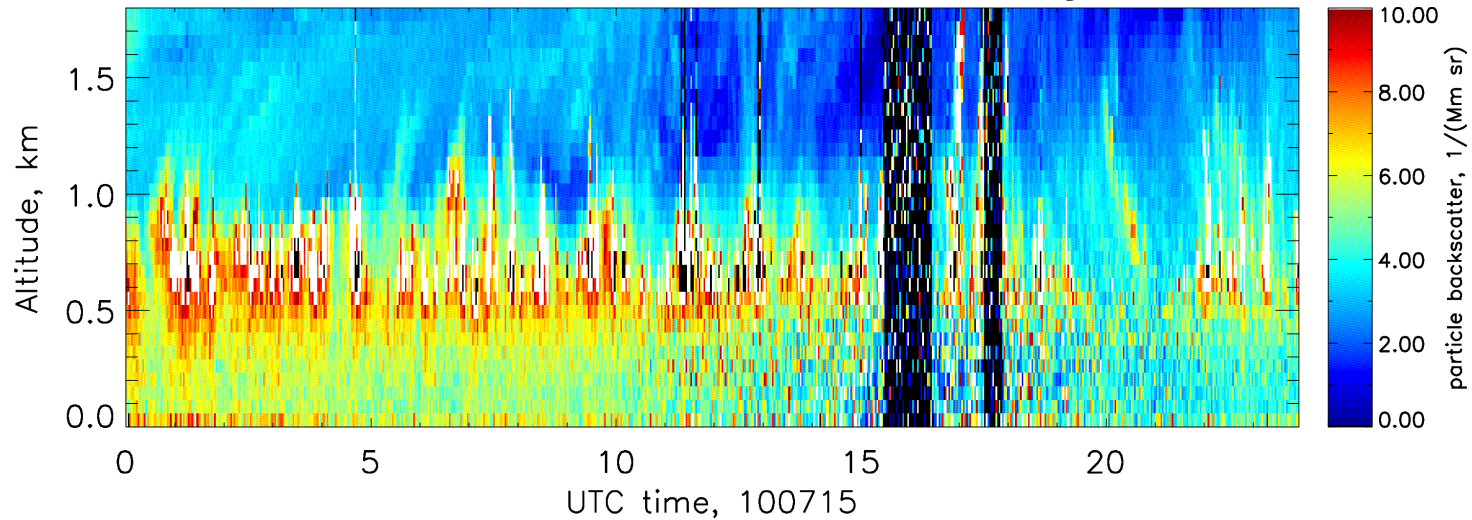
particle backscatter, 532nm, close range



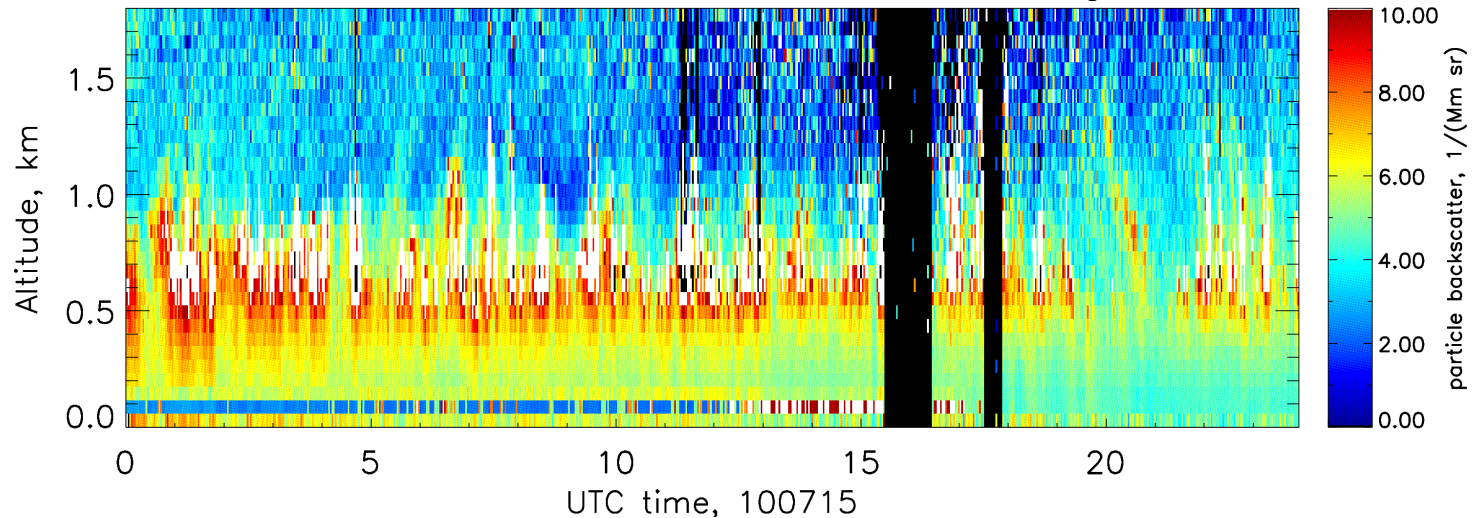
resolution: 2 minutes, 60 meters

# Particle backscatter 532nm, far & close range

particle backscatter, 532nm, far range

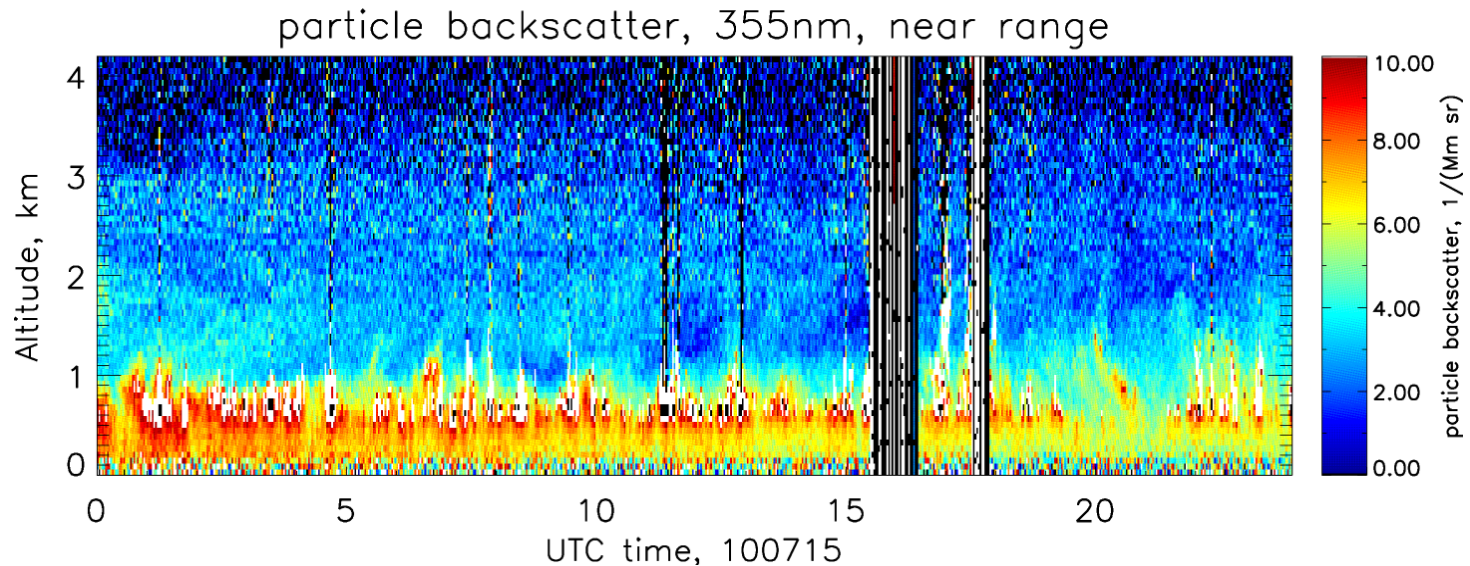
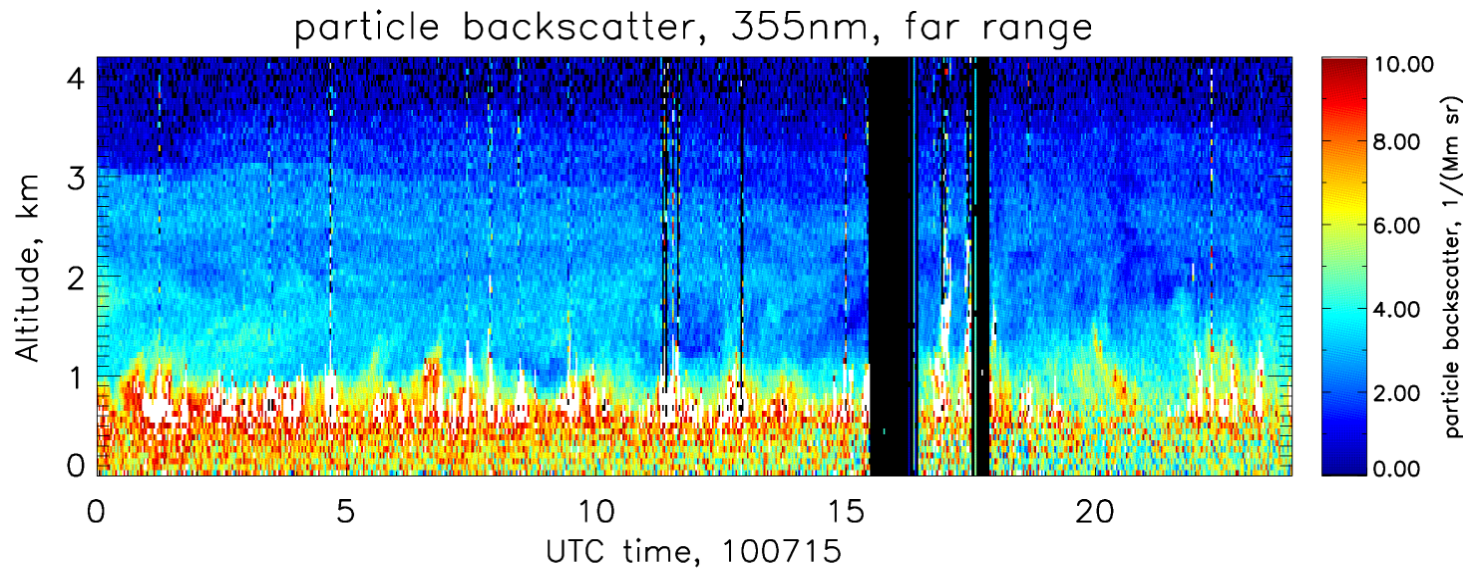


particle backscatter, 532nm, close range



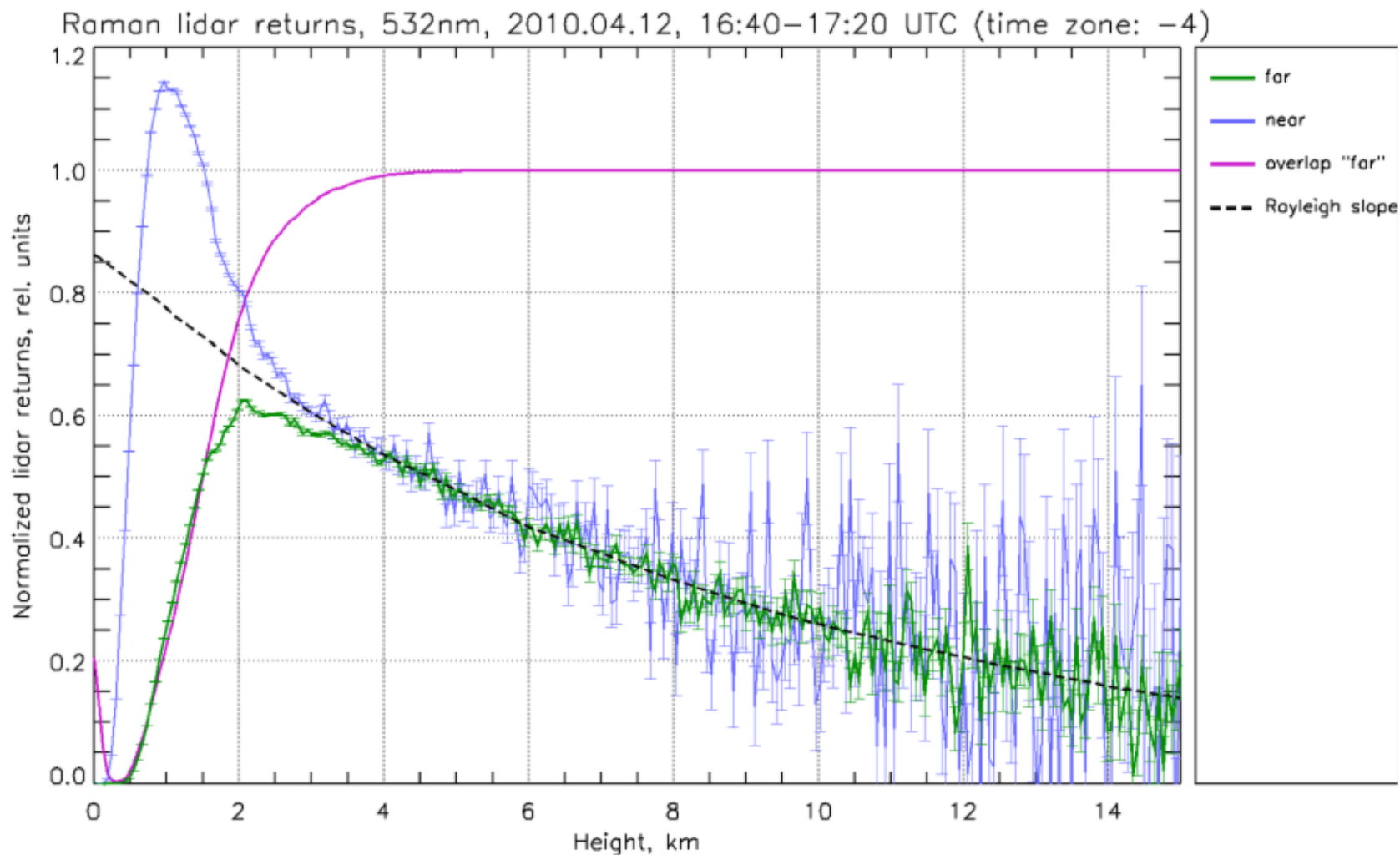
resolution: 2 minutes, 60 meters

# Particle backscatter 355nm, far & near range



resolution: 2 minutes, 60 meters

# Raman lidar returns, 532nm, near & far range

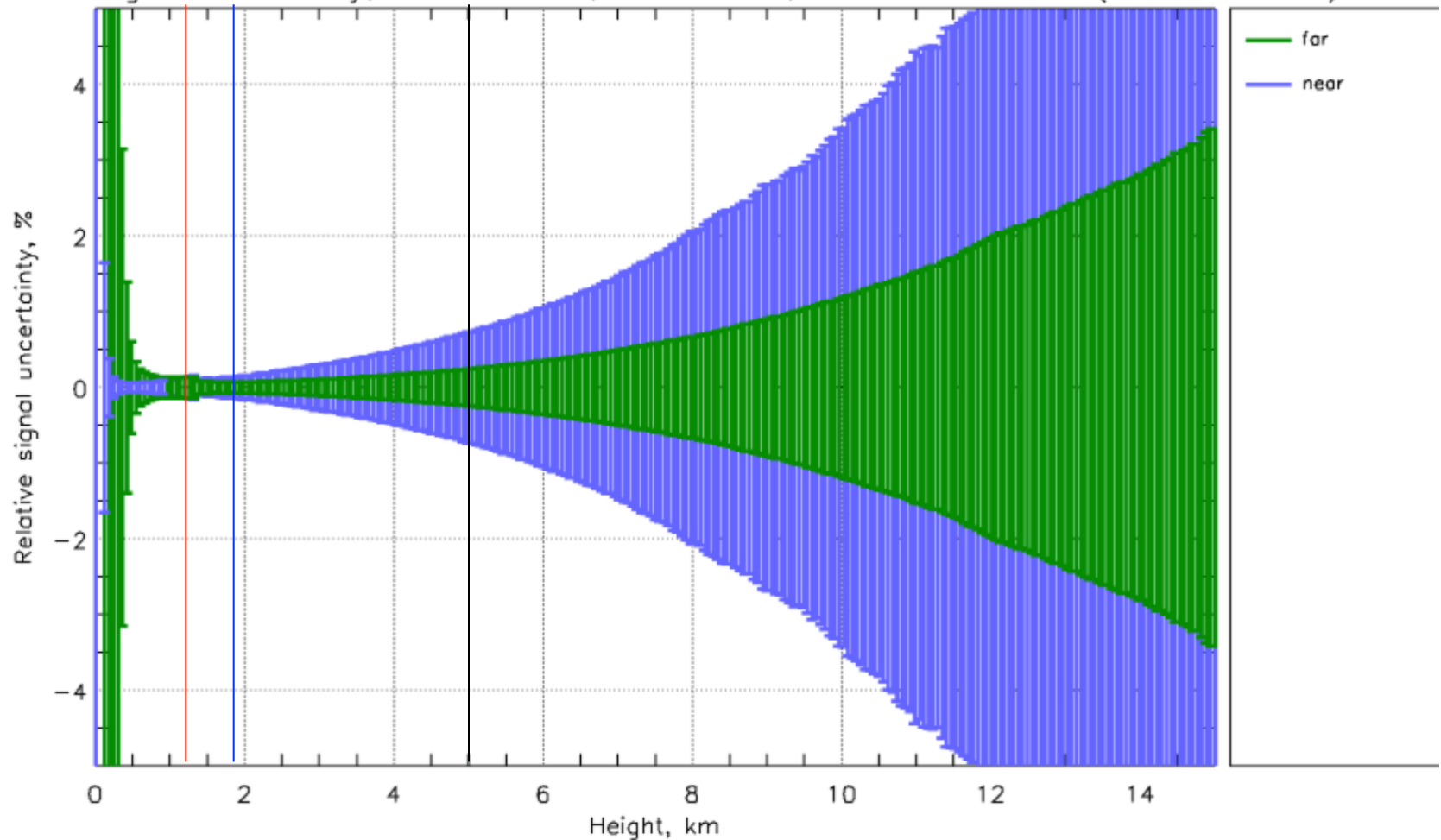


resolution: signals: 40 minutes, 60m  
overlap: 3 hours, 60m÷5km



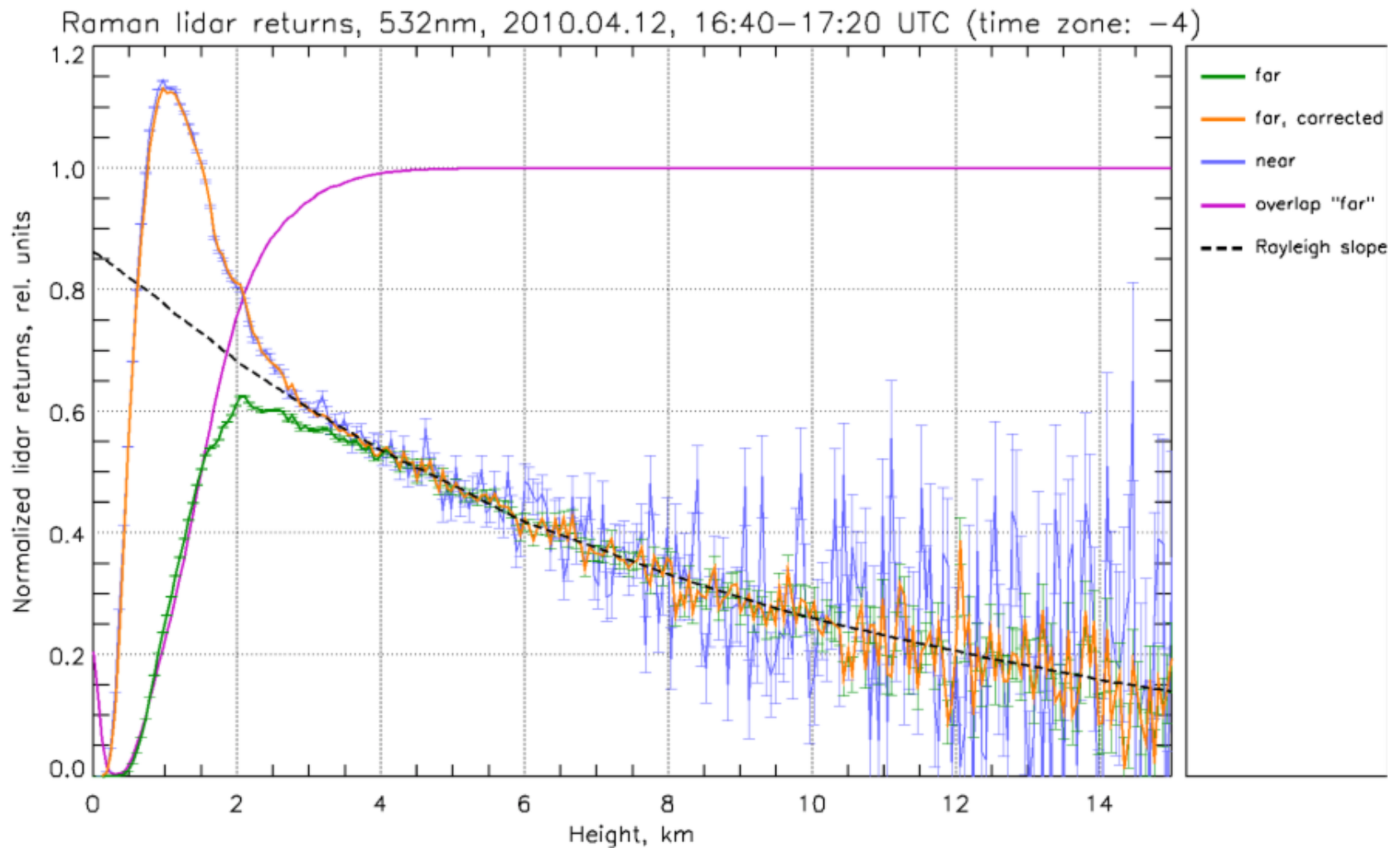
# Statistical uncertainty of lidar returns, near & far range

Relative signal uncertainty, PRRS 532nm, 2010.04.12, 16:40–17:20 UTC (time zone: -4)





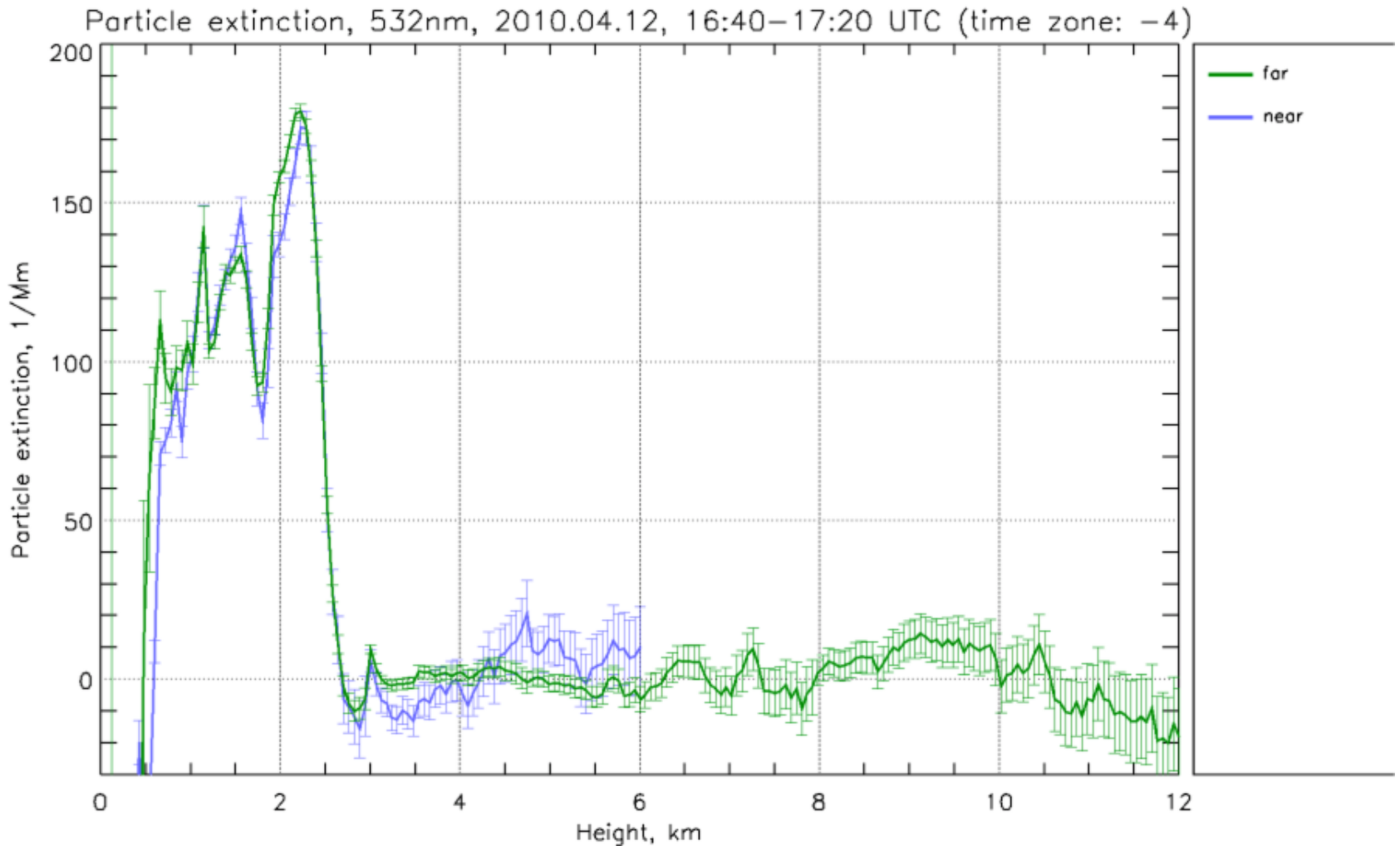
# Raman lidar returns, 532nm, near & far range



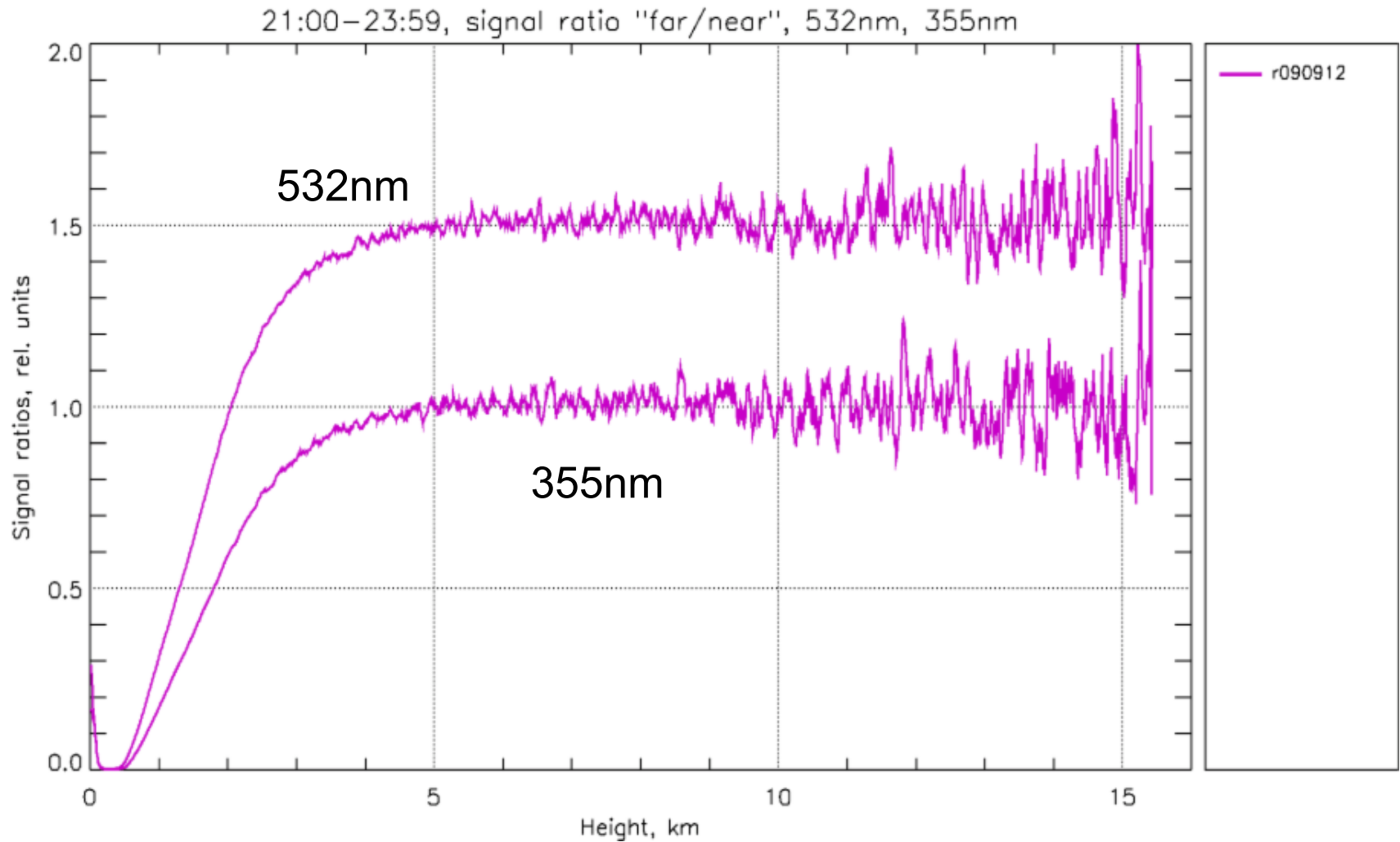
resolution: signals: 40 minutes, 60m  
overlap: 3 hours, 60m±5km



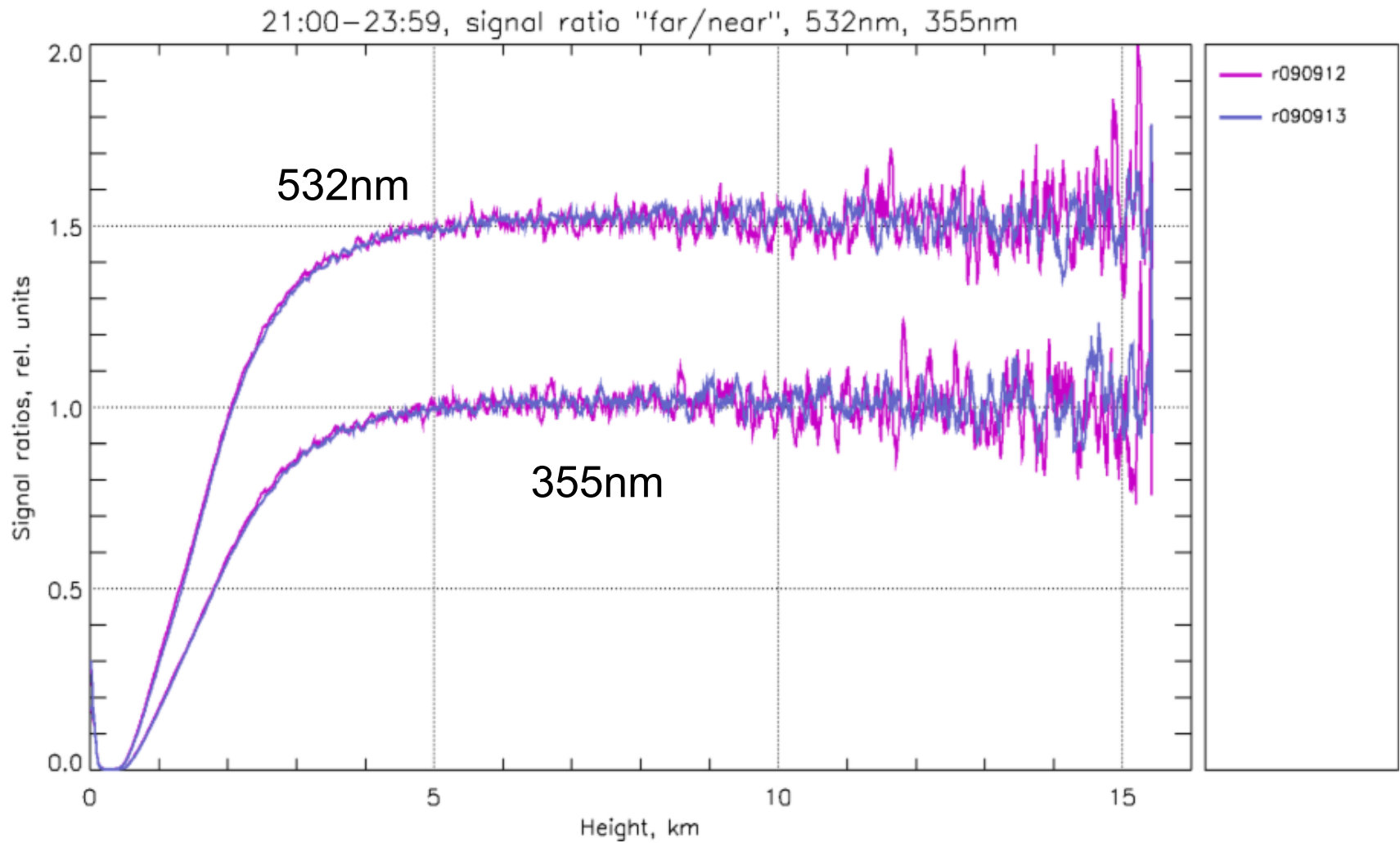
# Particle extinction, 532nm, near & far range



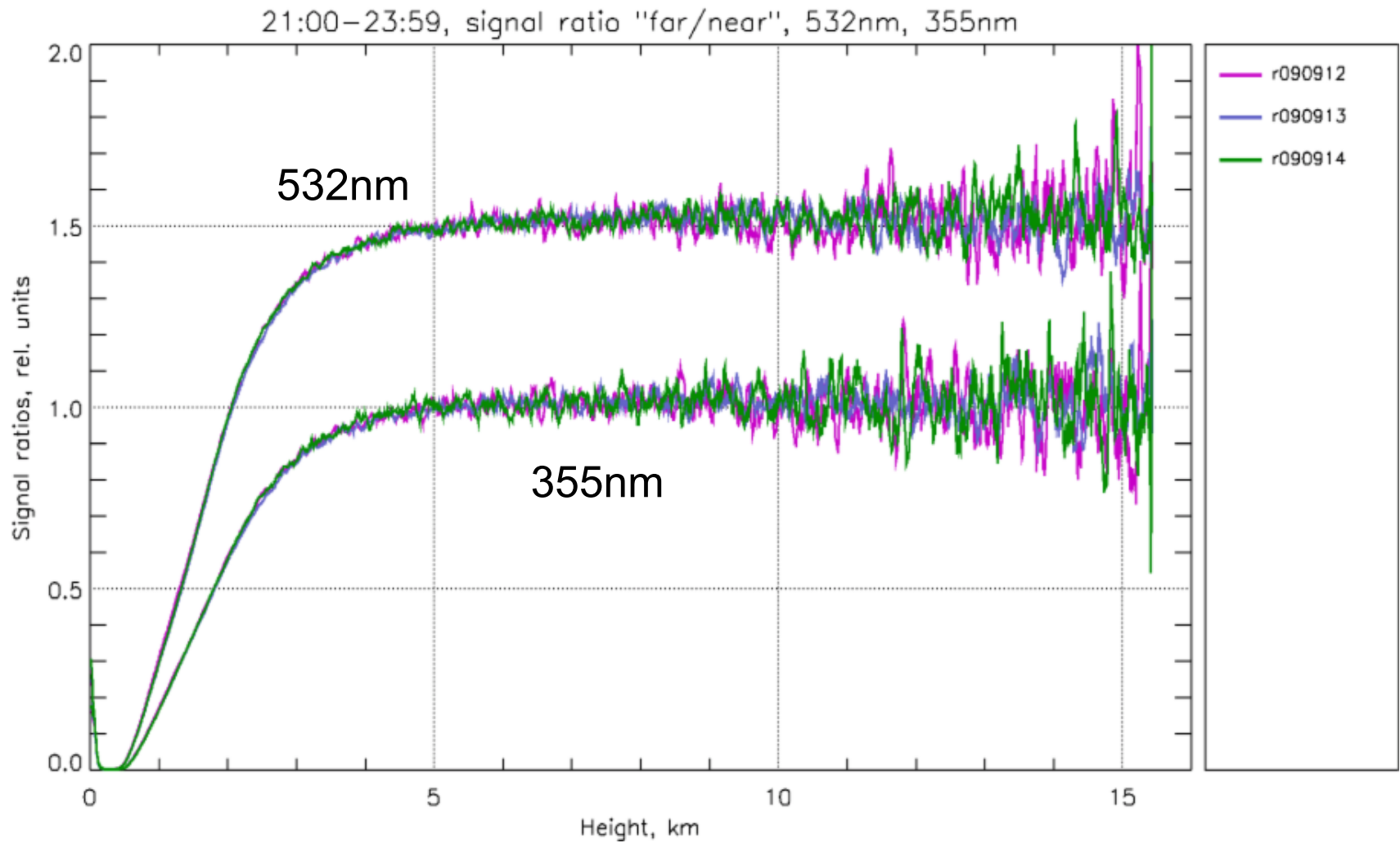
# Overlap long term stability



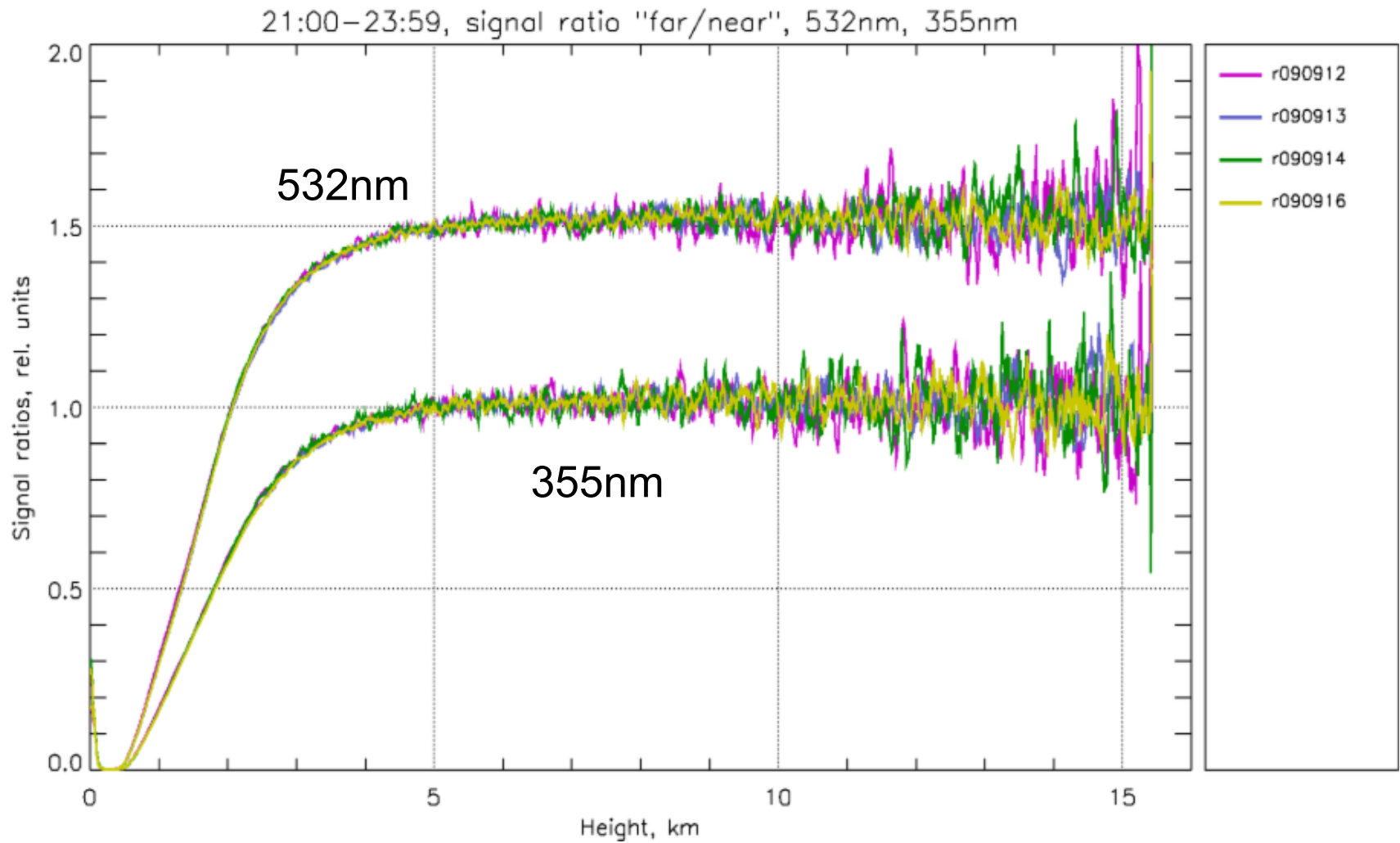
# Overlap long term stability



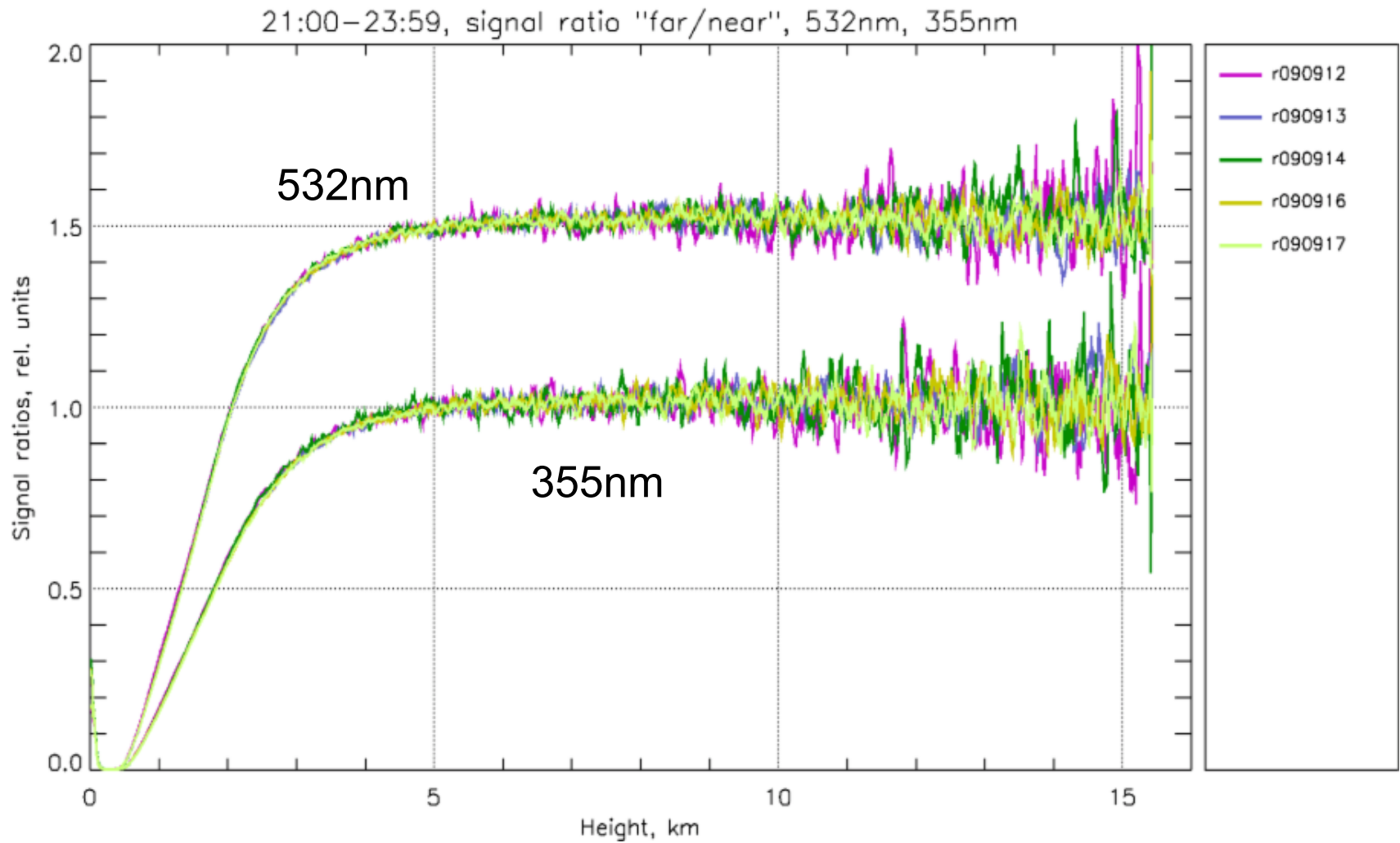
# Overlap long term stability



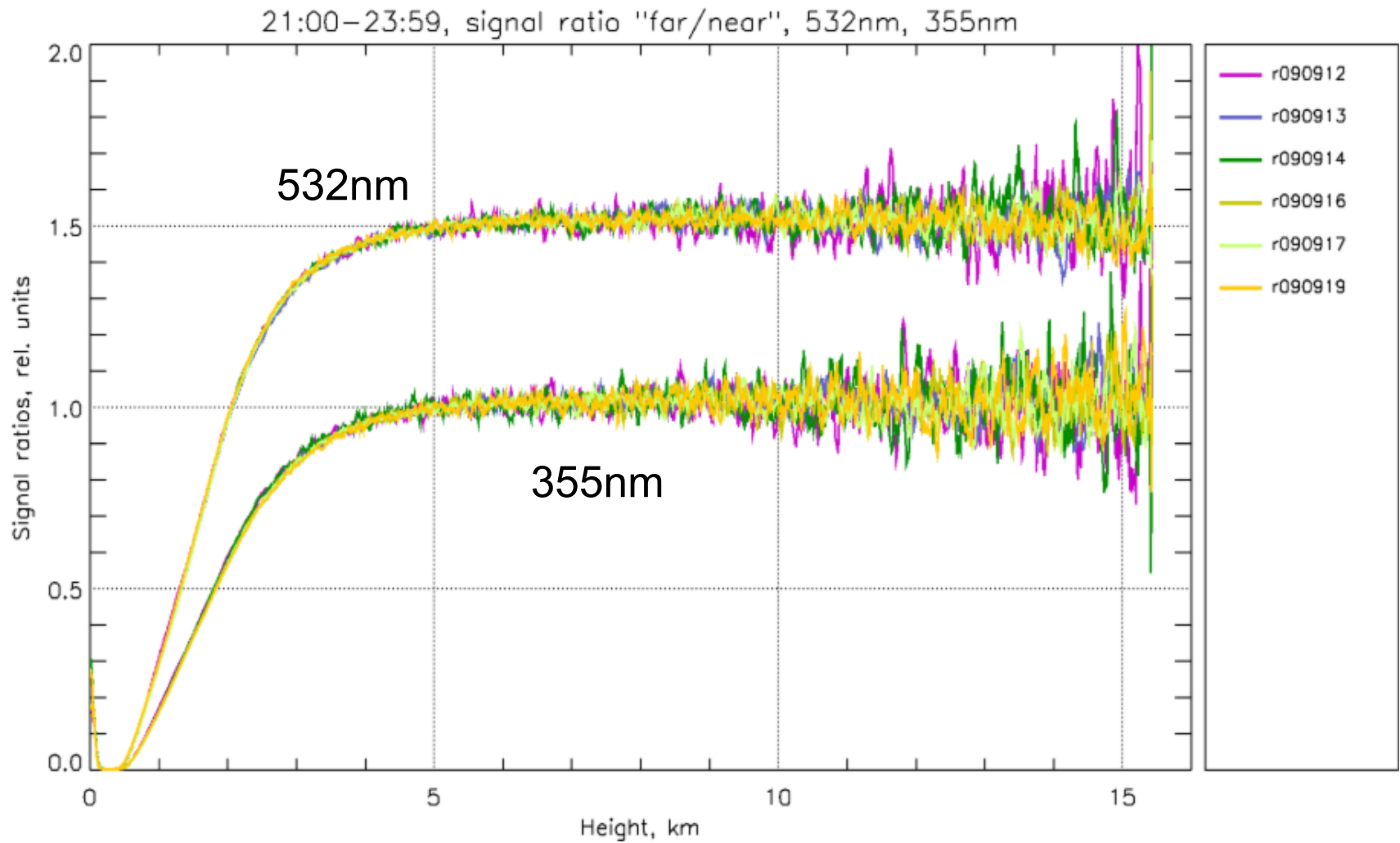
# Overlap long term stability



# Overlap long term stability

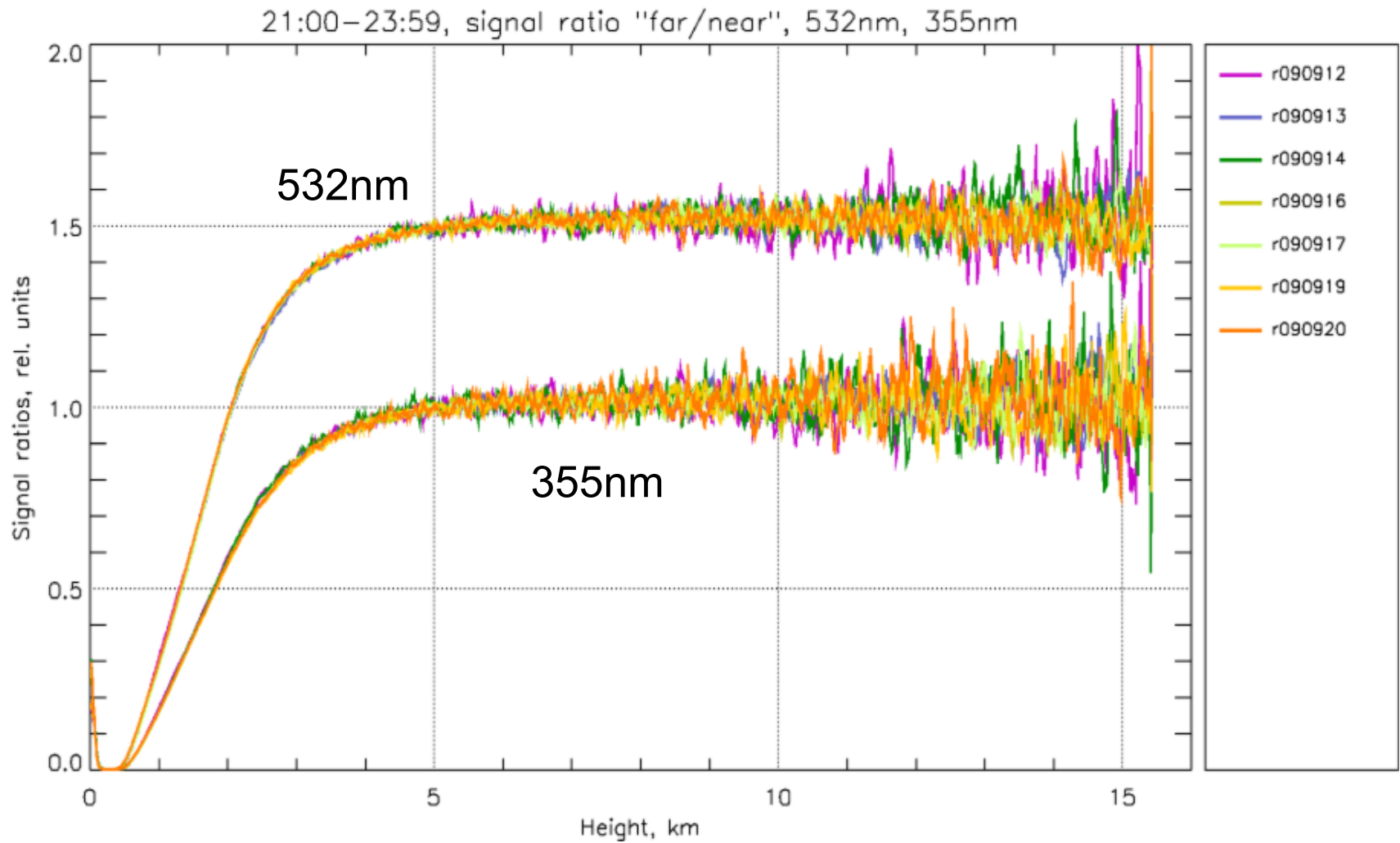


# Overlap long term stability

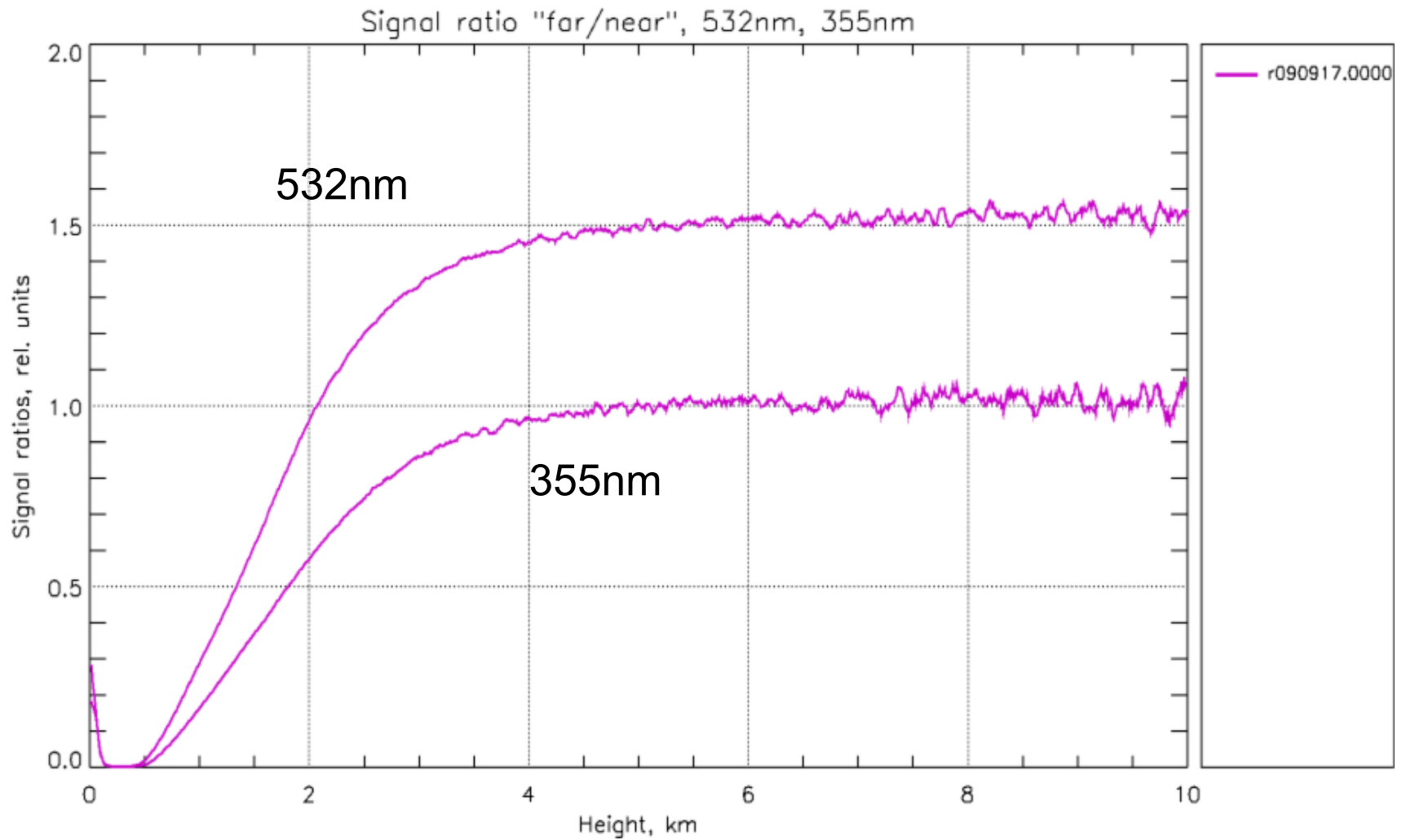




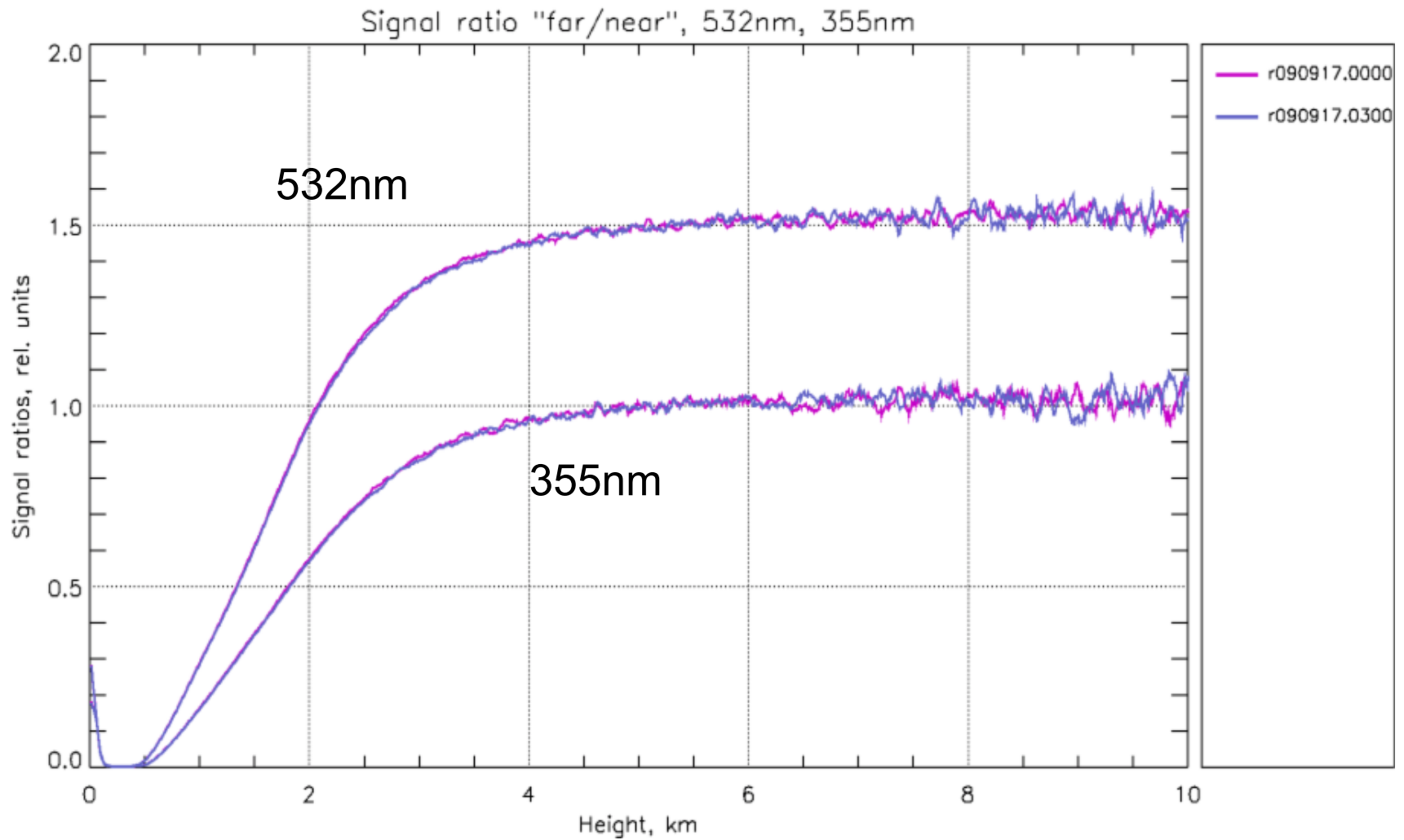
# Overlap long term stability



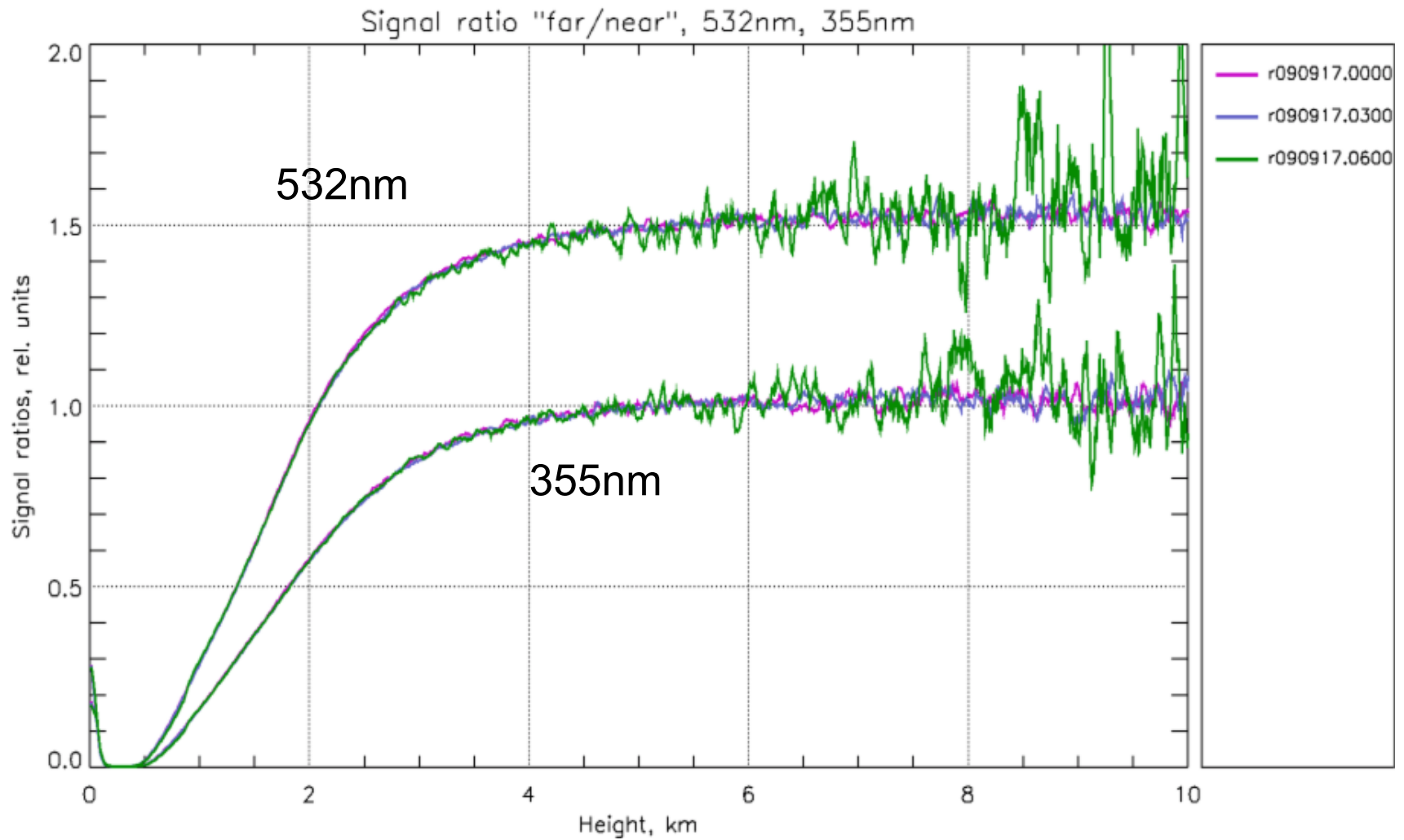
# Overlap, 24h stability



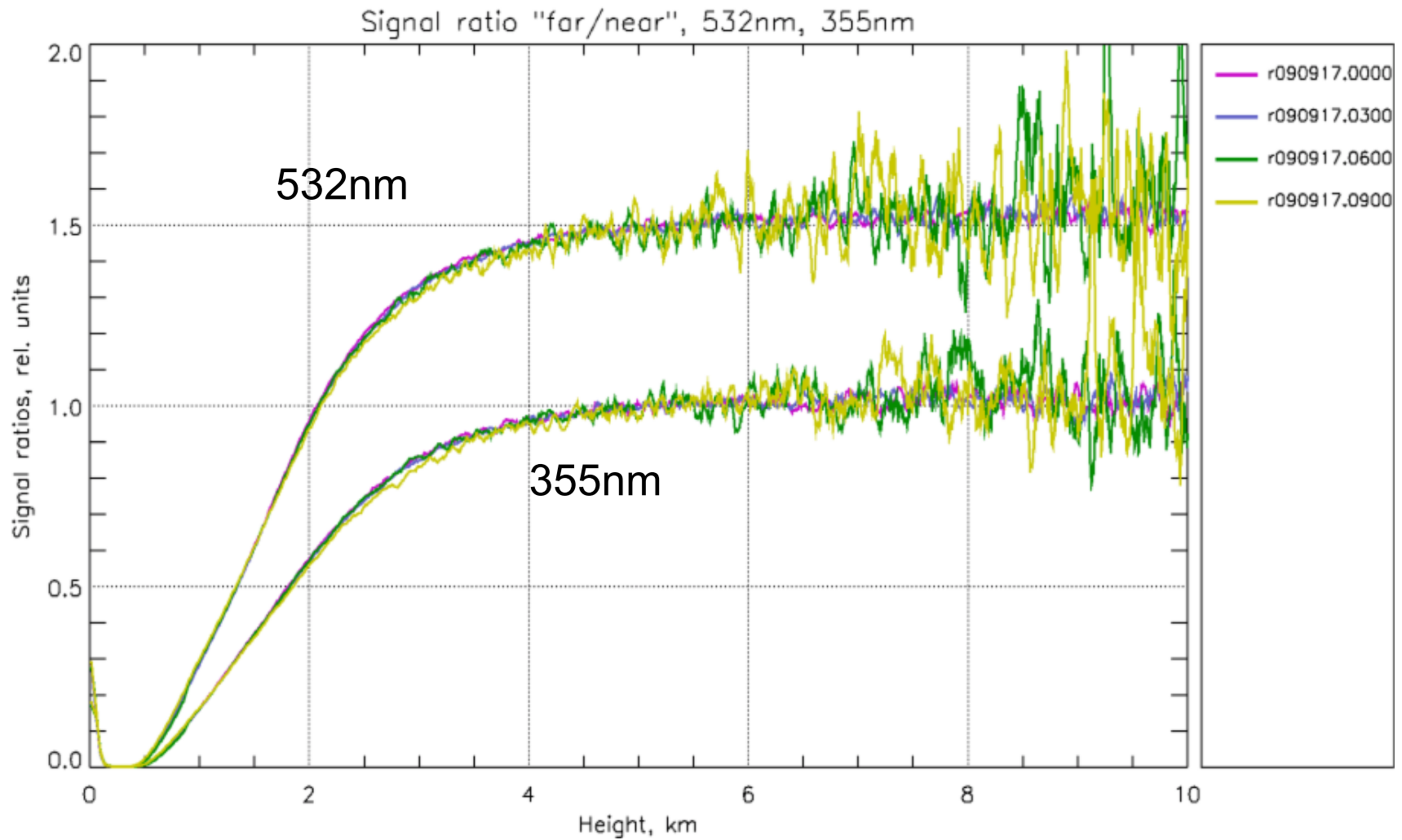
# Overlap, 24h stability



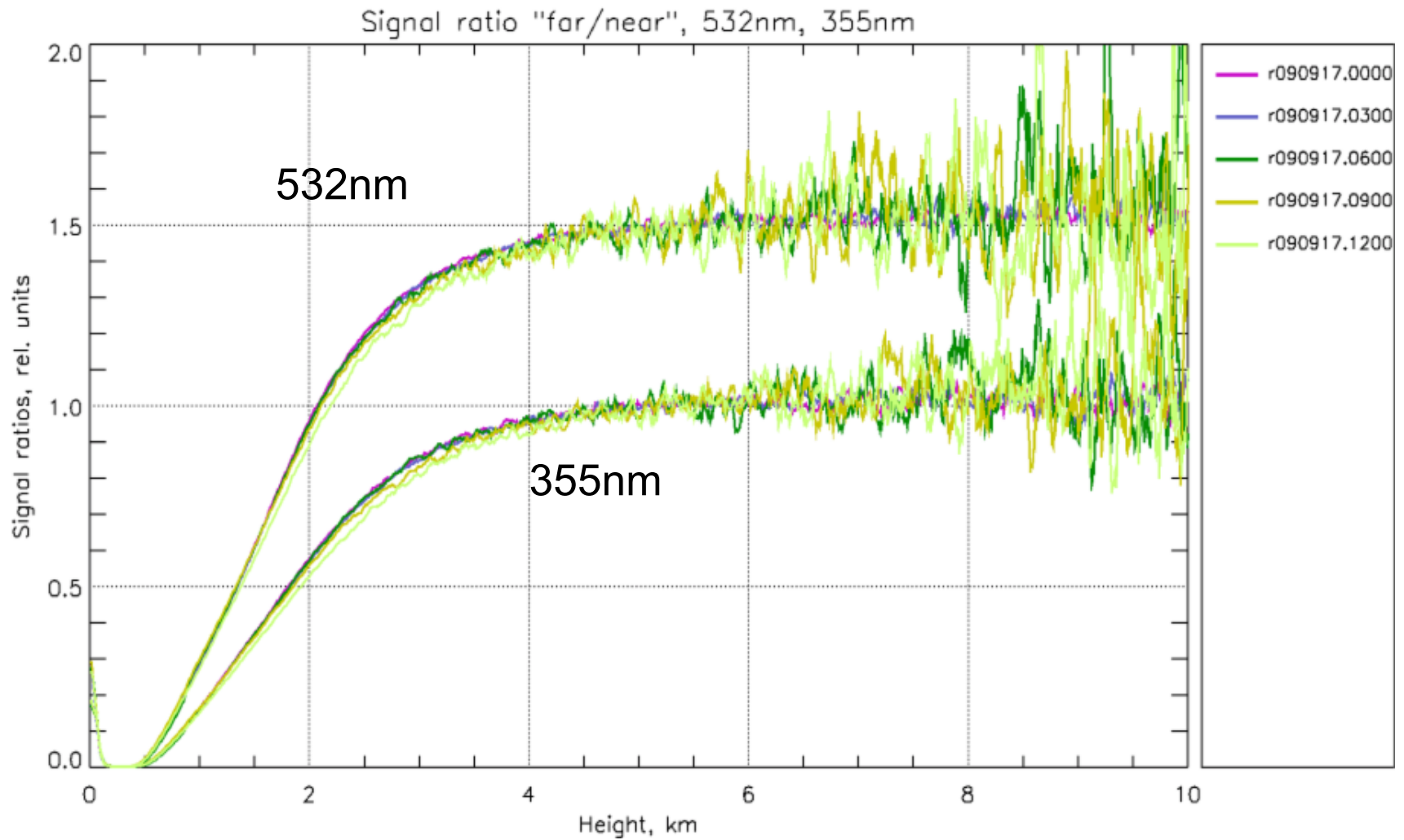
# Overlap, 24h stability



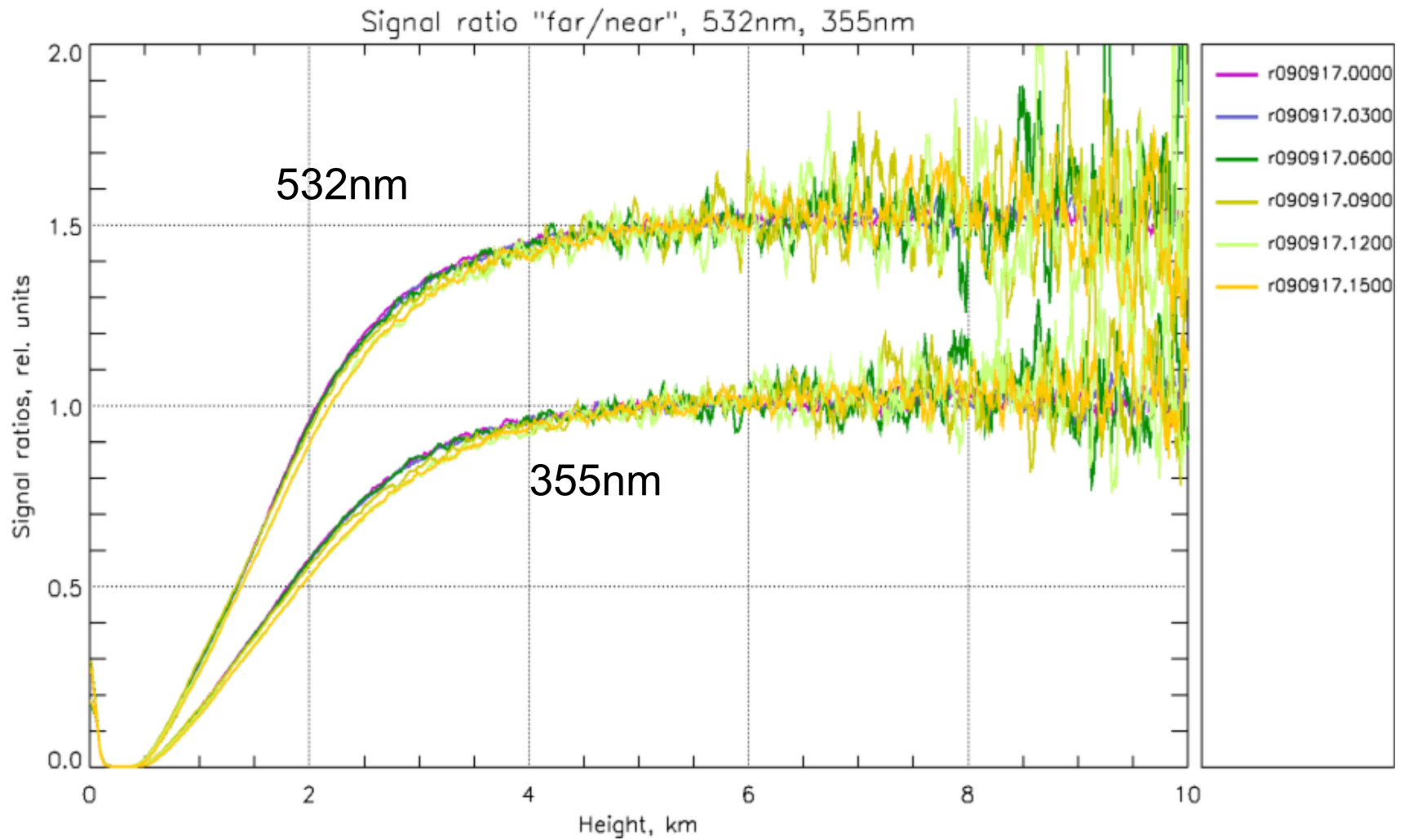
# Overlap, 24h stability



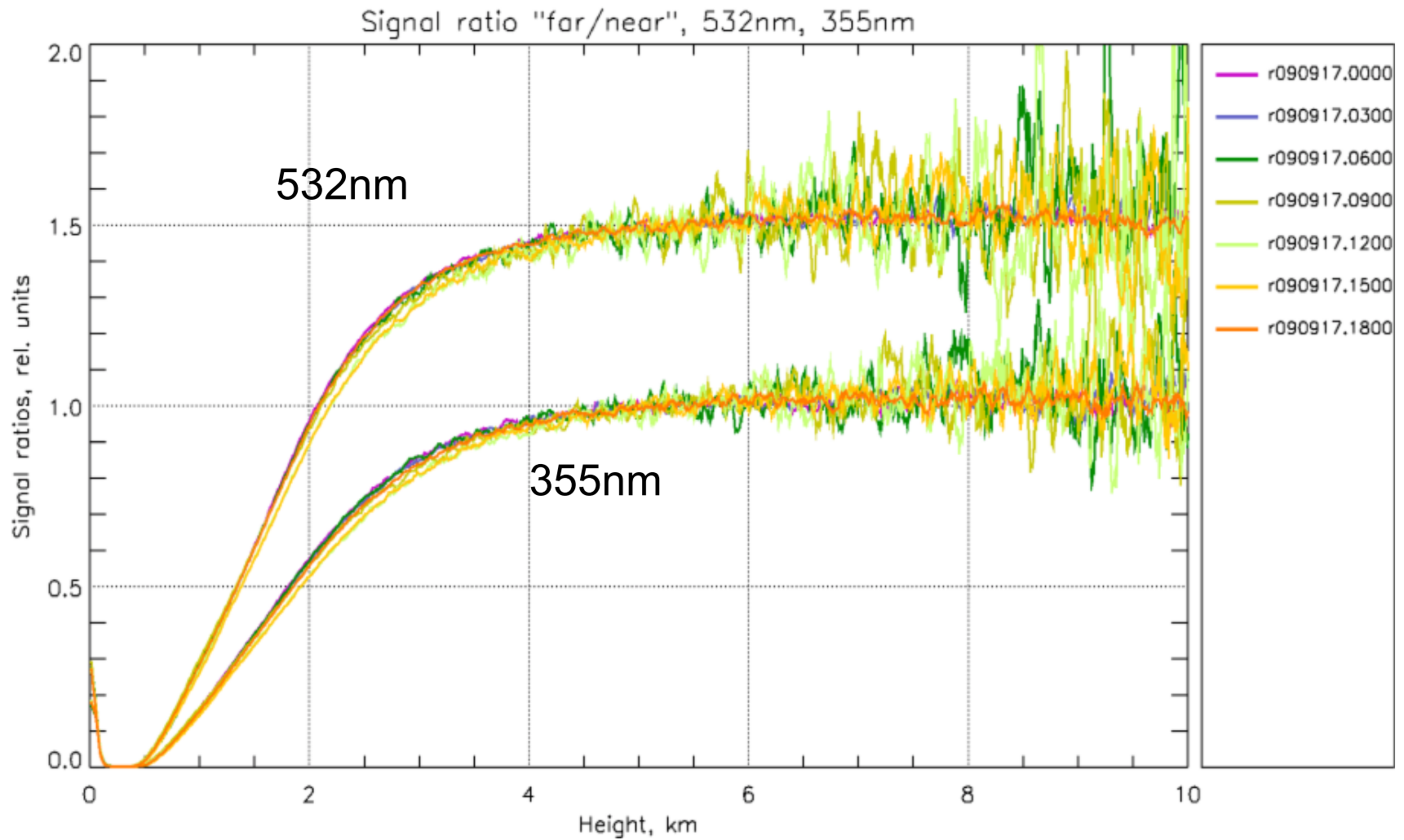
# Overlap, 24h stability



# Overlap, 24h stability

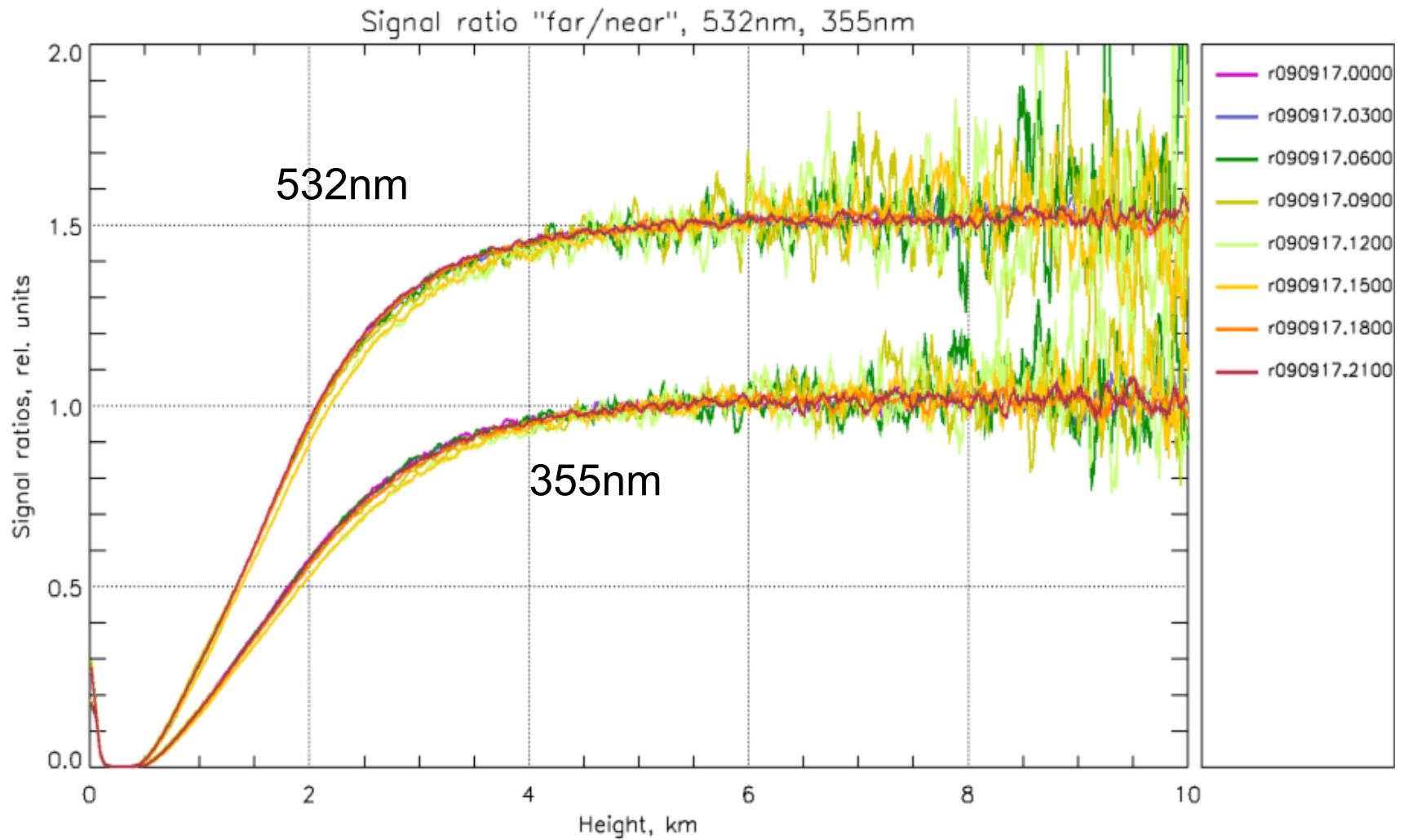


# Overlap, 24h stability

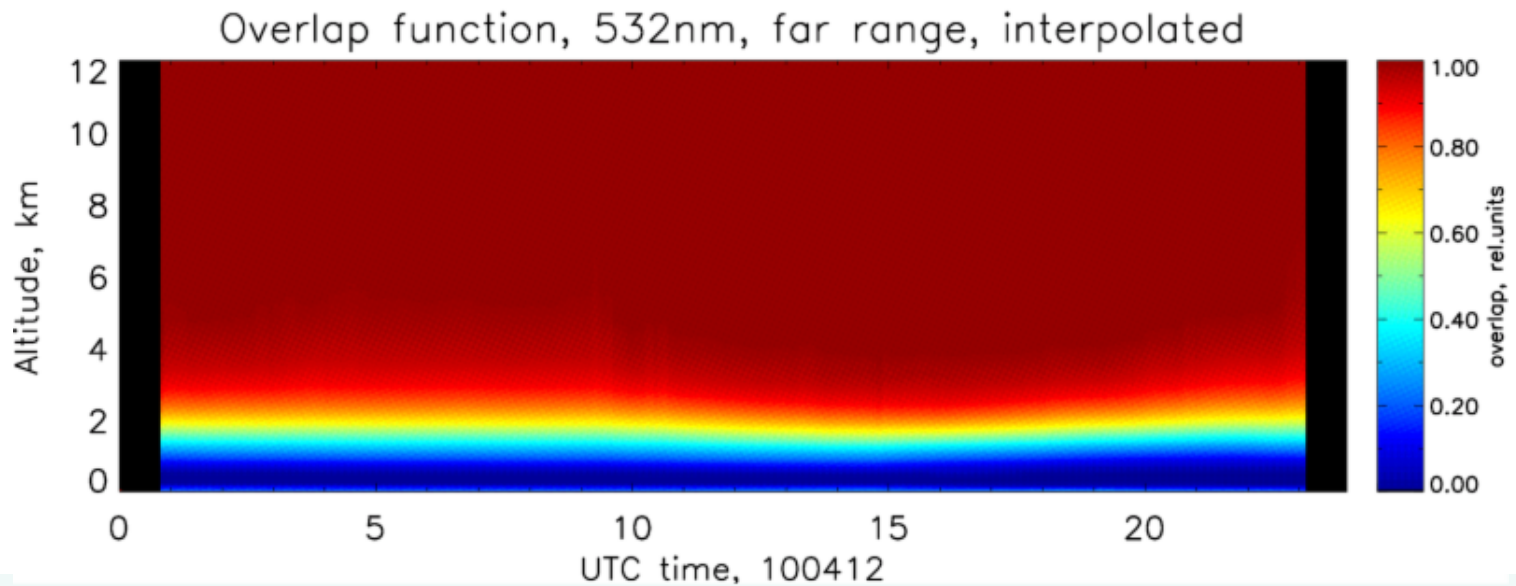
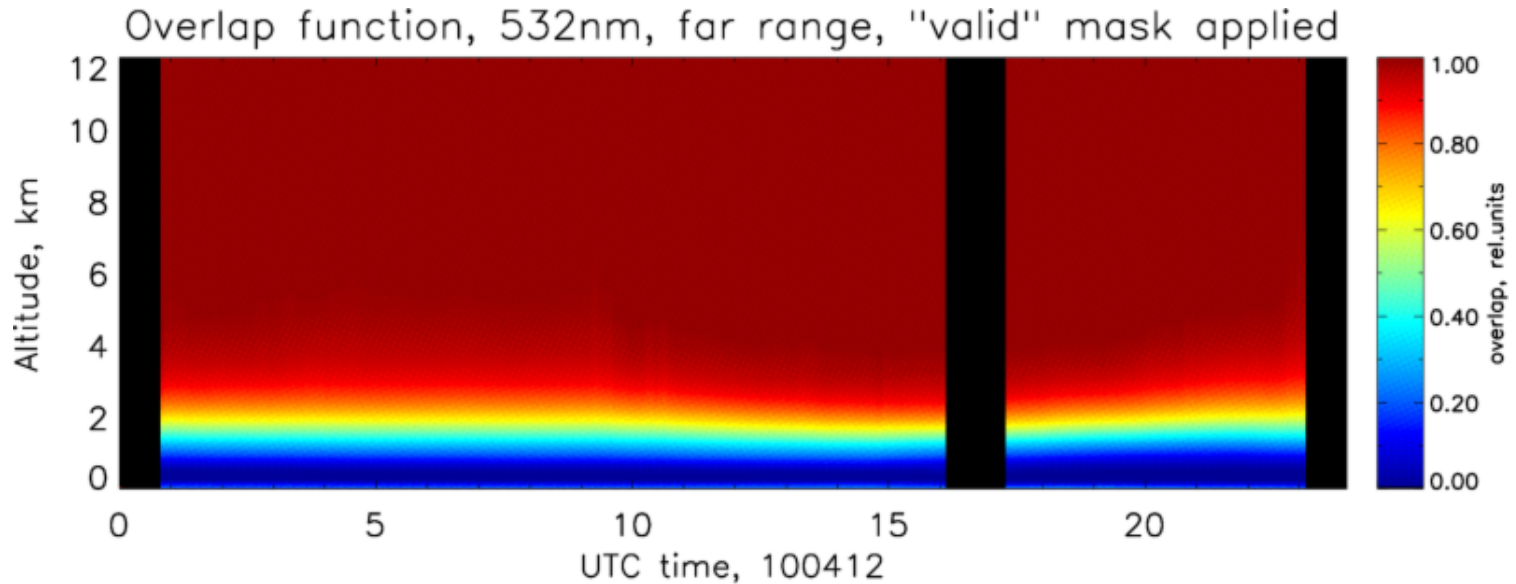




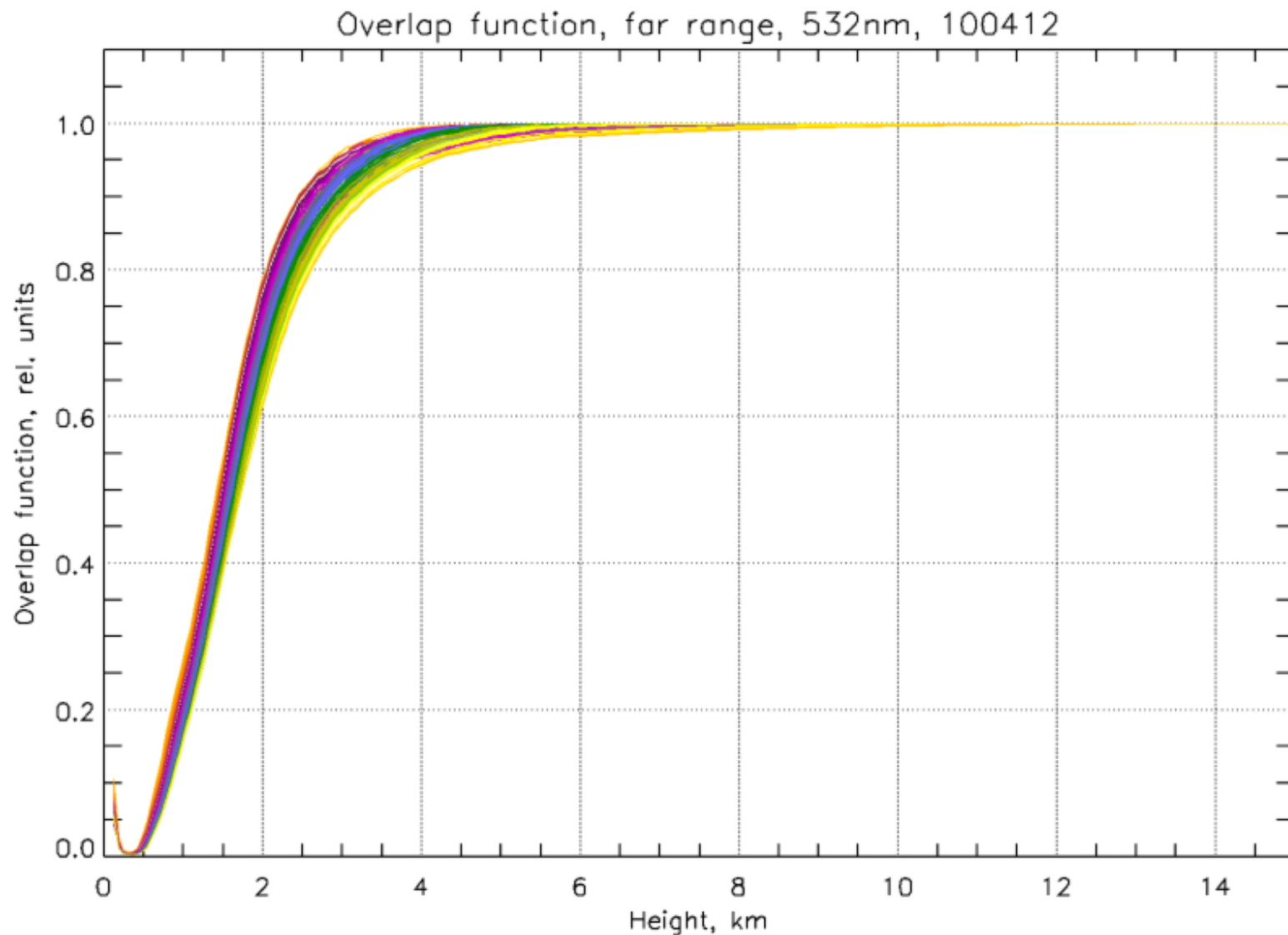
# Overlap, 24h stability



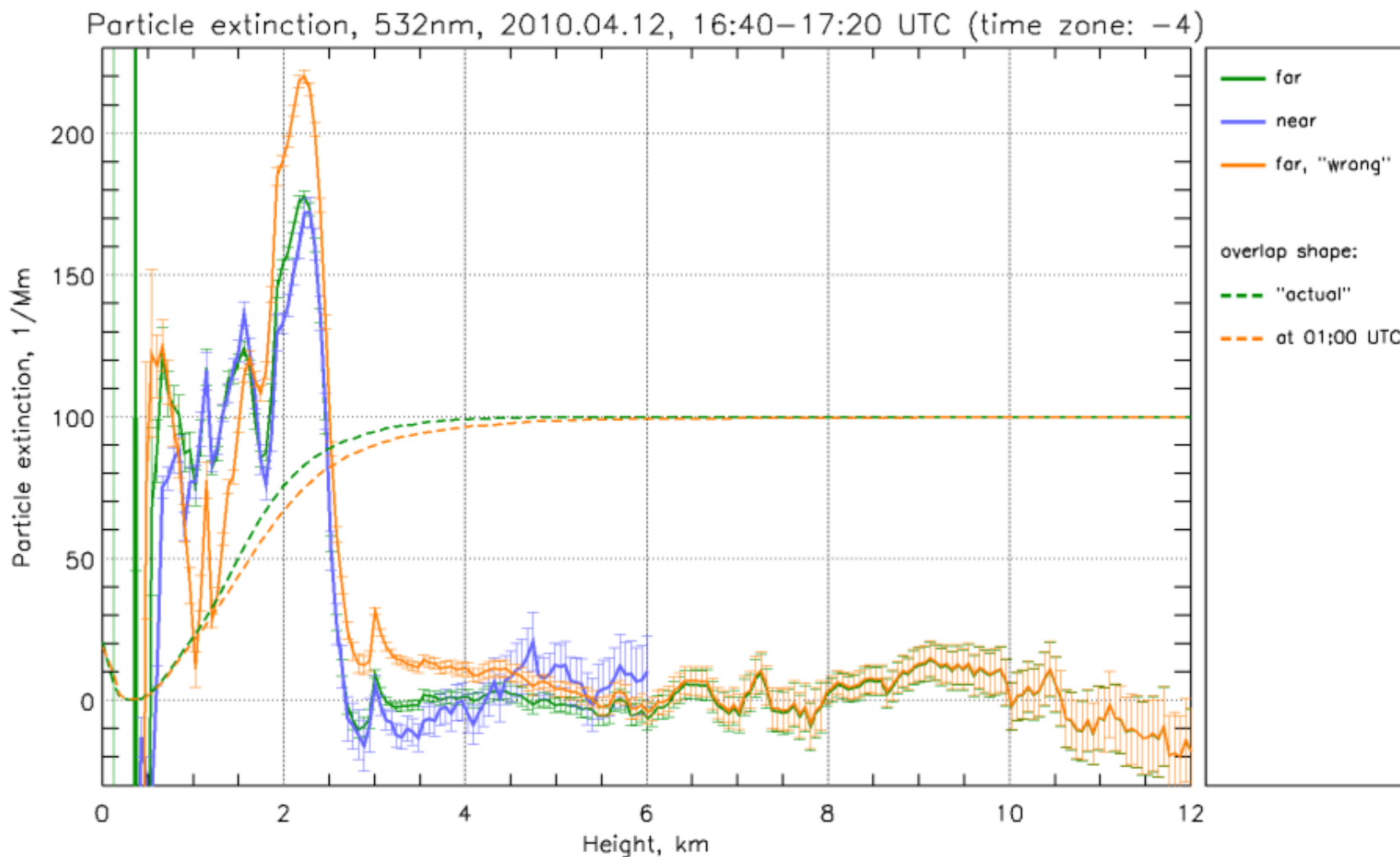
# Overlap function, far range telescope, 532nm, 10.04.12



# Overlap function, far range telescope, 532nm, 10.04.12



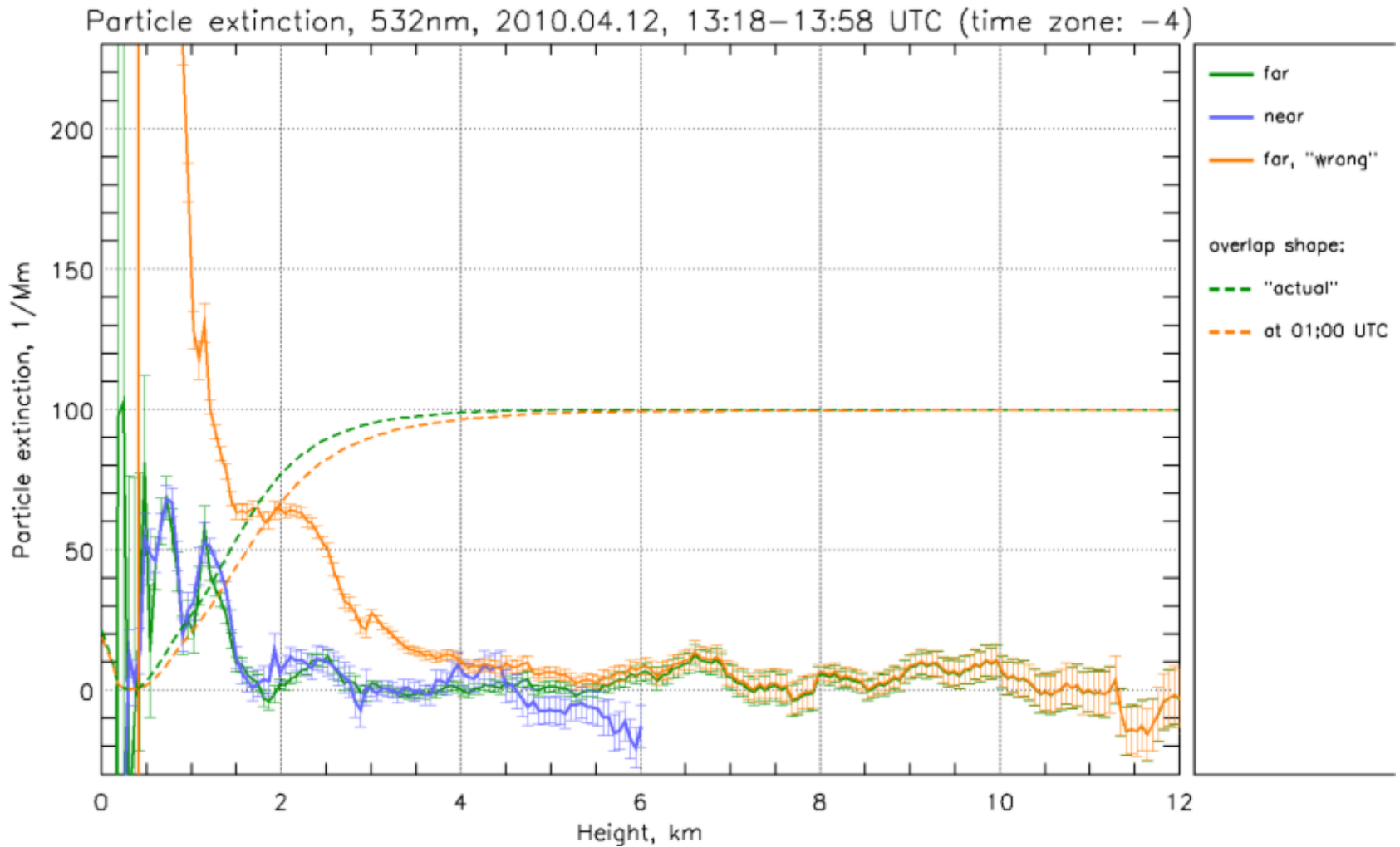
# Particle extinction, 532nm, near & far range



resolution: extinction: 40 minutes,  $0.18 \div 3\text{km}$   
overlap: 3 hours,  $60\text{m} \div 5\text{km}$



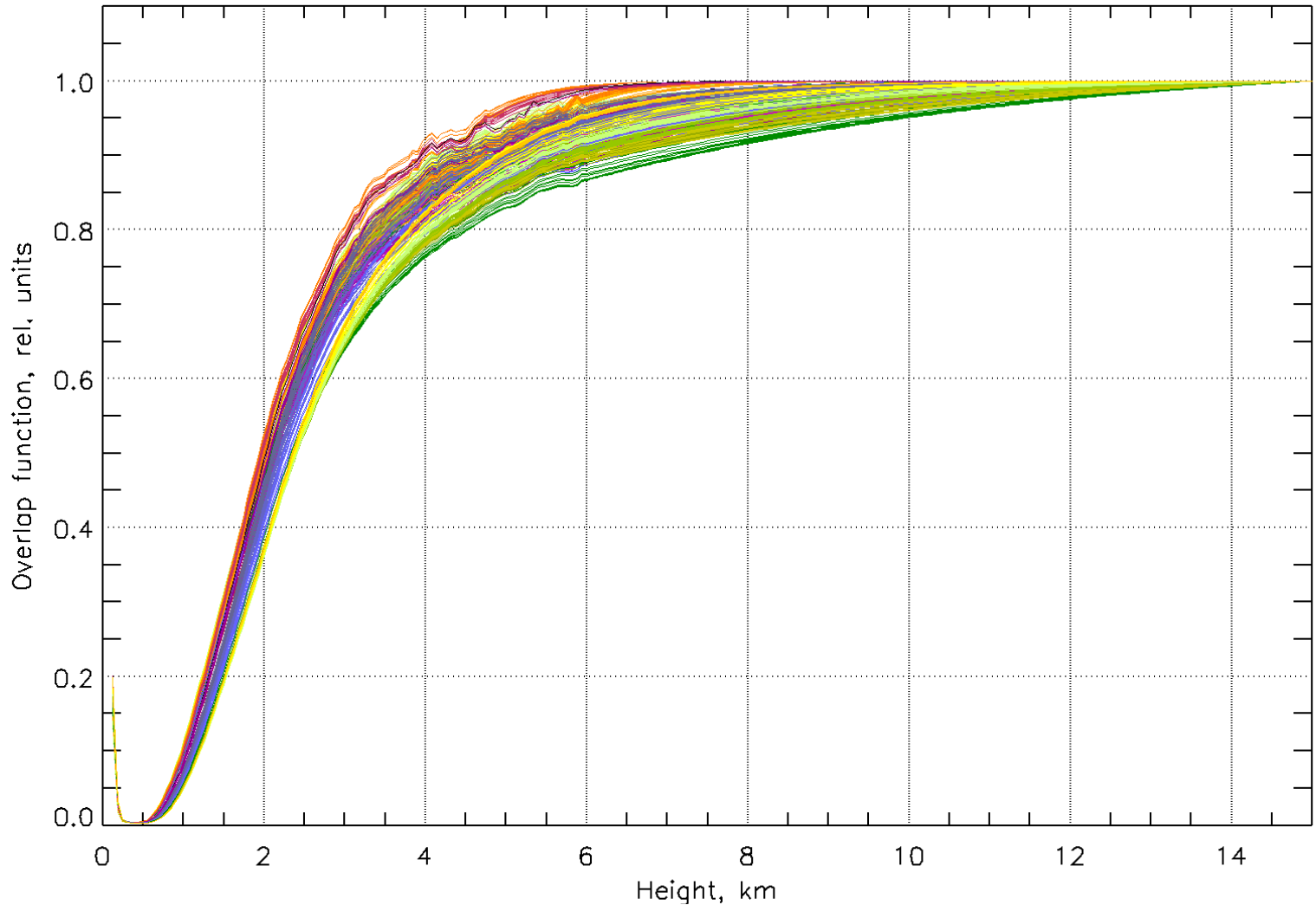
# Particle extinction, 532nm, near & far range



resolution: extinction: 40 minutes,  $0.18 \pm 3\text{km}$   
overlap: 3 hours,  $60\text{m} \pm 5\text{km}$

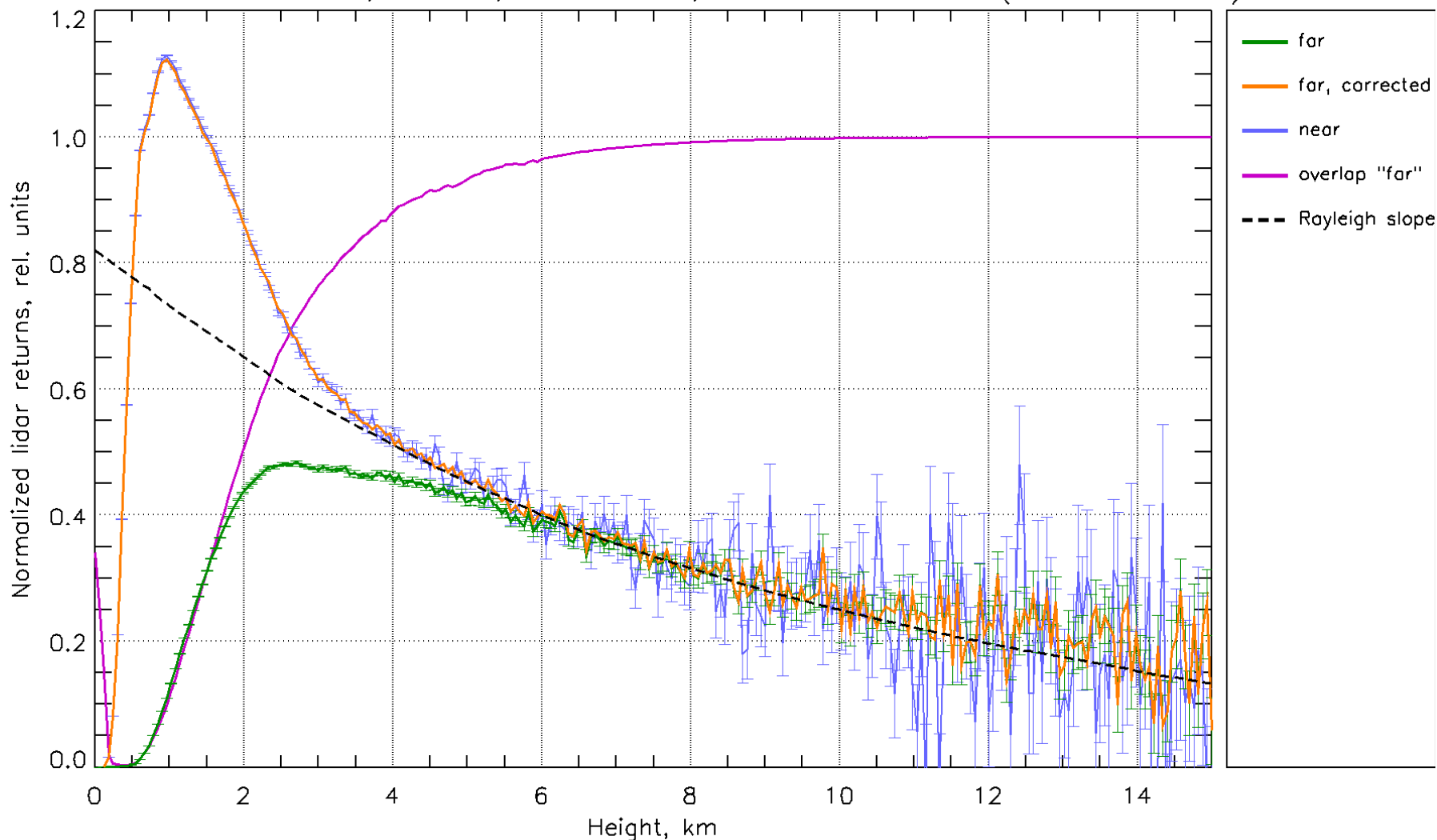
# Overlap function, far range telescope, 532nm, 10.07.15

Overlap function, far range, 532nm, 100715



# Raman lidar returns, 532nm, near & far range

Raman lidar returns, 532nm, 2010.07.15, 13:18–13:58 UTC (time zone: -4)

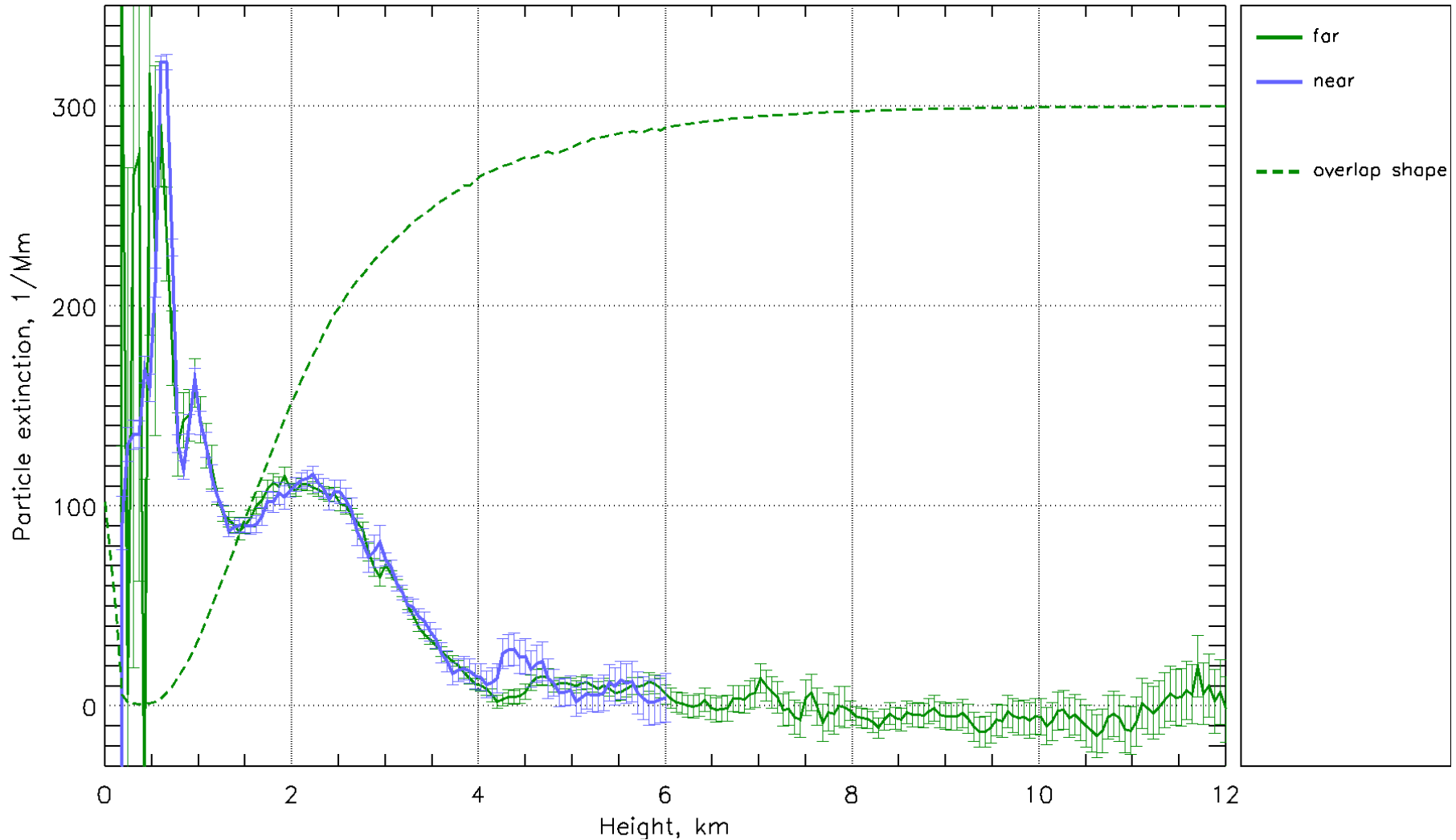


resolution: signals: 40 minutes, 60m  
overlap: 3 hours, 60m÷5km



# Particle extinction, 532nm, near & far range

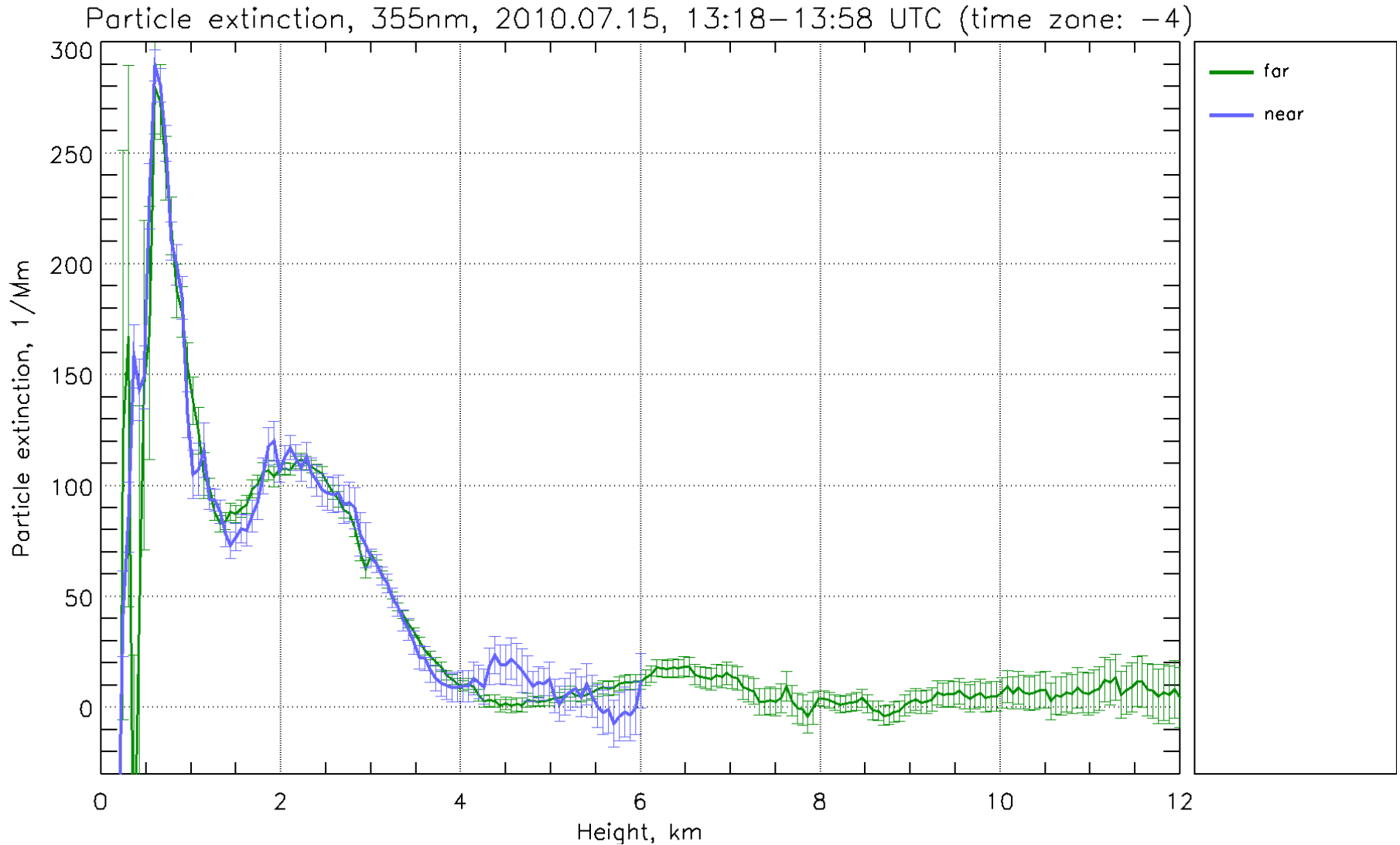
Particle extinction, 532nm, 2010.07.15, 13:18–13:58 UTC (time zone: -4)



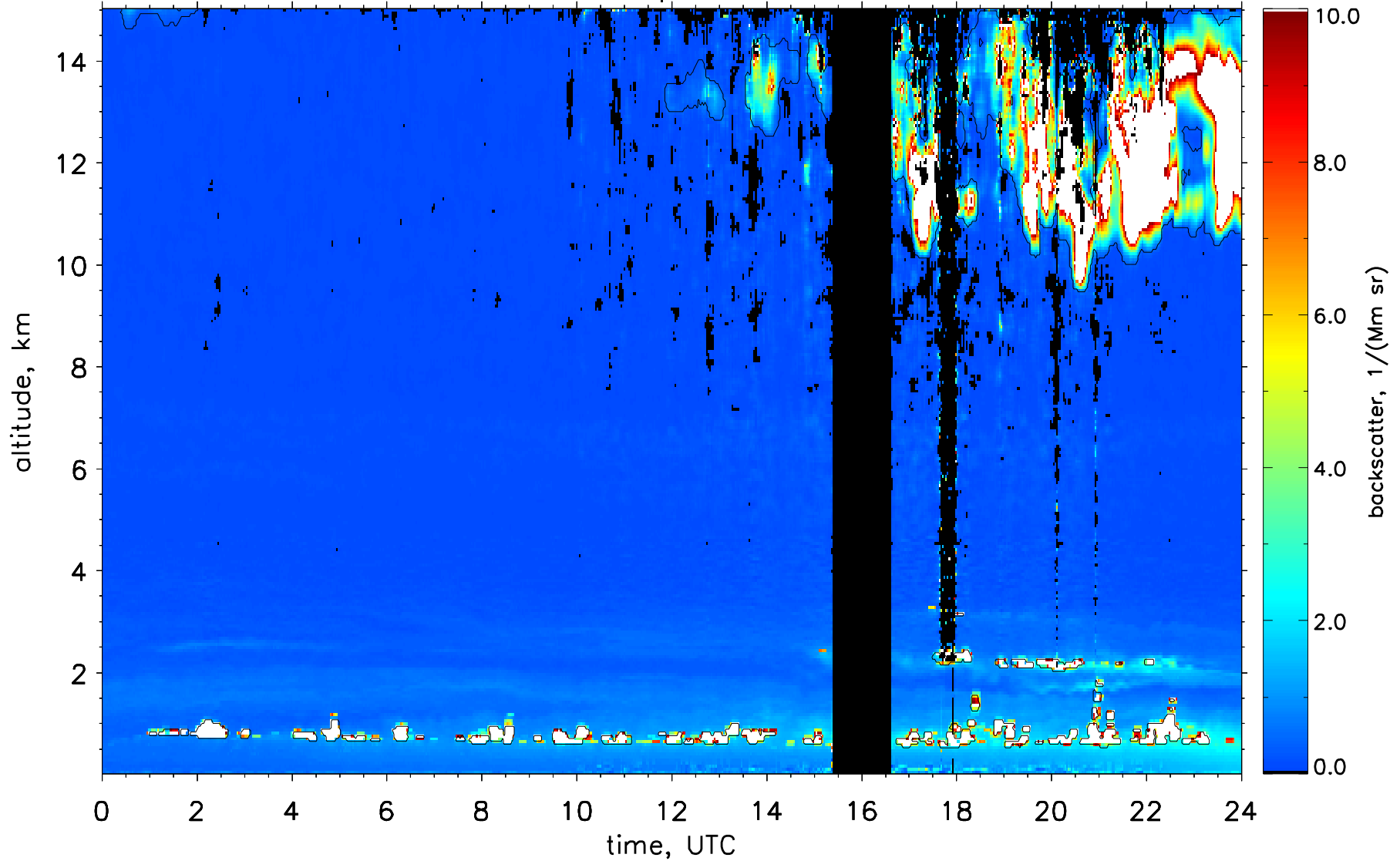
resolution: extinction: 40 minutes, 0.18÷3km  
overlap: 3 hours, 60m÷5km



# Particle extinction, 355nm, near & far range

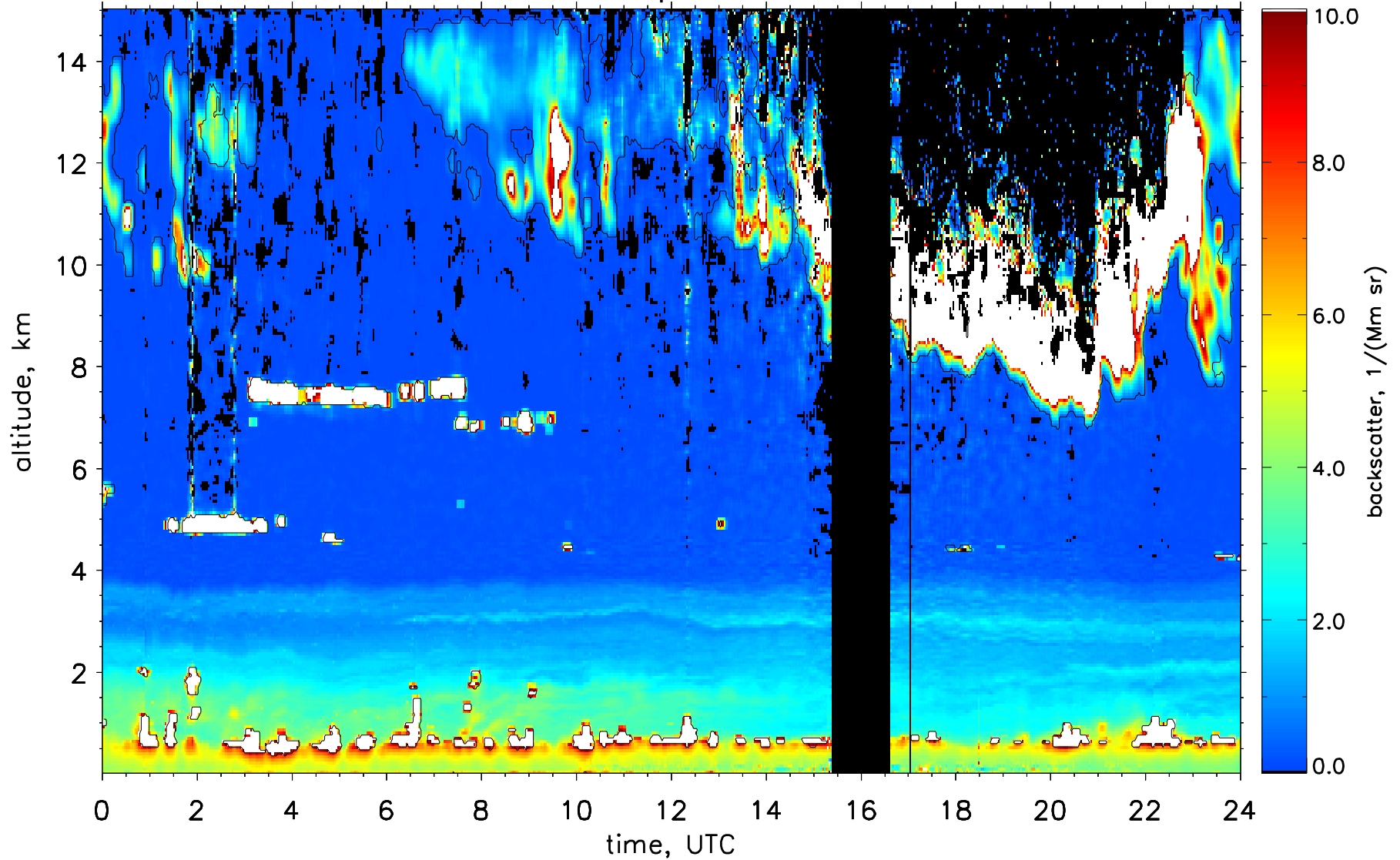


Particle backscatter, 532nm, 20 April 2011, res.: 10 min., 60–660 m

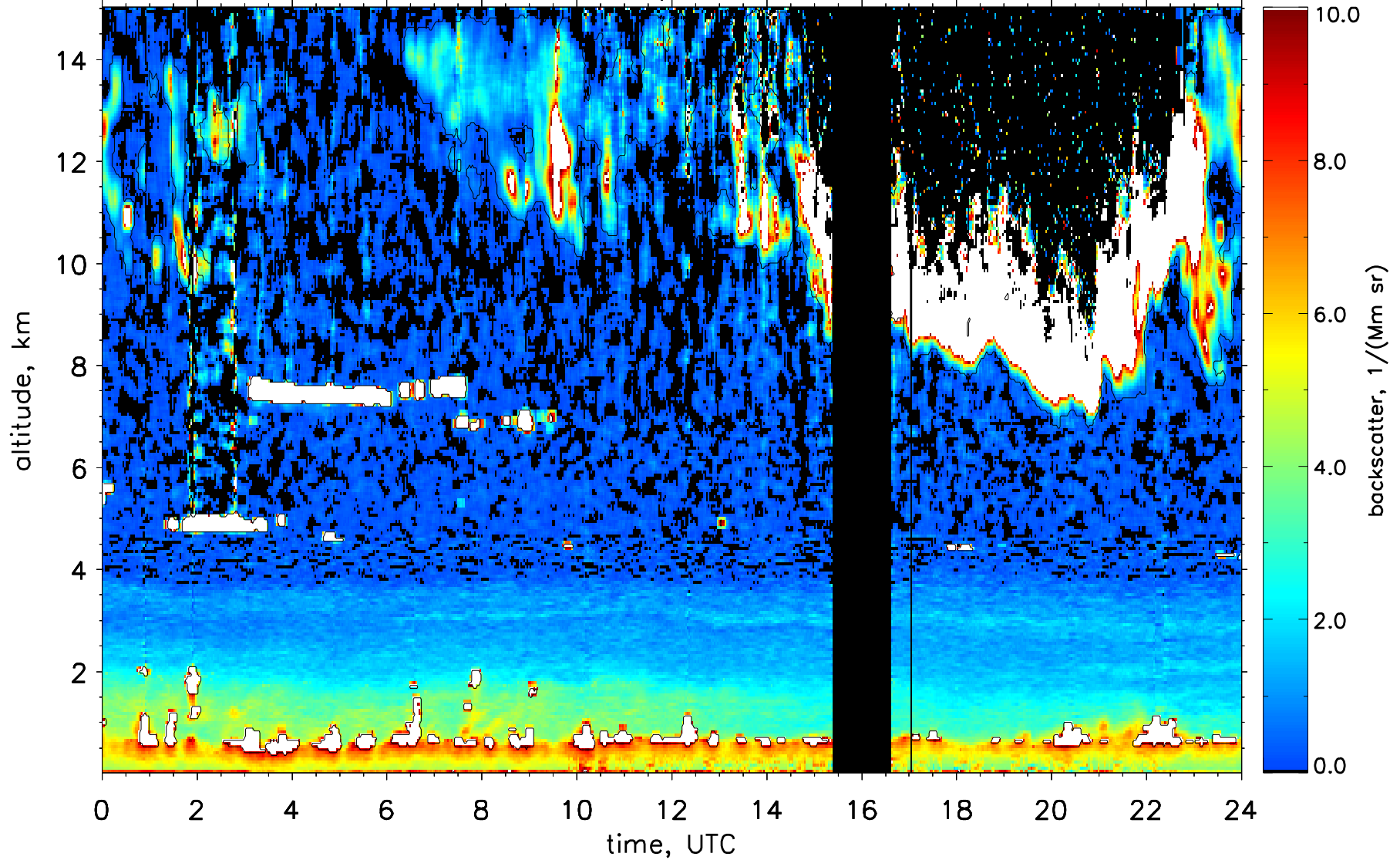




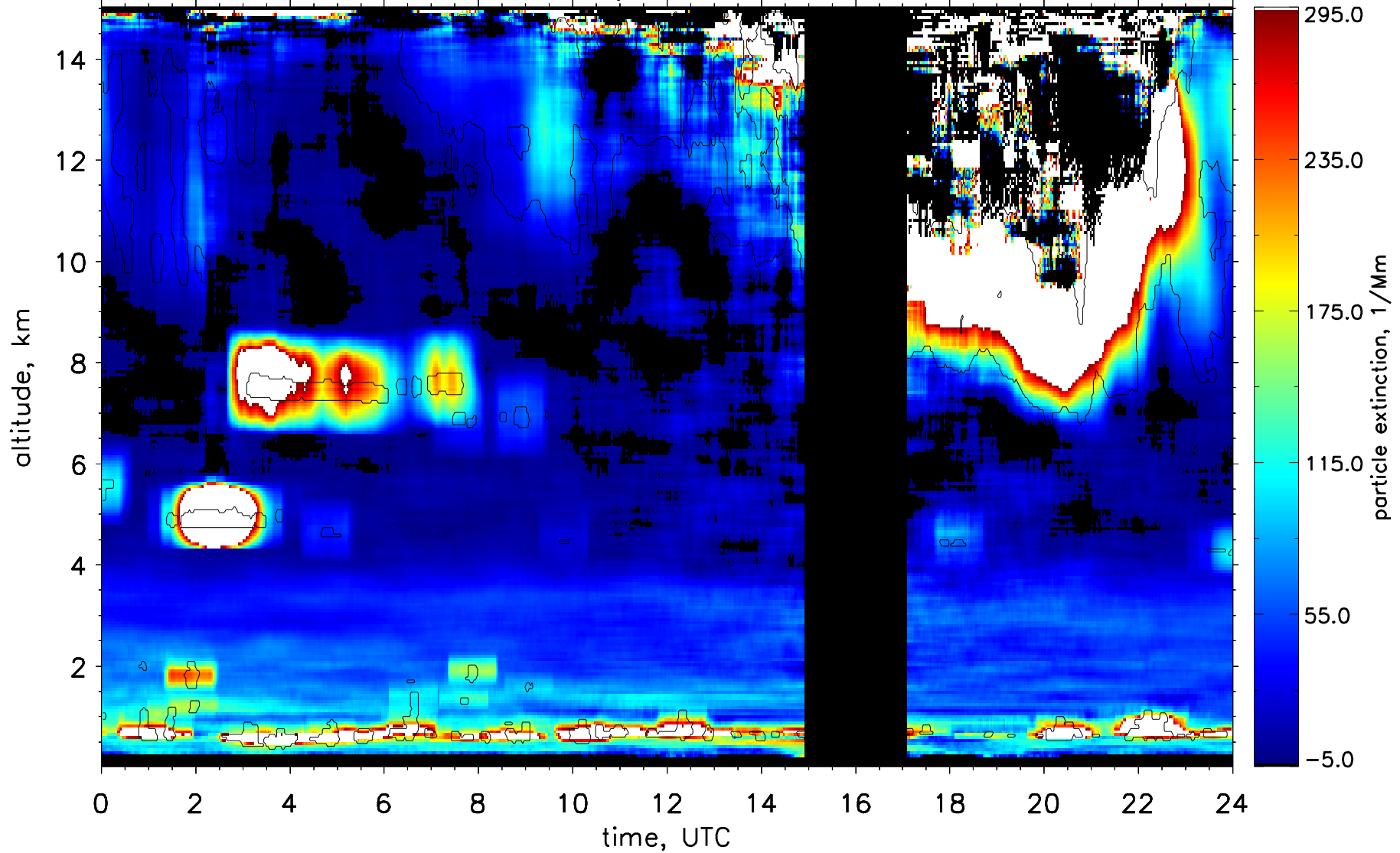
Particle backscatter, 532nm, 15 April 2011, res.: 10 min., 60–660 m



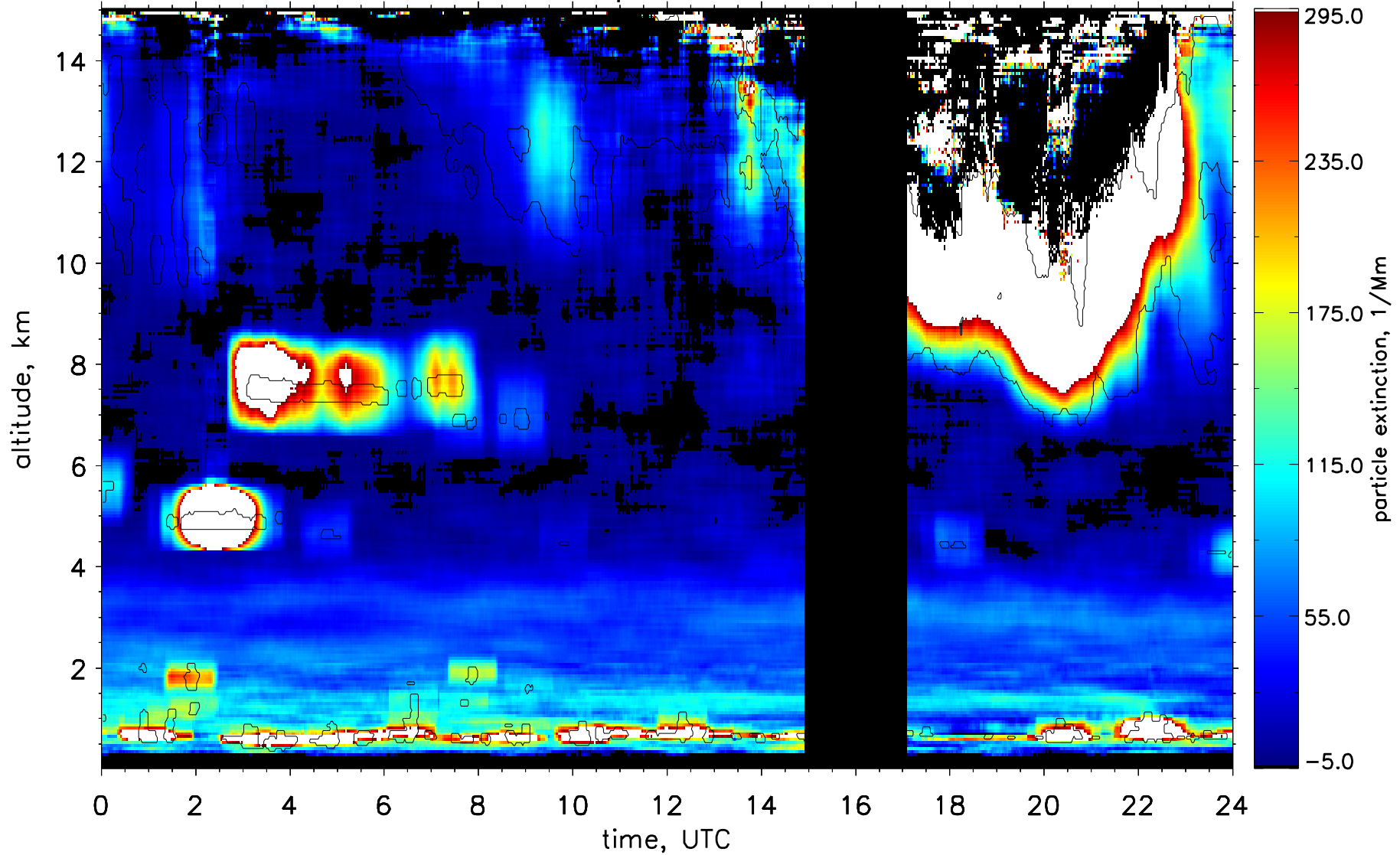
Particle backscatter, 355nm, 15 April 2011, res.: 10 min., 60–660 m



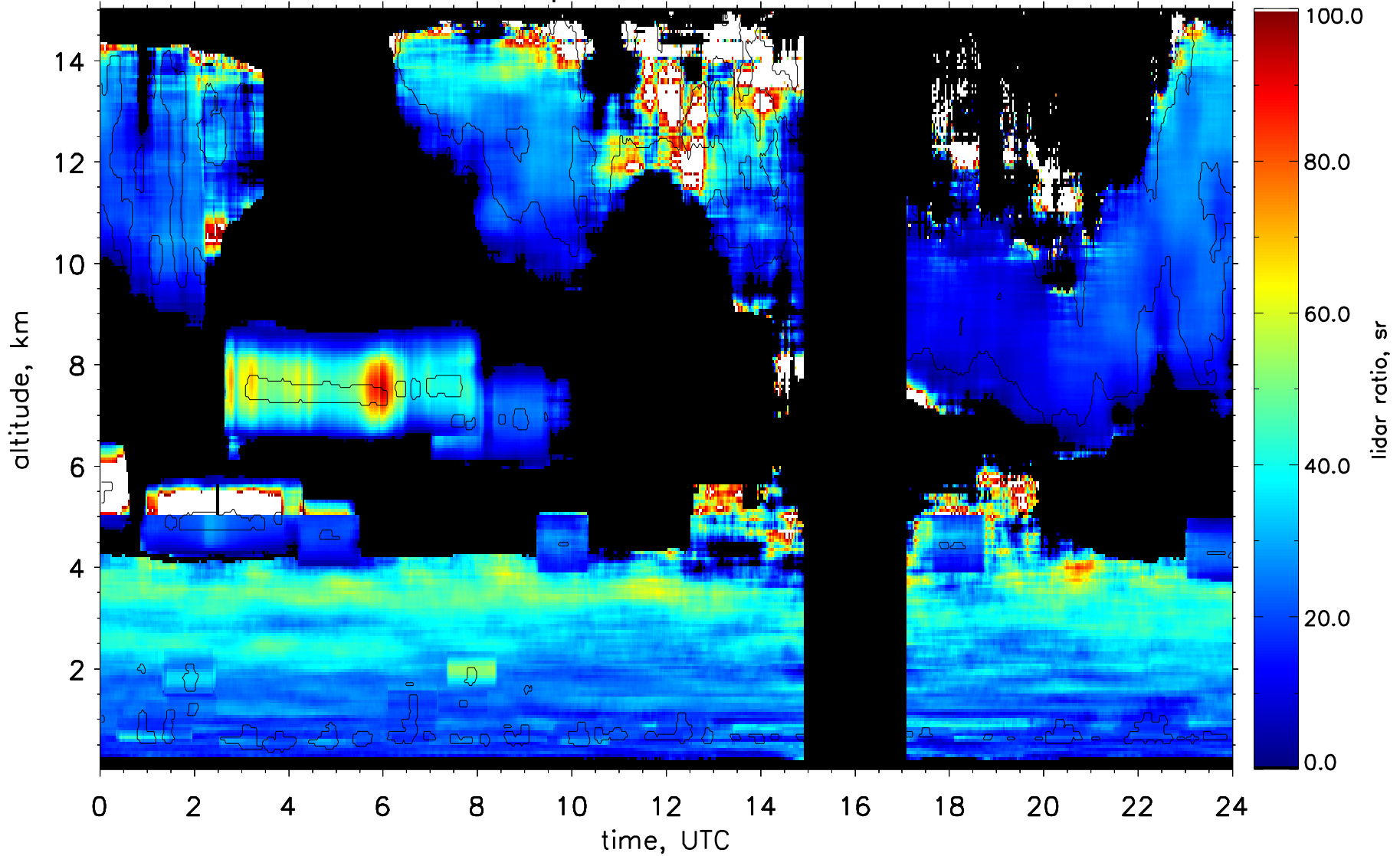
Particle extinction, 532nm, 15 April 2011, res.: 60 min., 180–3540 m



Particle extinction, 355nm, 15 April 2011, res.: 60 min., 180–3540 m

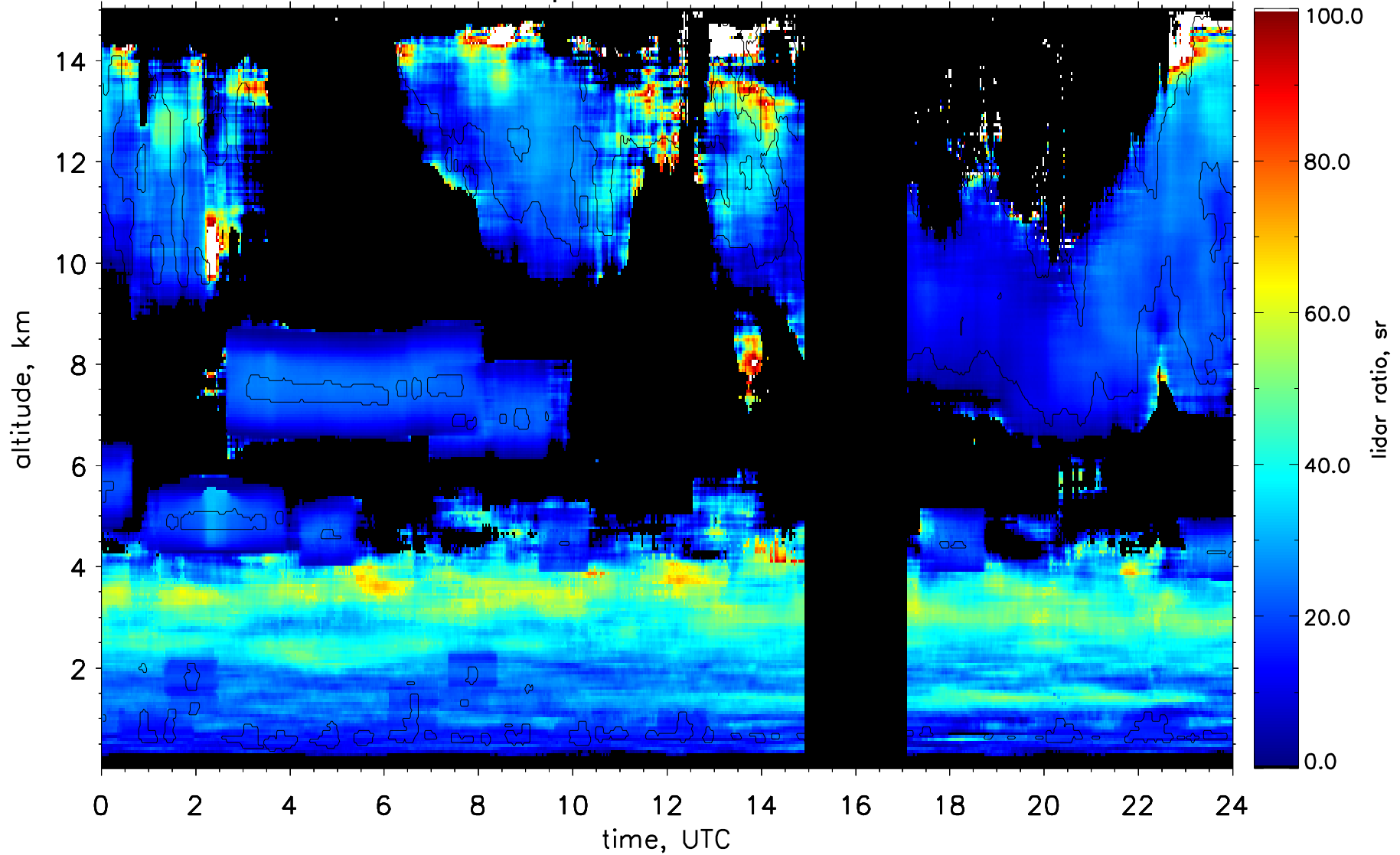


Lidar ratio, 532nm, 15 April 2011, res.: 60 min., 180–3540 m

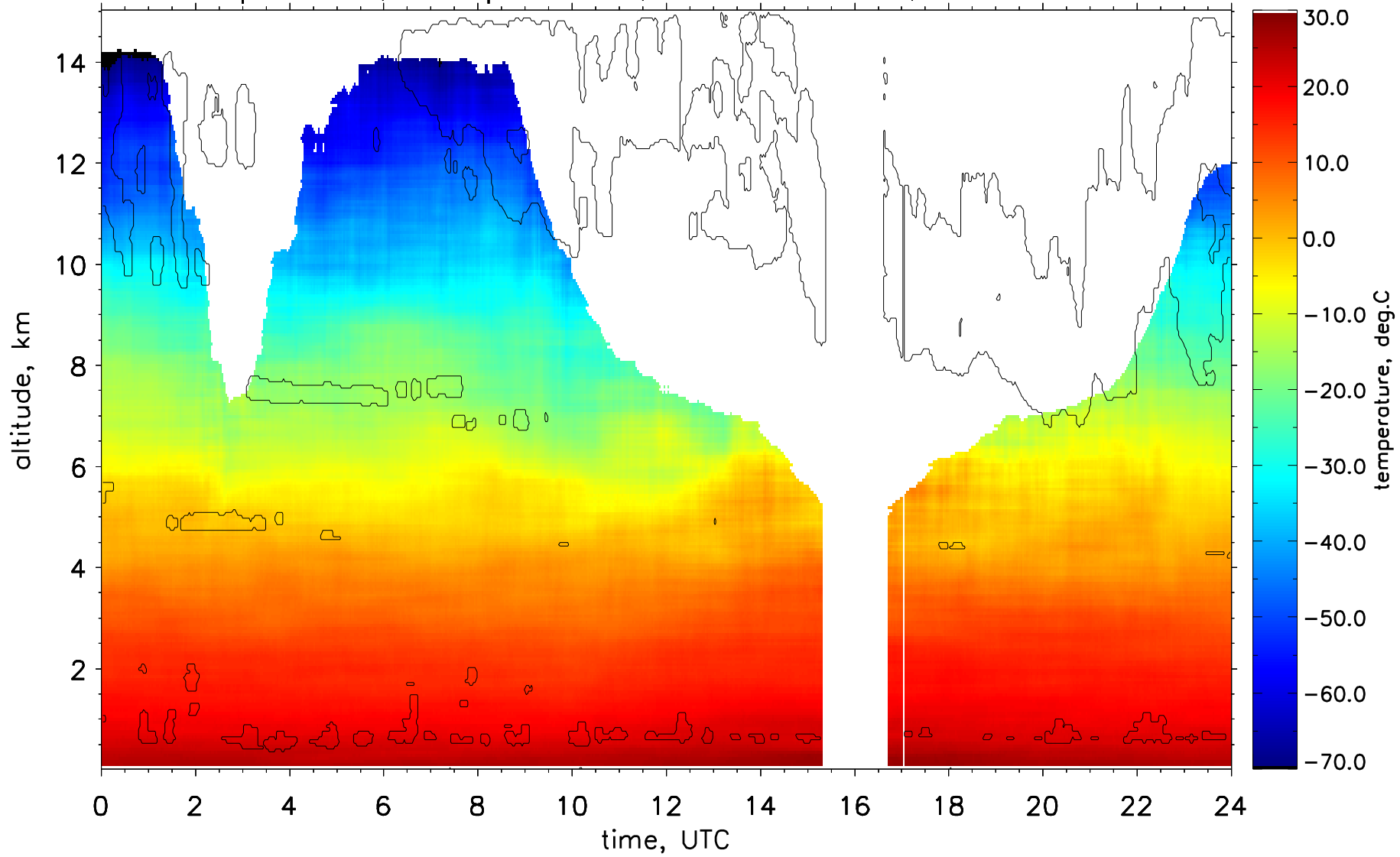




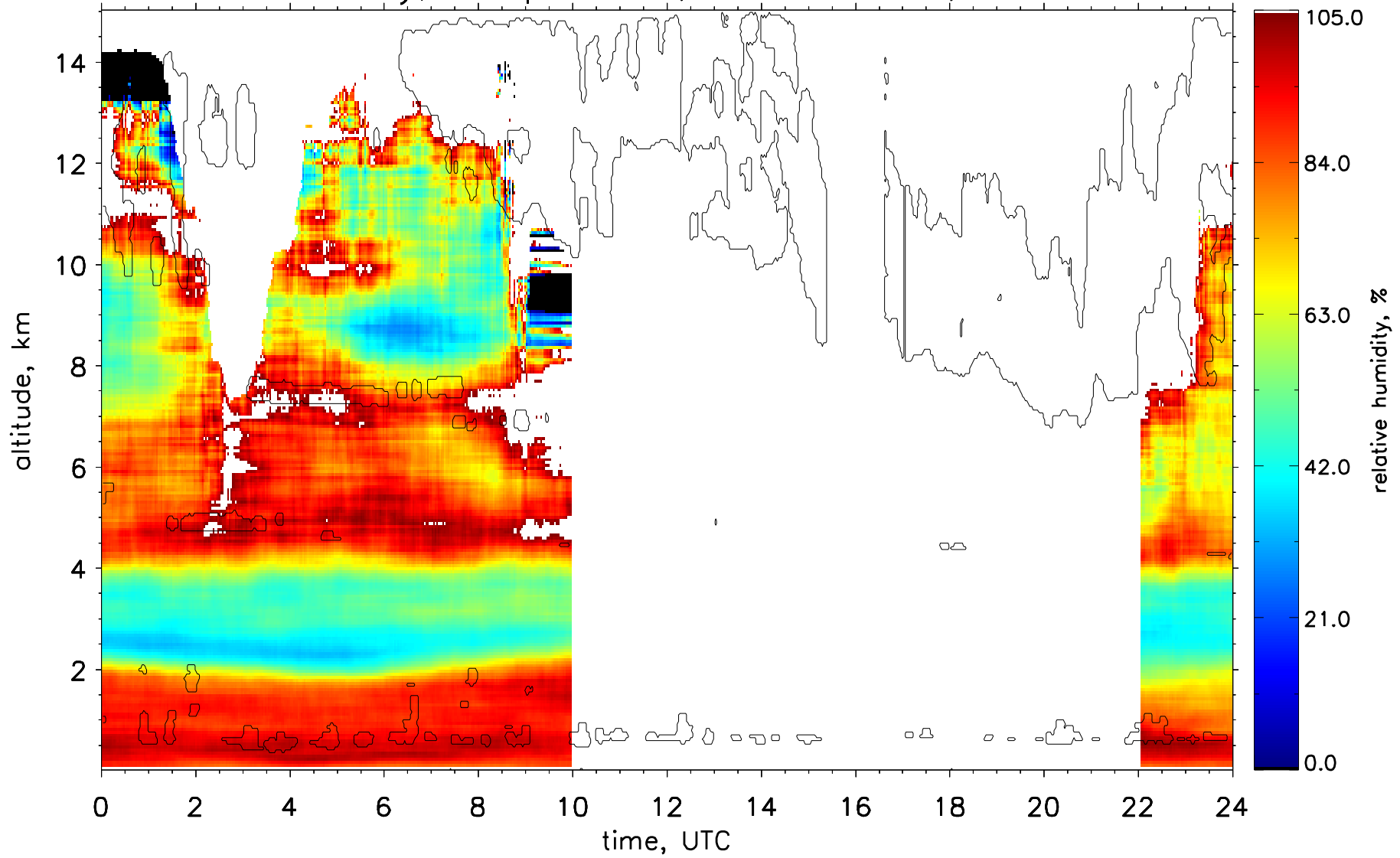
Lidar ratio, 355nm, 15 April 2011, res.: 60 min., 180–3540 m



Temperature, 15 April 2011, res.: 118 min., 180–2220 m



Relative humidity, 15 April 2011, res.: 118 min., 180–2220 m



Thank you!

